# My Projects Using Game Theory 

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## Poker



## The Challenges

- Large game tree
- Stochastic element
- Imperfect information (during hand, and after)
- Variable number of players (2-10)
- Aim is not just to win, but to maximize winnings
- Need to exploit opponent weaknesses


## 2-player, limit, Texas Hold'em



## Game-Theoretic Approach



MACHINE LEARNING


## Linear Programming

åyer, zero-sum game with chance mixed strategies, and imperfect tion can be formulated as a linear 1 (LP).
can be solved in polynomial time to auce Nash strategies for P1 and P2.

- Guaranteed to minimize losses against the strongest possible opponent.
- "Sequence form" - the LP is linear in the size of the game tree
(Koller, Megiddo, and von Stengel)


## Linear Programming

- A 2-player, zero-sum game with chance events, mixed strategies, and imperfect information can be formulatil III
- The LP can be solved
produce Nash strategies for P1 and
- Guaranteed to minimize losses against ine strongest possible opponent.
- "Sequence form" - the LP is line: size of the game tree.


## PsOpti (Sparbot) - IJCAI’03

- Abstract game tree of size $10^{7}$
- Bluffing, slow play, etc. fall out from the mathematics.
- Best 2-player program to date
- Has held its own against 2 world-class humans
- Won the AAAl'06 poker-bot competitions


## PsOpti2 vs. "theCount"




## PsOpti's Weaknesses

- The equilibrium strategy for the highly abstract game is far from perfect.
- No opponent modelling.
- Nash equilibrium not the best strategy:
- Non-adaptive
- Defensive
- Even the best humans have weaknesses that should be exploited


## http://www.poker-academy.com

A Poker Academy Pro


# Network Routing when Traffic Demands are Uncertain 

Recent Ph.D. thesis by Yuxi Li

## Example

TRAFFIC DEMAND

| To <br> From | A | B | C |
| :---: | :--- | :--- | :--- |
| A | 0 | 80 | 20 |
| B | 80 | 0 | 10 |
| C | 20 | 10 | 0 |

- A routing is a set of fractions for all meaningful combinations of H, O, D, N in:
At node $\mathrm{H}, \mathrm{f}_{\mathrm{H}, \mathrm{O}, \mathrm{D}, \mathrm{N}}$ of the packets going from node O to node D should be sent next to node N


## Treat this as a 2-player game

- Objective function:
- lifetime of an energy-constrained network (e.g. sensor network)
- Player 1 (max): choose a routing
- Player 2 (min): choose a traffic demand matrix
- The Nash equilibrium of this game is a routing that is resistant to adversarial attacks


## Behaviour under Attack

AS 6461


## Combinatorial Auctions

## Rodent auction



Flopsy

## Rodent auction



Flopsy


## Rodent auction



Flopsy
Mopsy $\longrightarrow$


Jack

## Rodent auction



Flopsy
Mopsy $\longrightarrow$


C1: will pay $\$ 5$ for any one C3: will pay $\$ 12$ for all three
C2: will pay $\$ 9$ for a breeding pair (Flopsy and one of the others)


Jack

## Combinatorial Auctions

- Single Unit C.A. - one copy of each item
- Auction all items simultaneously
- Bid specifies a price and a set of items ("all or nothing")
- Exclusive-OR can be achieved by having a "dummy item" representing the bidder
- Multi-round or single-round


## \$12 for all three



## \$9 for a breeding pair



## \$5 for any one



## Applications

- FCC spectrum auctions
- Goods distribution routes
- Airport gates, parcels of land
- eBay


## Example Application

SPOT: earth observation satellite
Requests are made for photographs.
Each photograph can be taken at several times by several different instruments/settings, but quality (profit) may vary.
Using one instrument/setting at a given time may prevent the use of another at the same or adjacent times.

## Example

## Photograph 1

. \$4 if taken on instrument A at time T1

- \$3 if taken in instrument A at time T2
- \$12 is taken on instrument B at time T2

Photograph 2

- \$7 if taken on instrument B at time T2

If $B$ is being used, $A$ cannot used at the same time.

## Formulation as a C.A.

Each instrument/setting/time is a separate item for auction.

Each photograph is a bidder, with XOR bids for each of the different ways of achieving the photograph.
If "items" A and B are mutually exclusive, any bid for $A$ also includes $B$.

## Example as a C.A.



## Winner Determination

Problem: how to determine who wins ?

Choose a set of bids that are feasible (disjoint) and maximize the auctioneer's profit.

NP-complete (set packing problem)

## Multi-unit Combinatorial Auctions

- There are $b_{i}$ copies of item $i$
- A bid specifies a quantity for each item (is a vector length $m$ if there are $m$ items)
- A set of bids is feasible if its total demand for each item does not exceed the number of available copies of the item


## Manufacturing Application 1

- Inventory consists of $m$ types of parts, with $b_{i}$ instances of type $i$.
- A customer order requests a certain quantity of each part, and offers a price.

Determine which orders to fill to maximize profit.

## Auctions and Knapsacks

Winner determination in a multi-unit combinatorial auction with a single item is the classic NPcomplete Knapsack problem.

With more than one item, it is the multidimensional Knapsack problem (MDKP) much less studied.

