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Iterative Budgeted Exponential Search

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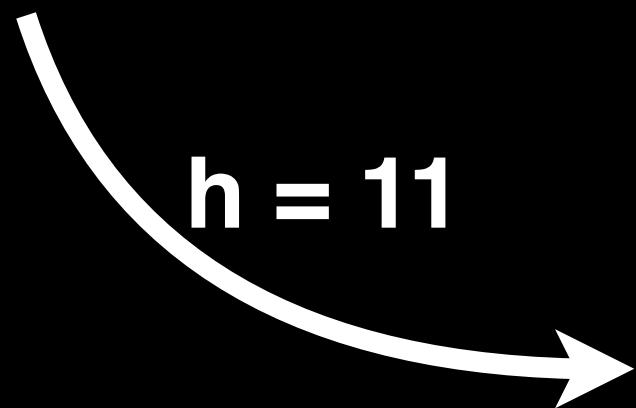
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IJCAI 2019 - Macau, China

Talk jointly presented by Laurent
Orseau and Nathan Sturtevant

Start

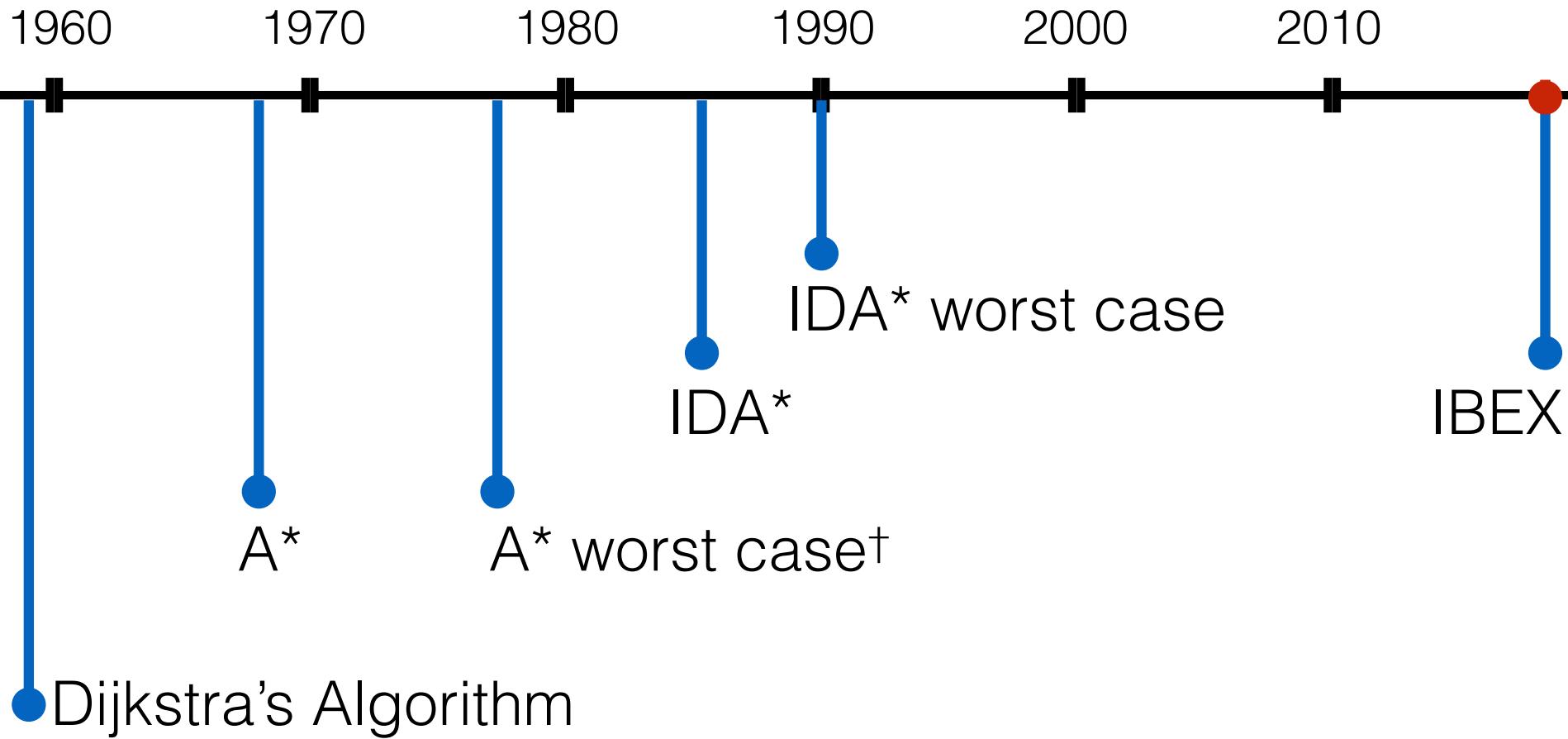


$$h = 11$$

Goal

	1	2
3	4	5

Shortest Path Algorithm History



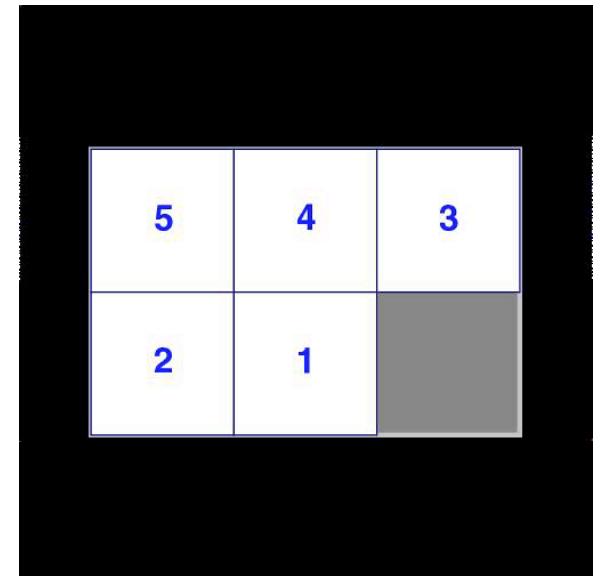
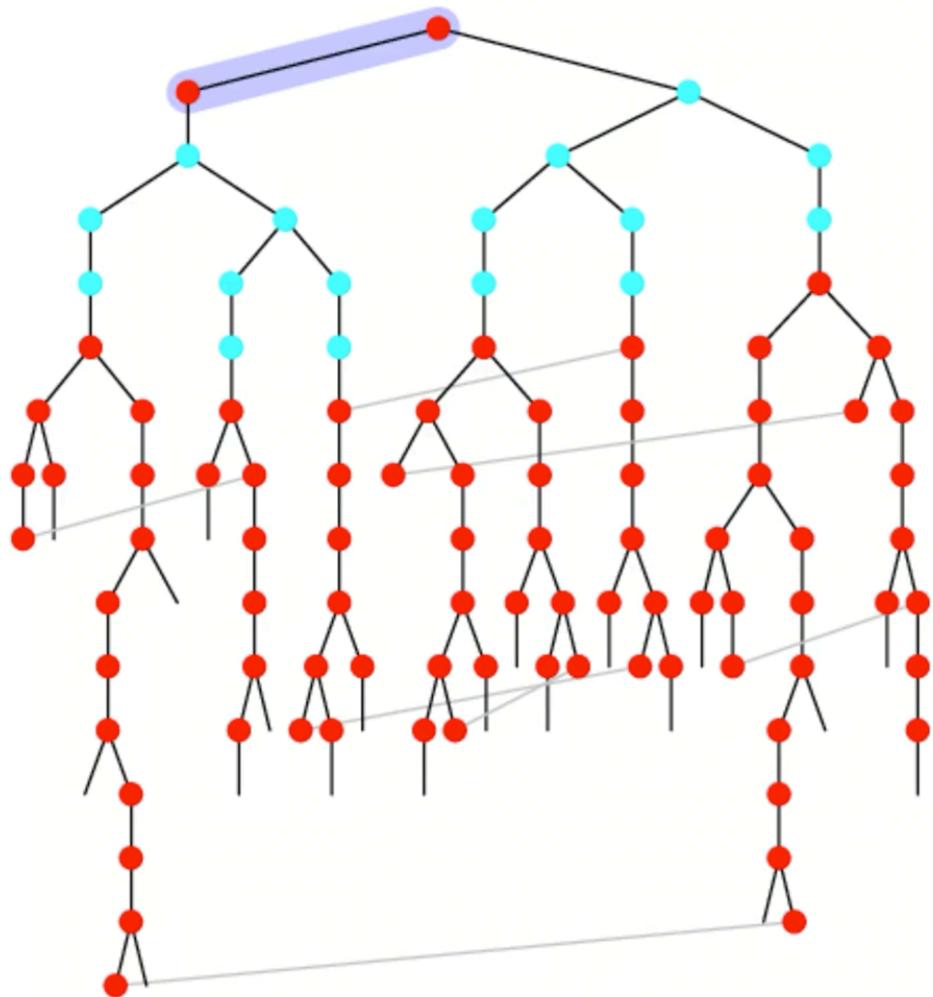
The N^2 problem

- Algorithms perform N^2 re-expansions of N states
- IDA*: N^2 expansions of $N = b^d$ states
- A*: 2^N expansions of N states
 - B & B': N^2 (Martelli 1977; Mero, 1984)
- Weighted A*: N^2 (Chen et al, 2019)

IDA* Refresher

- IDA* does *iterative deepening* search on f -costs
 - $f(n) = g(n) + h(n)$
- Next iteration f -cost:
 - Smallest unexplored from previous iteration
- If f -cost layers grow exponentially
 - IDA* is asymptotically optimal in node expansions

IDA* - Unit Costs



2 States

x8

16 States

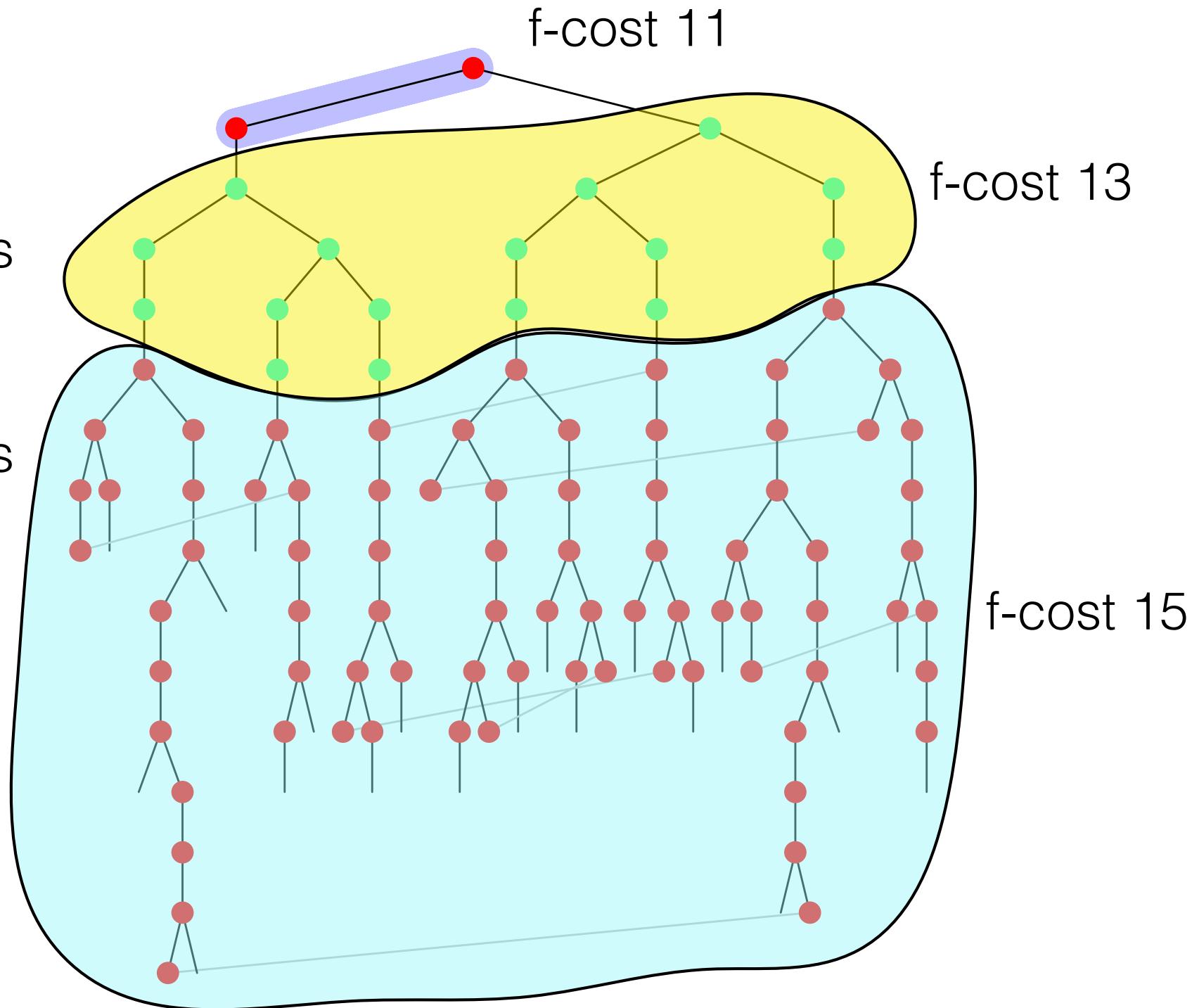
x5

79 States

f-cost 11

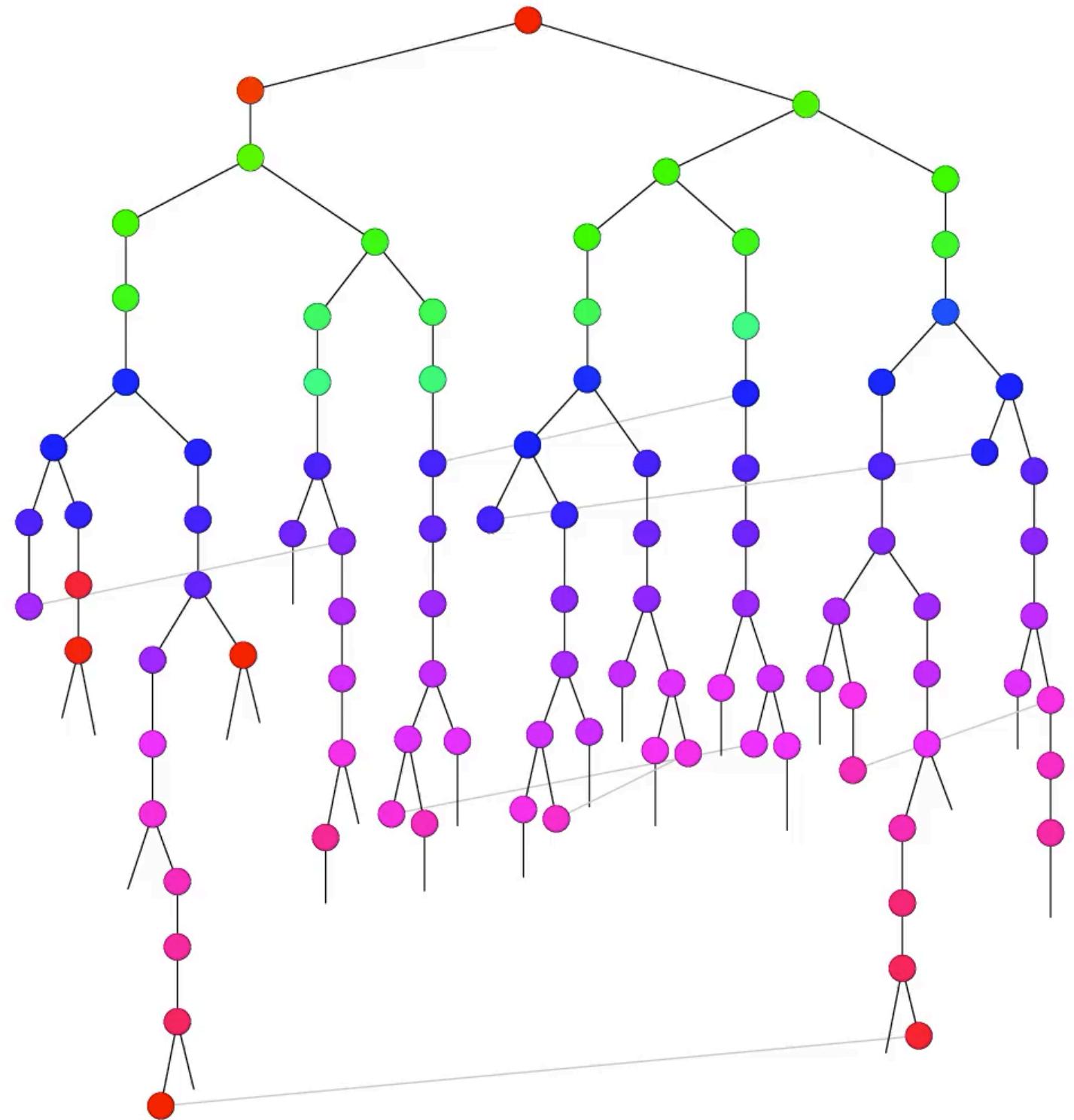
f-cost 13

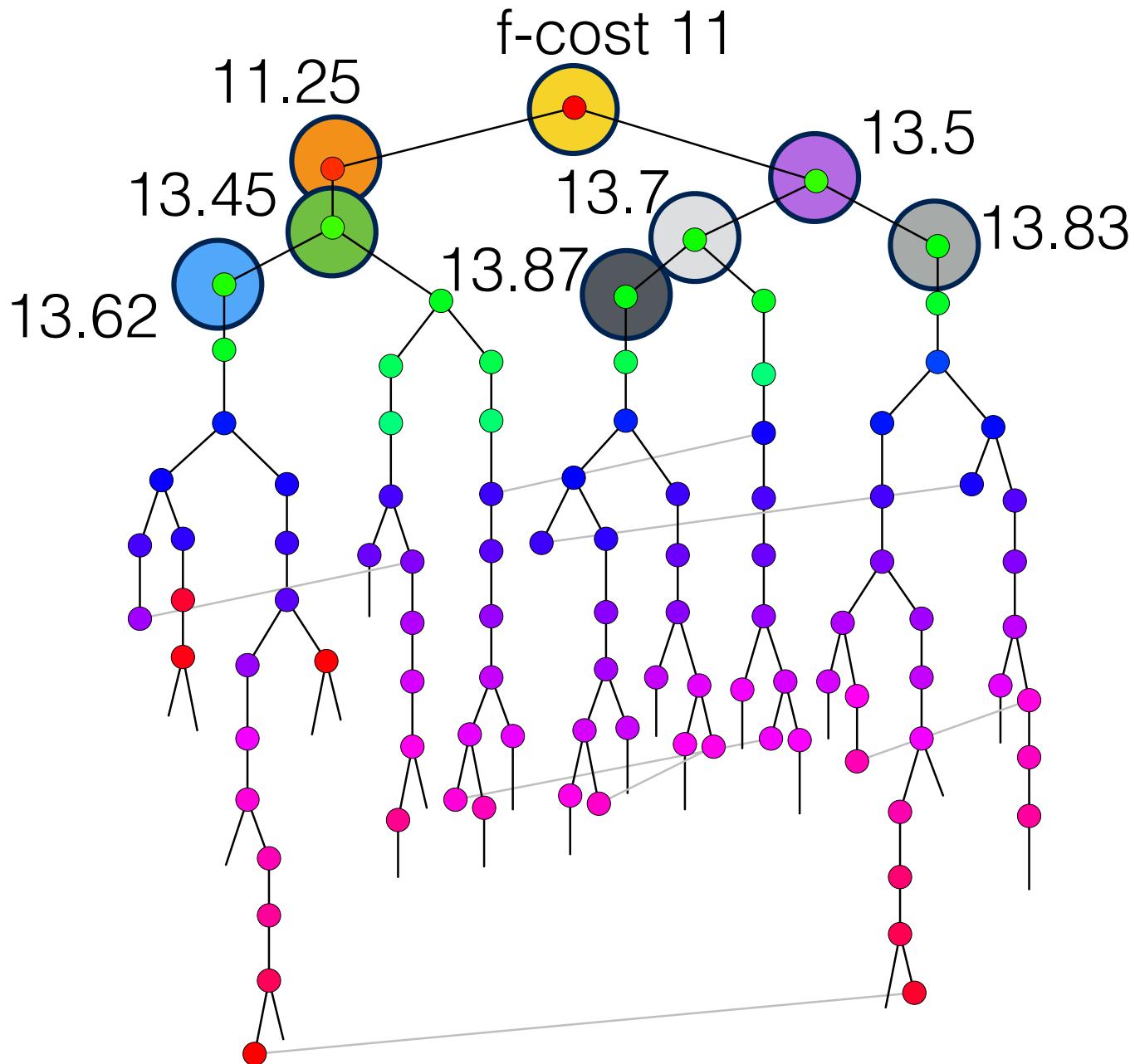
f-cost 15



IDA* Worst Case

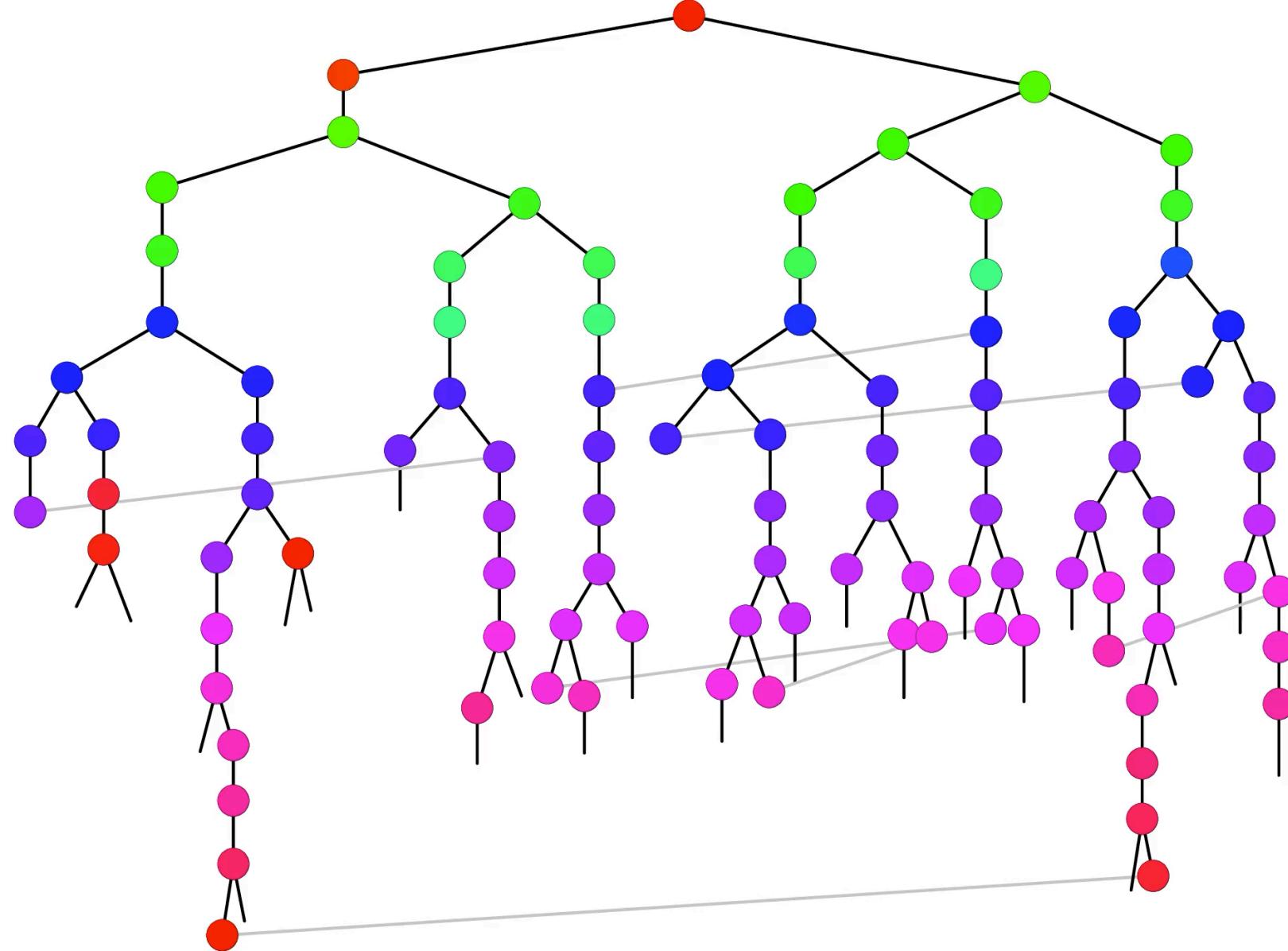
- f -cost layers grow exponentially
 - $1 + b + b^2 + b^3 + \dots + b^d \approx b^d$