## The Knapsack Problem

- An "easy" NP-complete problem
- Garey \& Johnson: knapsack is considered "solved" by many (by branch-and-bound)
- n (\#bids) can be reduced by decomposition and preprocessing
- Solvable in pseudo-polynomial time by dynamic programming


## Knapsack Algorithms

- Dave Pisinger's PhD (1995) - publicly available, very fast code (d.p.)
- There is a very simple greedy algorithm guaranteed to be $1 / 2$ optimal or better


## The Multidimensional Knapsack Problem (MDKP)

- An hard NP-complete problem
- Not solvable in pseudo-polynomial time.
- No greedy (polynomial) algorithm can guarantee an approximation that is better than OPT/k $k^{1 / 2}$ where $k$ is the sum of the $b_{i}$.


## Why Try Hill-climbing?

- It is part of branch\&bound search and some heuristic search algorithms
- Try simple, generic search algorithms before complex ones and problem-specific variants


## Deterministic Hill-Climbing

Start with the empty bid-set
REPEAT:

- Consider adding one bid to the current bid-set
- Prune bid-sets that are infeasible
- Add the bid with the highest "score"

UNTIL pruning eliminates all alternatives
Report the highest price seen during search, not the price of the final local "score" maximum

## Deterministic Hill-Climbing

Start with the empty bid-set
REPEAT:

- Consider adding one bid to the current bid-set
- Prune bid-sets that are infeasible or cannot be extended to improve the best price seen so far
- Add the bid with the highest "score"

UNTIL pruning eliminates all alternatives
Report the highest price seen during search, not the price of the final local "score" maximum

## Scoring functions

- Price
- N2norm = Price/size
- Single-unit, size $=(\# \text { items in the bid })^{1 / 2}$
- Multi-unit, size $=\left(\sum f(i)^{2}\right)^{1 / 2}$
$f(i)$ is the fraction of the remaining quantity of item $i$ required by the bid
- $\mathrm{KO}=$ Price/(price of contending bids KO'd by the bid)


## Randomized Hill-climbing

Instead of adding the bid with the best score, choose among the alternative bids (after pruning) randomly, with probability proportional to score.

Restart (with the empty bid-set) several times on a given problem and report best price seen on any restart.

## Single-Unit Test Problems

## CATS test suite from Stanford

- new
- Problem generators for 5 different scenarios
e.g. airport takeoff and landing time-slots
- Realistic (e.g. airports are Chicago, LaGuardia, etc.)
- Numerous Parameters - defaults used except
. 3 variations on "regions" (default + 2 others)
- scaled down "paths" and "scheduling"


## Experimental Setup

- For each problem type randomly generate 100 different problems
- On each problem run
- the 3 deterministic hill-climbers
"Best DHC" = best of these prices
- the 3 randomized hill-climbers (20 restarts each)
"Best RHC" = best of these prices


## Average Solution Quality (\% of optimal)

| problem type | best DHC | best RHC |
| :---: | :---: | :---: |
| path | 98 | 98 |
| match | 99 | 99 |
| sched | 96 | 98 |
| r75P | 83 | 92 |
| r90P | 90 | 96 |
| r90N | 89 | 96 |
| arb | 87 | 95 |

## Observations

- Randomized (20 restarts) better than deterministic
- Randomized finds very good solutions
(always > 80\%, average > 92\%)
- Problem ratings:
easy: path, match, sched
harder: r90P, r90N, arb
hardest: r75P
- On the easy problems, deterministic finds very good solutions (almost as good as randomized)


## Which Scoring Function?

N2norm and KO about the same, better than Price.

## Which Scoring Function?

N2norm and KO about the same, better than Price.

## But are they better than chance ?

## Blind Hill-climbing

Choose bid randomly with uniform probability

- still prunes
- still reports best price seen throughout search

Repeat 200 times on each problem to measure its solution quality distribution

## Percentage of Blind HC solutions worse than Deterministic solutions

| problem type | N2norm | KO |
| :---: | :---: | :---: |
| path | 100 | 100 |
| match | 100 | 100 |
| sched | 99 | 99 |
| r75P | 76 | 63 |
| r90P | 16 | 7 |
| r90N | 23 | 6 |
| arb | 40 | 20 |

## Single-unit CA - Conclusions

- hard for Blind HC, easy for DHC and RHC
- problems of this type are solved well by HC
- success is due to the scoring functions
- not good testbeds for comparative experiments allowing suboptimal solutions
- easy for Blind HC, hard for DHC
- scoring functions alone no better than chance
- numerous good solutions throughout the search space
- good testbeds as long as the Blind HC baseline is taken into account


# Multidimensional Knapsack Test Problems 

ORLIB test suite from J. Beasley

- mknap1, mknap2
- real-world, optimal values known
- widely used
- now considered "too easy"
- artificial, larger, harder problems
- only the smallest is solvable by CPLEX
- best known solutions very close to LP-optimal


## Average Solution Quality (\% of optimal or of best known)

| test set | Price | N2norm | KO | Blind |
| :---: | :---: | :---: | :---: | :---: |
| mknap1 | 90 | 98.99 | 83 | 84 |
| mknap2 | 94 | 99.00 | 79 | 58 |
| mknapcb1 | 89 | 98.94 | 85 | 82 |
| mknapcb2 | 89 | 99.03 | 85 | 83 |
| mknapcb3 | 89 | 99.21 | 85 | 83 |
| mknapcb7 | 93 | 98.35 | 85 | 81 |

## Conclusion - MDKP

- deterministic hill-climbing with N2norm competitive with all previous work, and much better than previous greedy approaches
- other scoring functions relatively poor
- randomized hill-climbing only better on the easy problems