- What if f -cost layers grew linearly?
 - $1 + 2 + 3 + 4 + \dots + b^d \approx (b^d)^2$
- Happens with non-unit edge costs:
 - STP: Cost of moving tile t : $\frac{t+2}{t+1}$





Previous Work

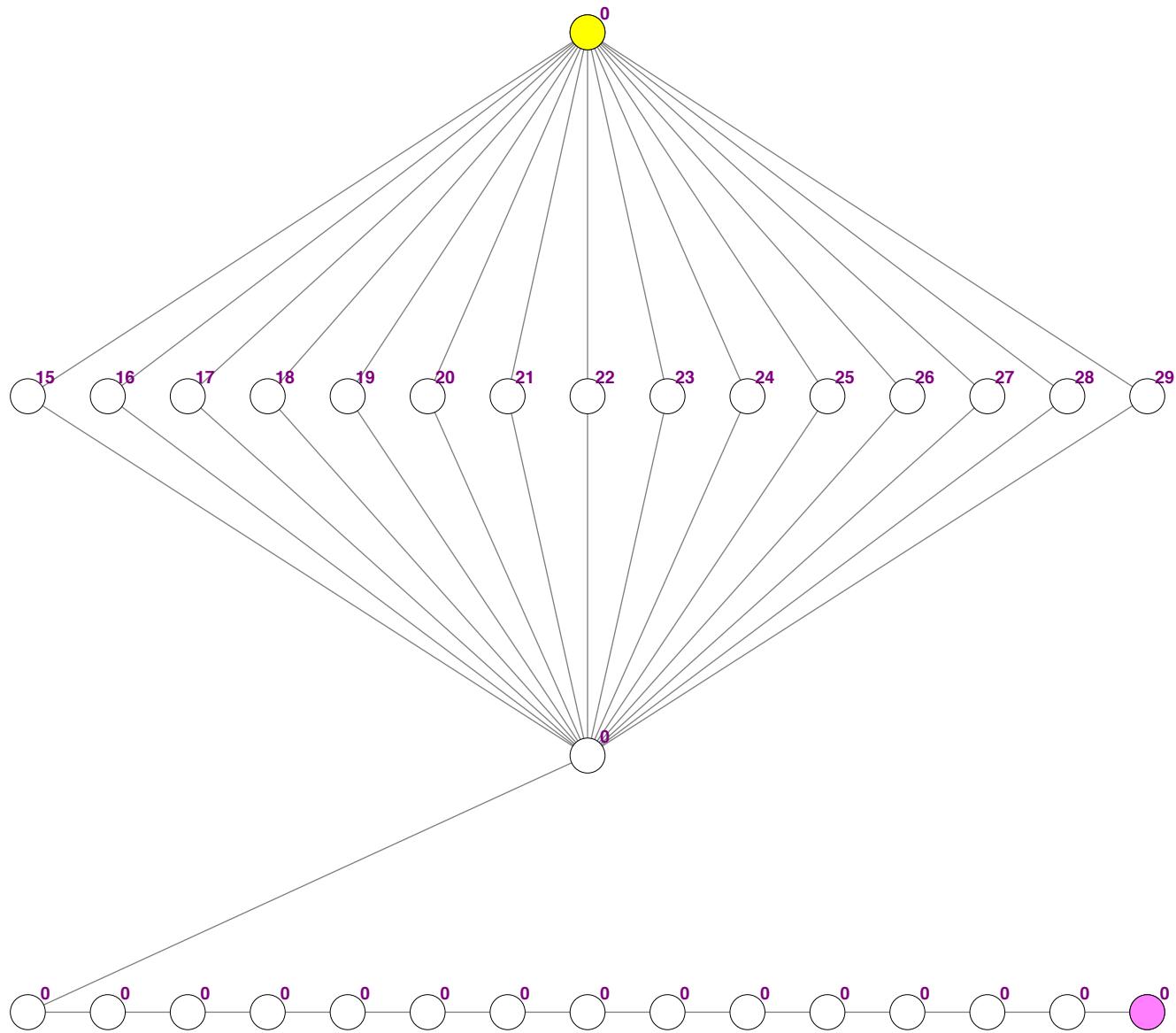
- Iterative Deepening
 - IDA* (Korf, 1985)
 - IDA*_{CR} (Sarkar et al, 1990)
 - IDA*_{IM} (Burns & Ruml, 2013)
 - EDA* (Sharon et al, 2014)



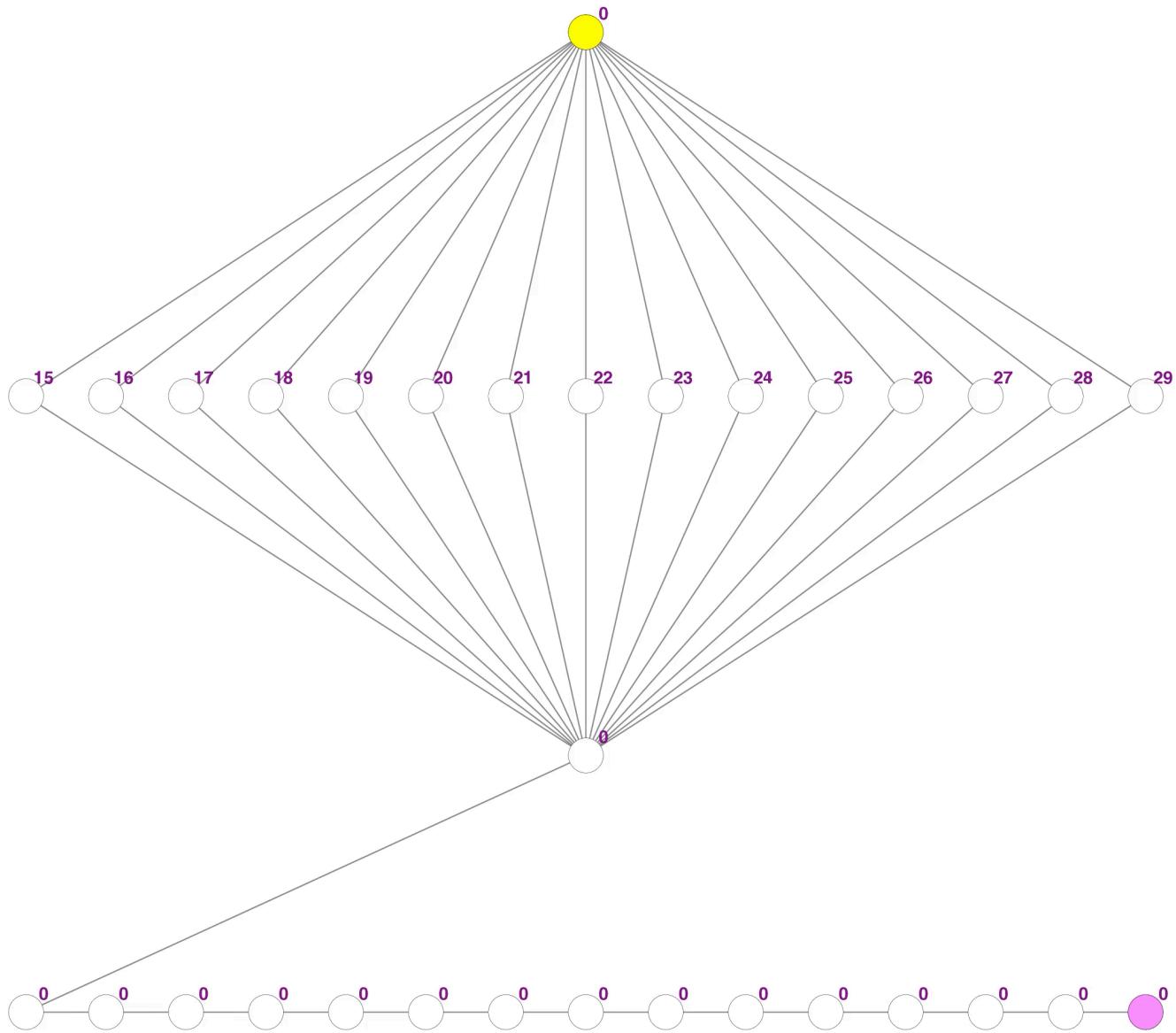
A* (B/B')

- A* with a consistent heuristic is optimal*
- With an inconsistent heuristic A* might do 2^N expansions of N states
- B and B' immediately propagate shorter paths
 - Will do at most N^2 expansions of N states

N states

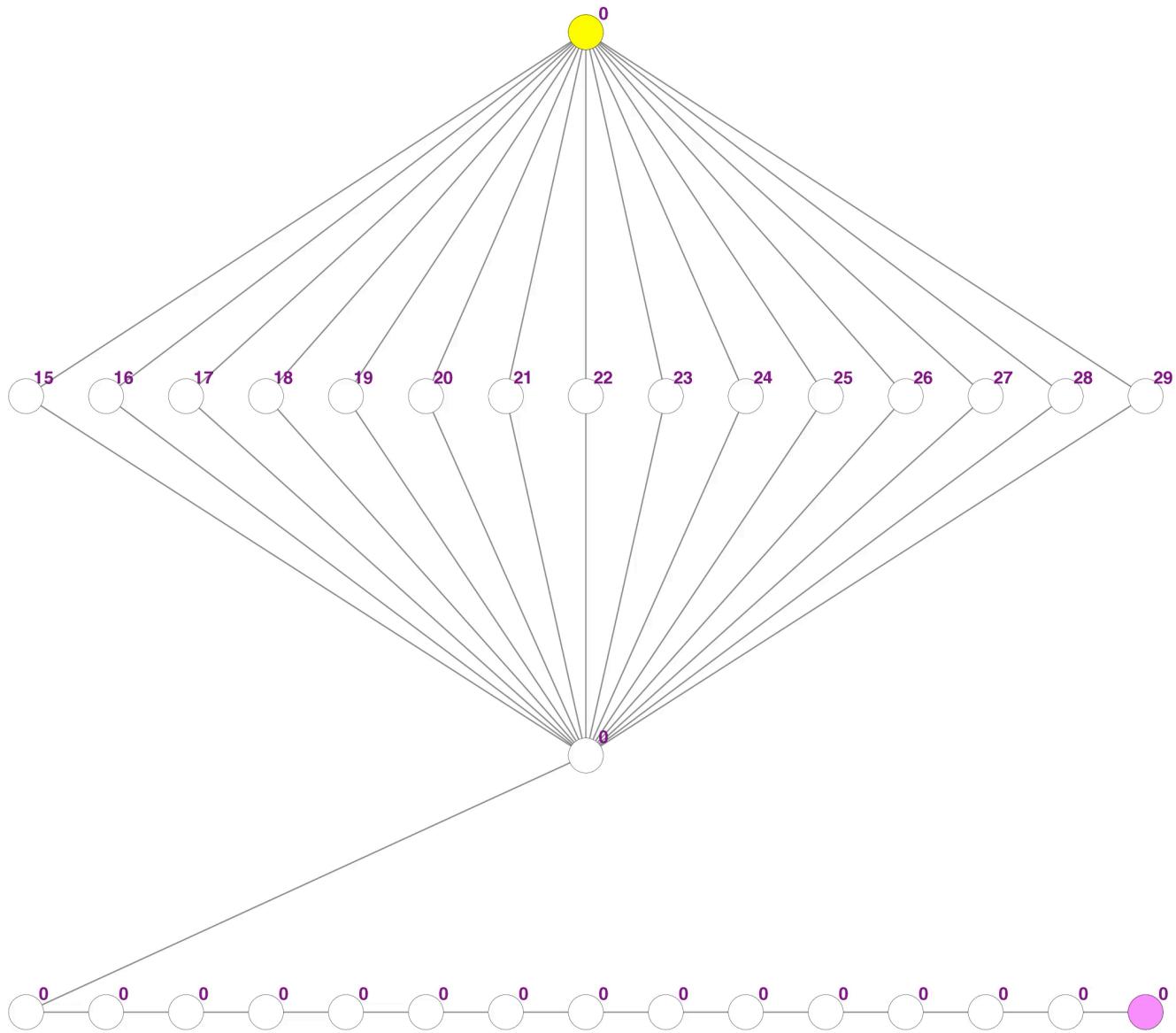


N states



Previous Work

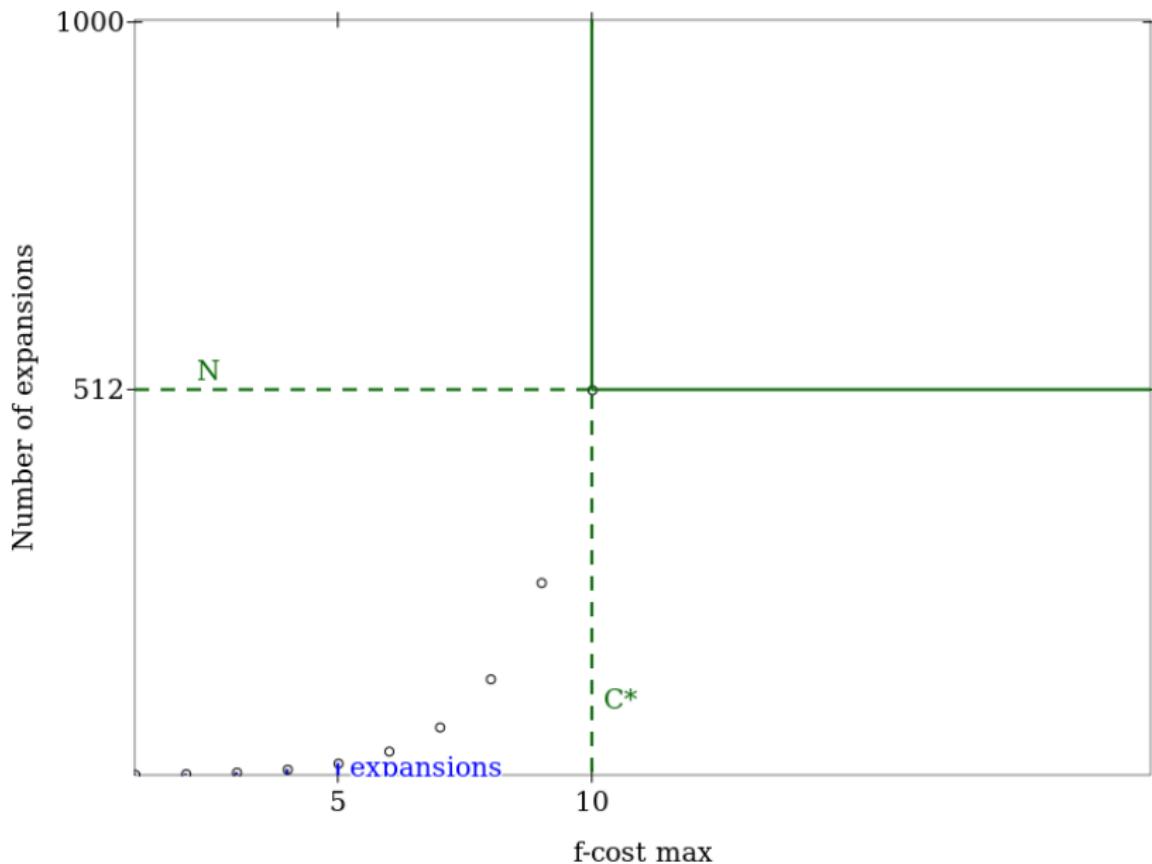
- Inconsistent Heuristics
 - B/B' (Martelli 1977; Mero, 1984)
 - Delay (Sturtevant et al, 2008)
 - BPMX (Felner et al, 2011)



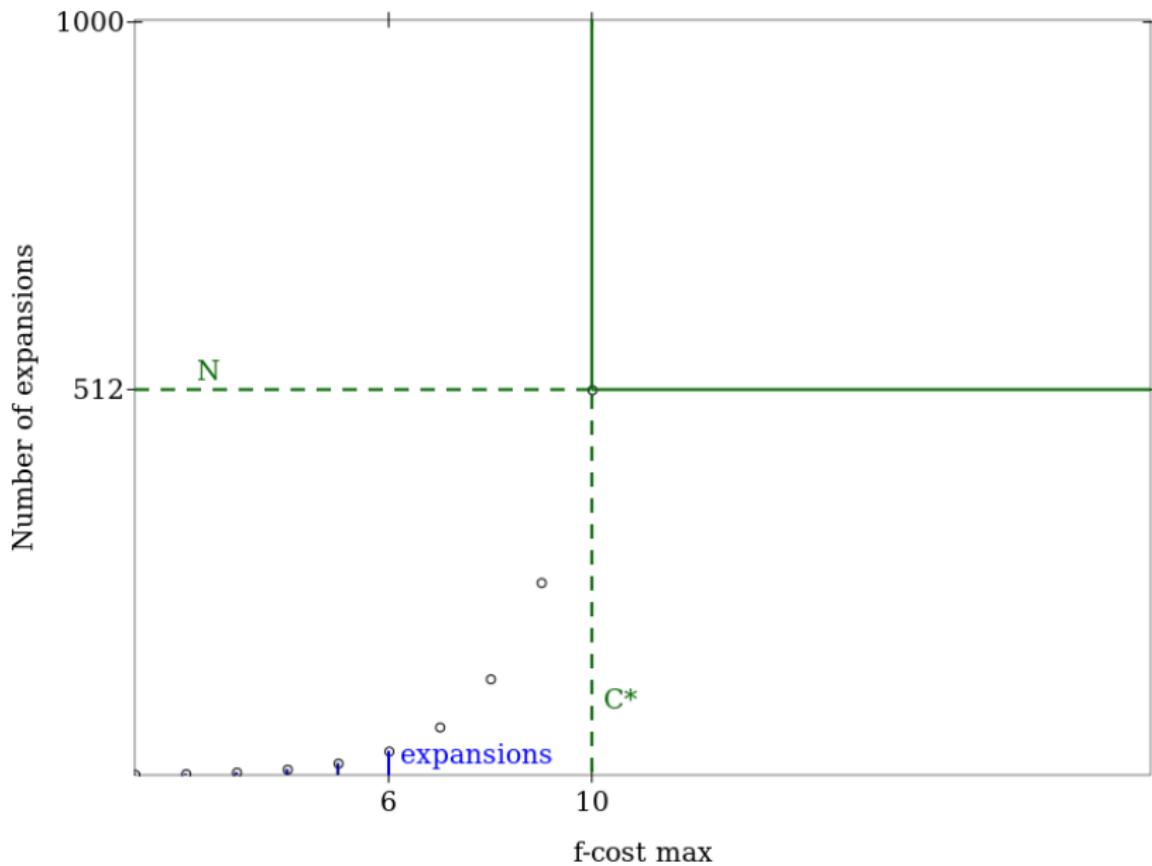
Demos

- All demos shown here runnable online:
 - <https://www.movingai.com/SAS/BTS/>
- Also running on my iPad; can give detailed demo

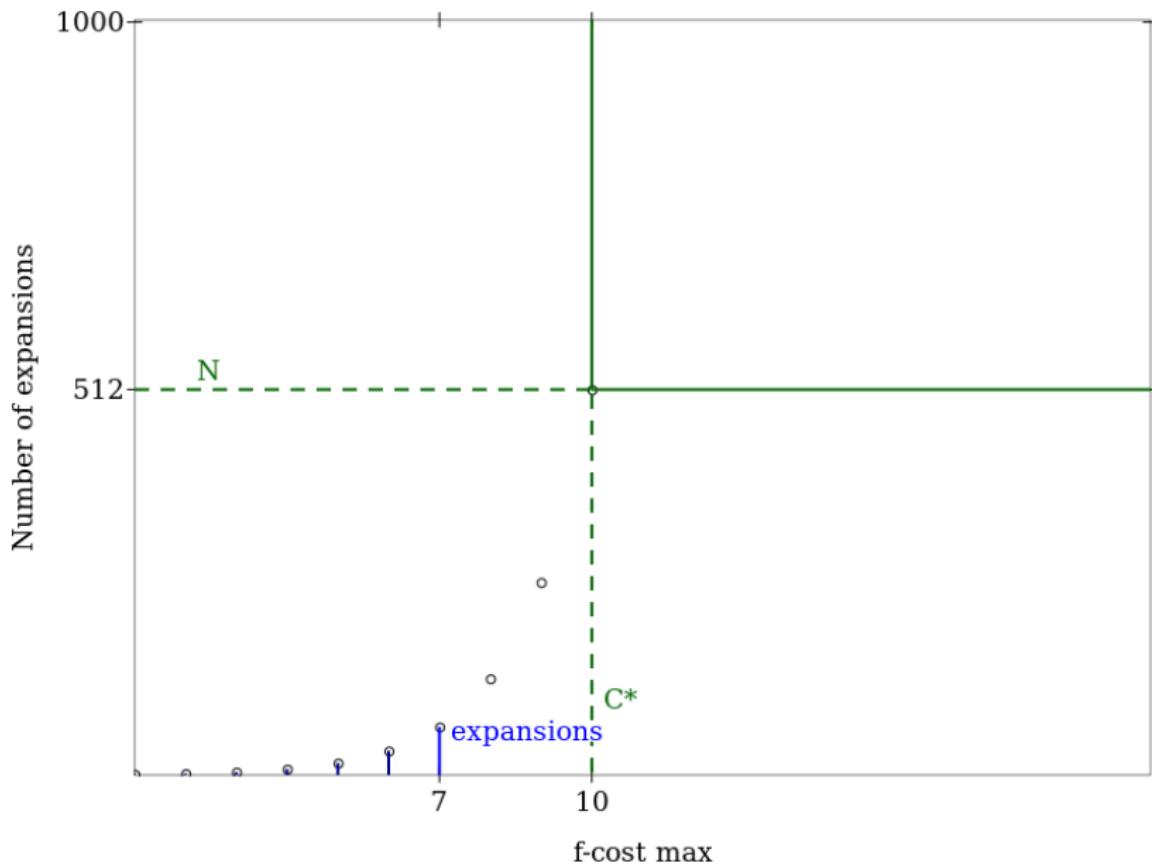
IDA* — Good Case



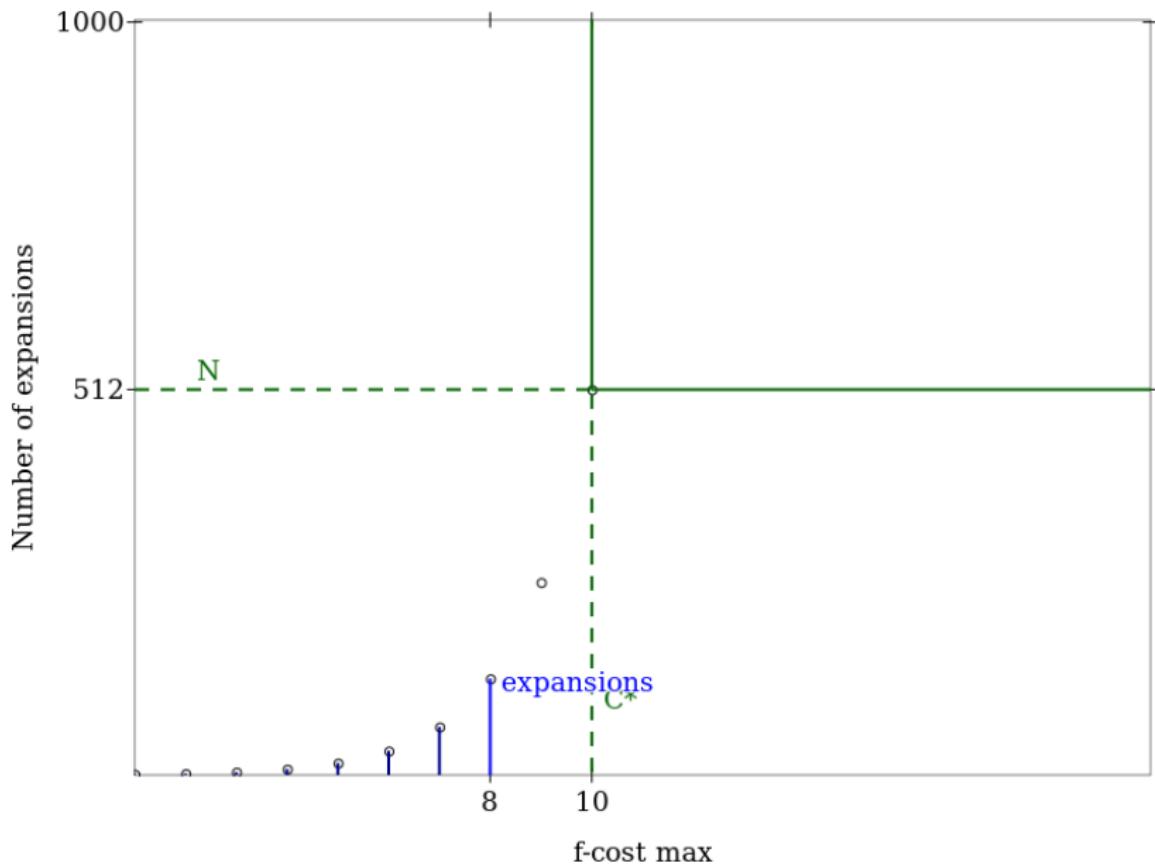
IDA* — Good Case



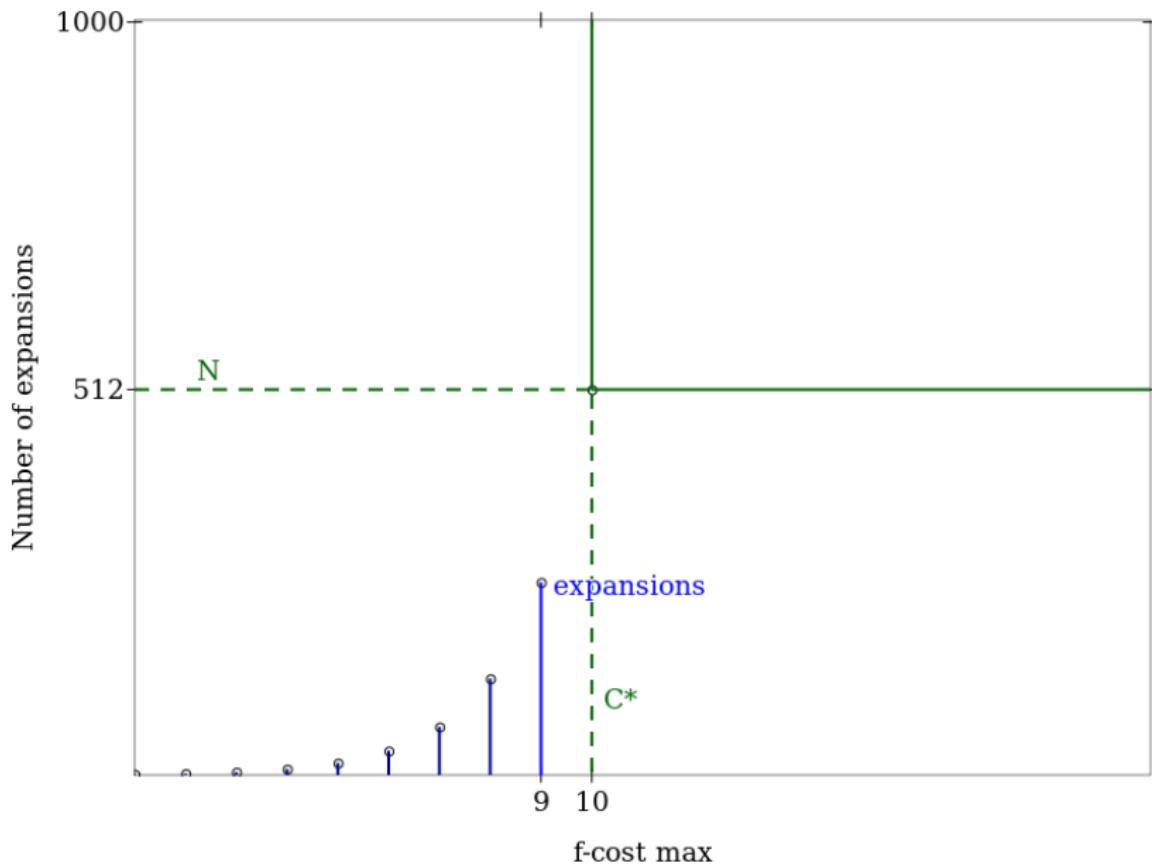
IDA* — Good Case



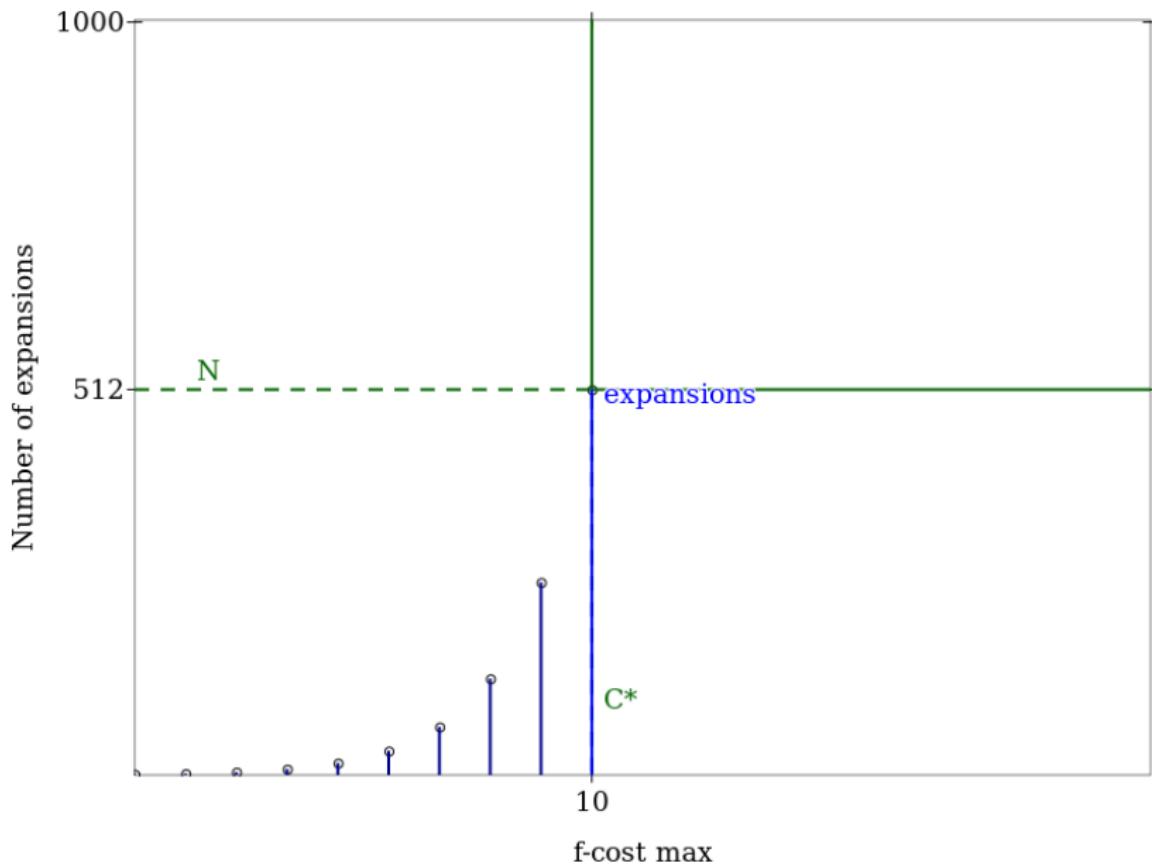
IDA* — Good Case



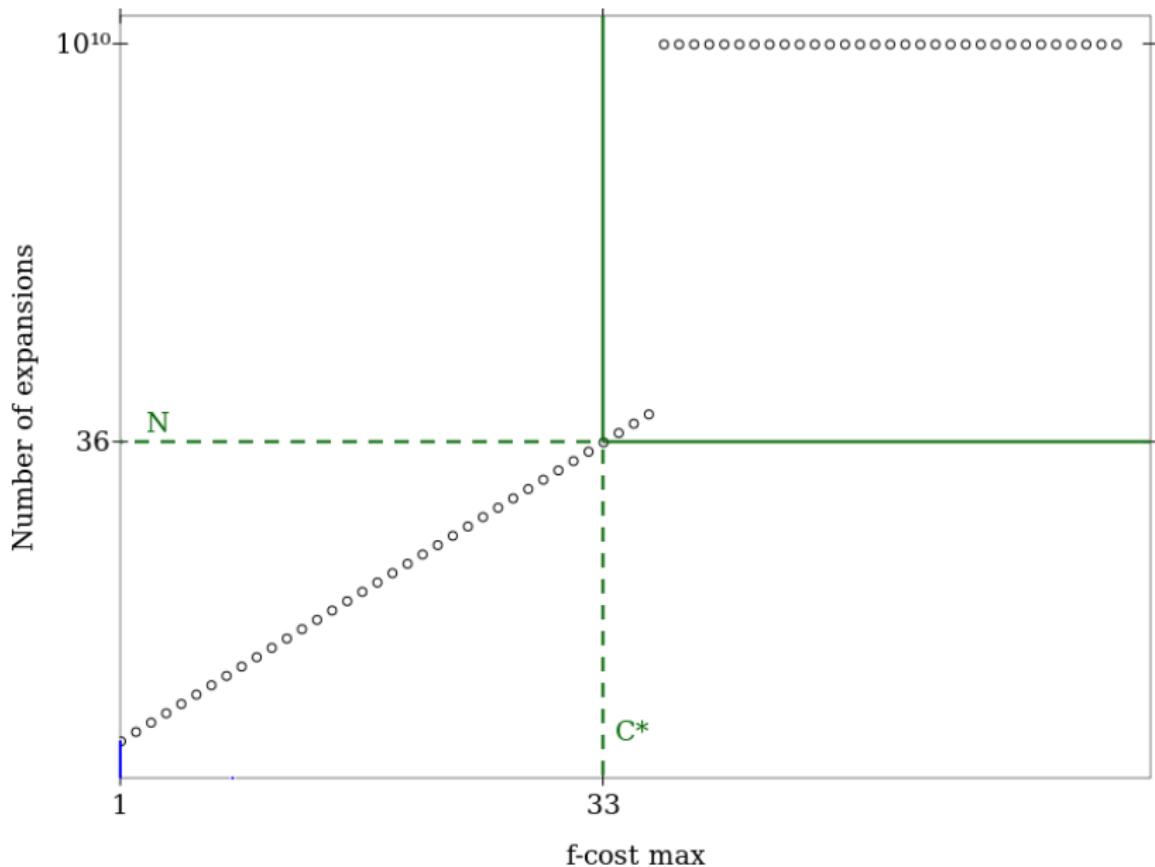
IDA* — Good Case



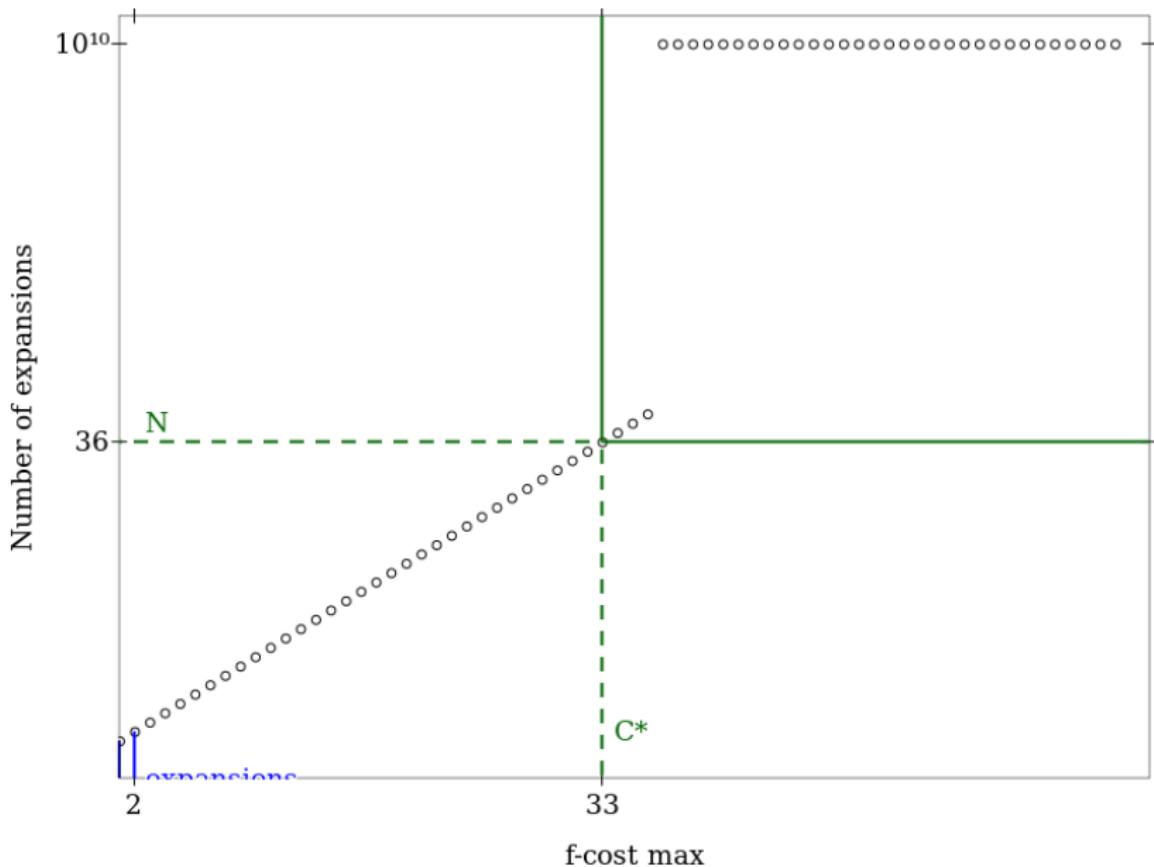
IDA* — Good Case



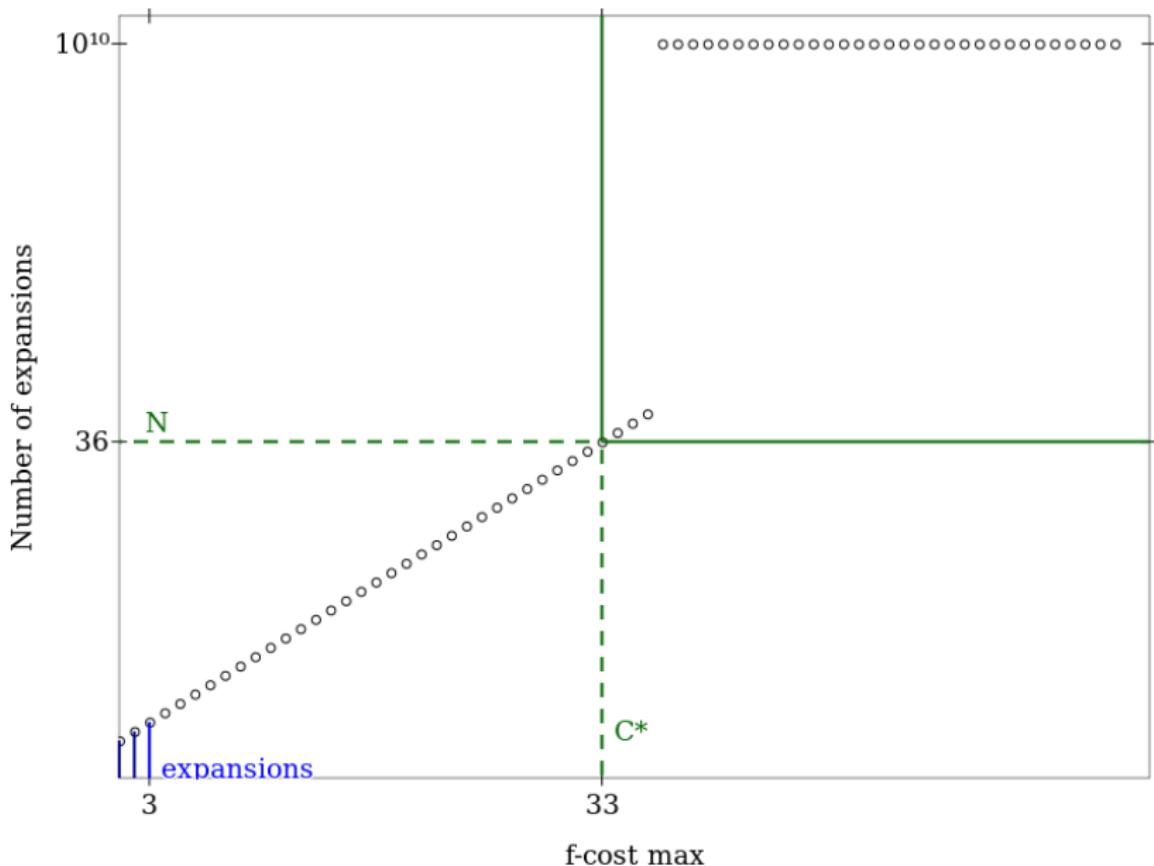
IDA* — Bad Case



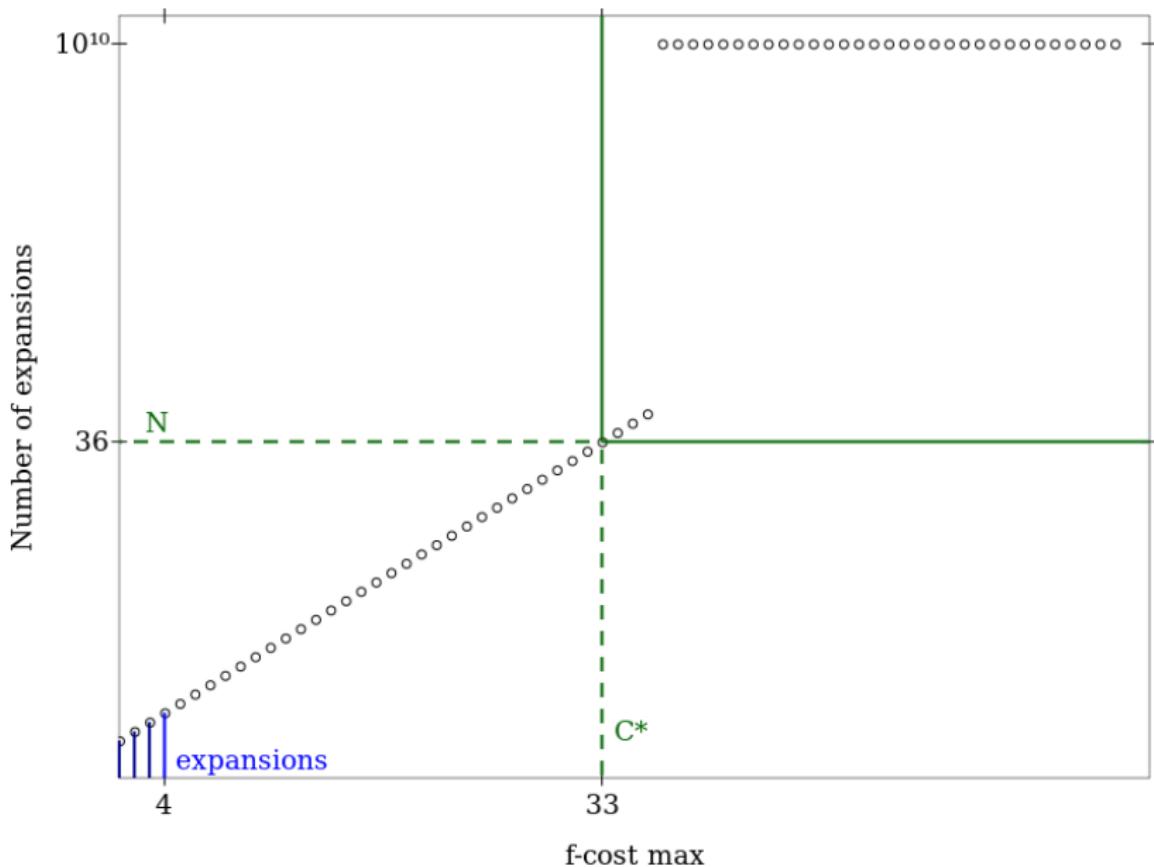
IDA* — Bad Case



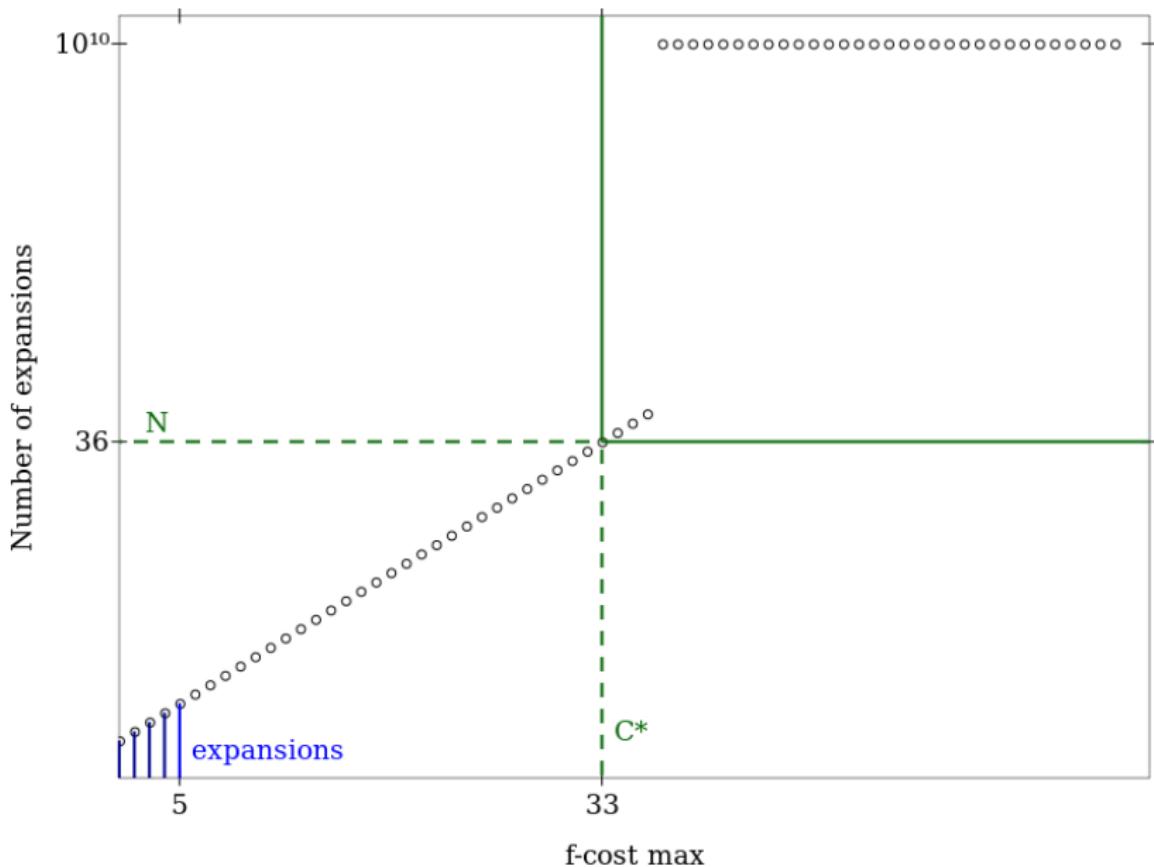
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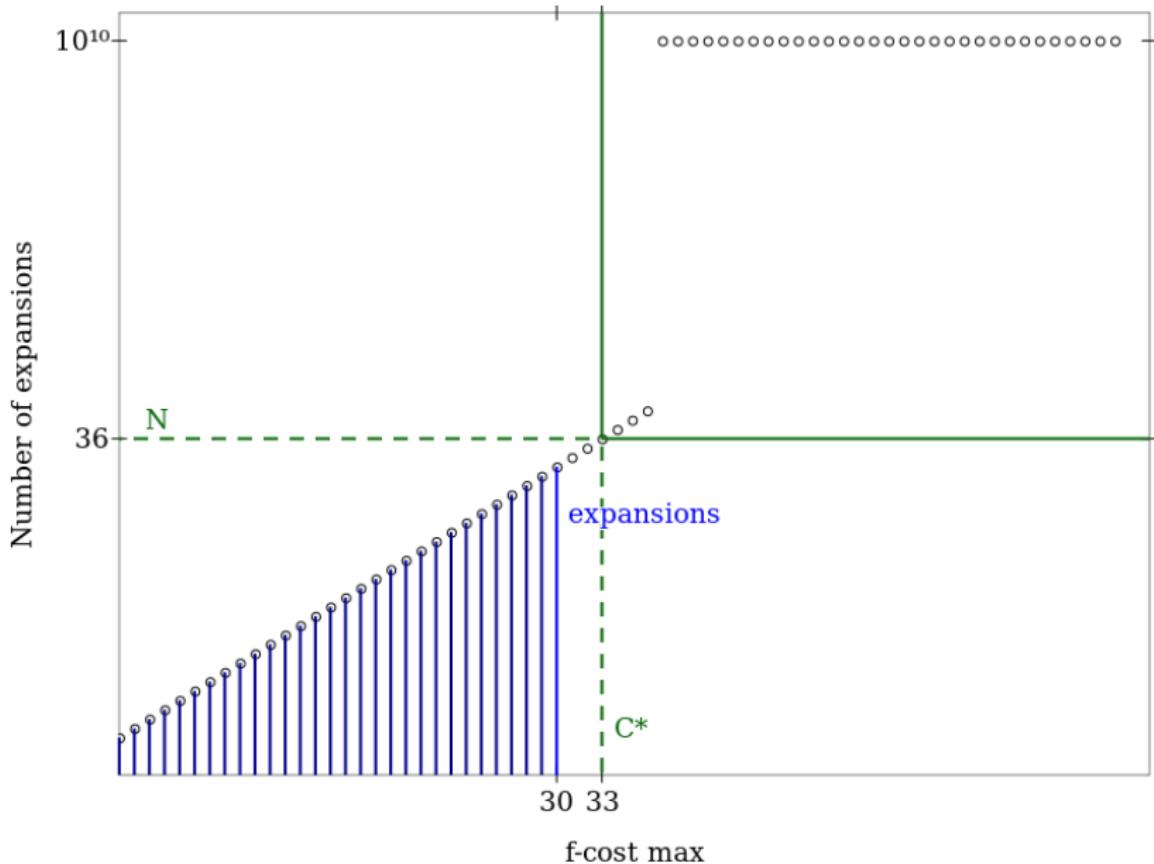
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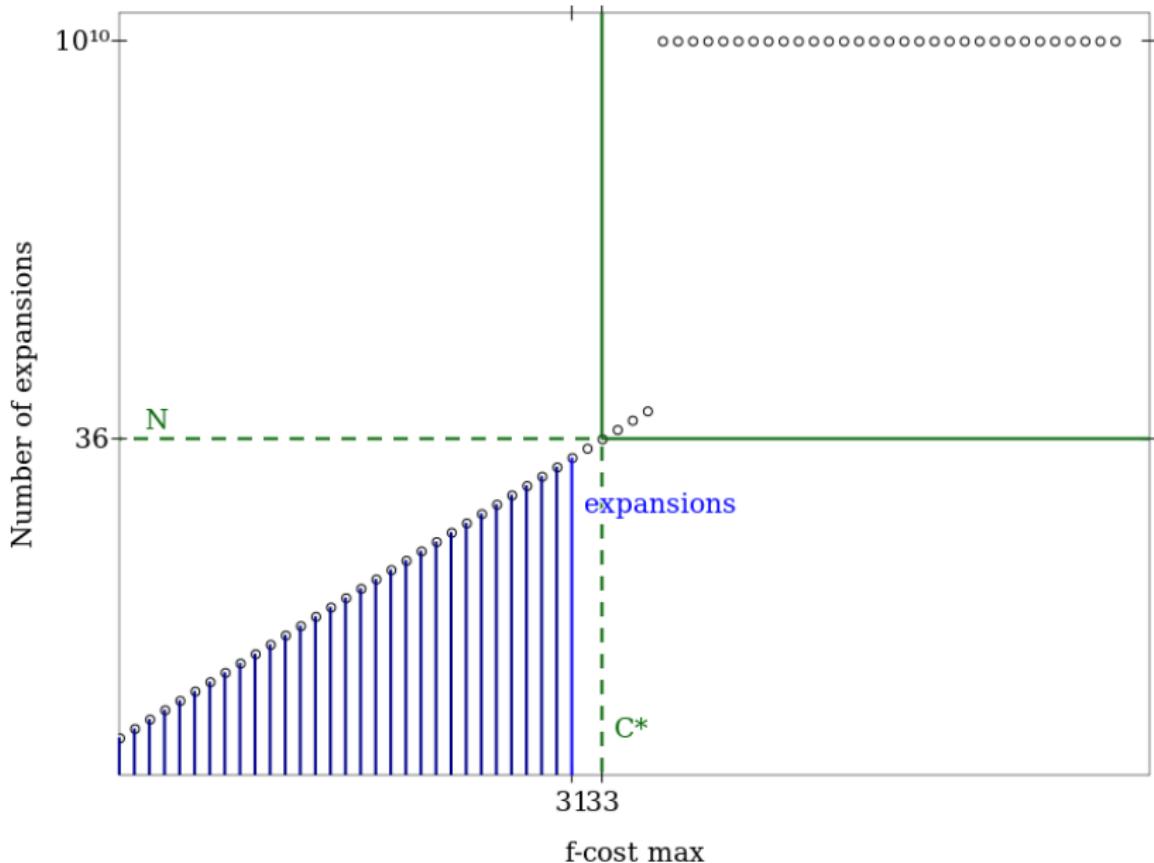
IDA* — Bad Case



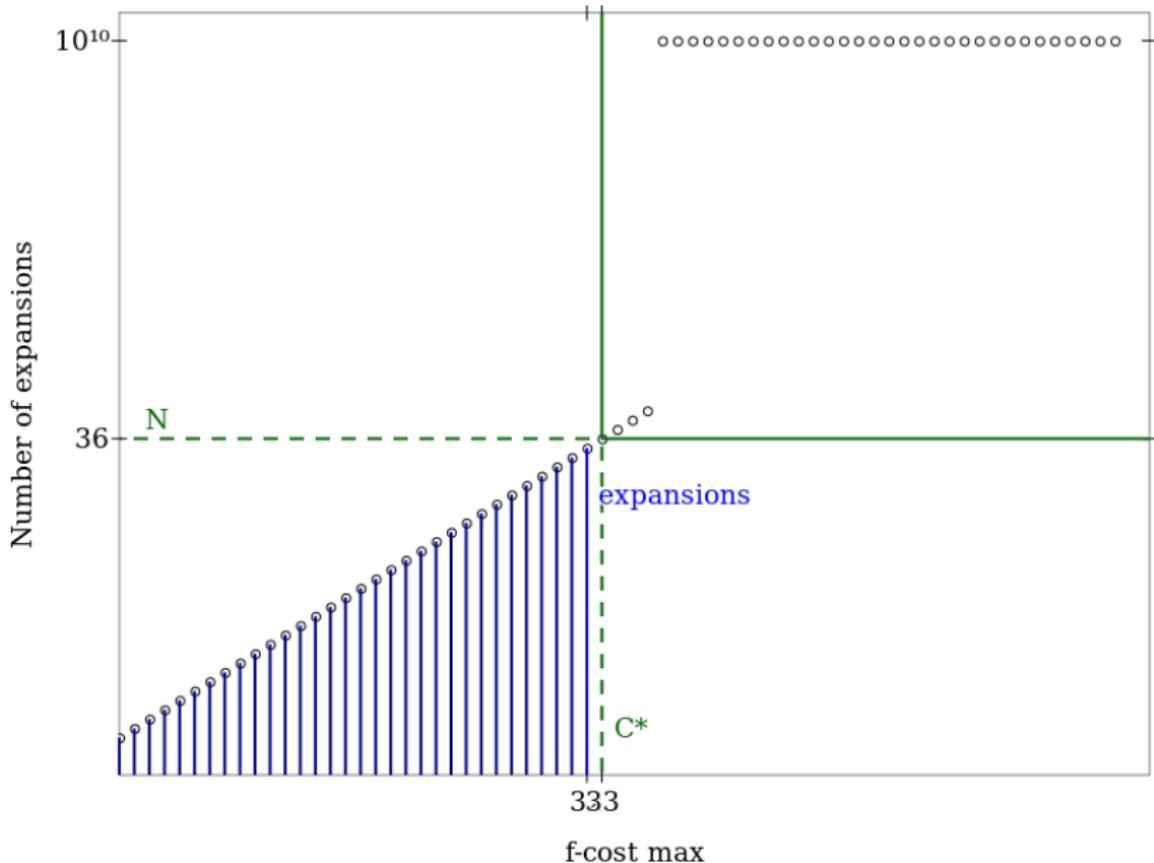
IDA* — Bad Case



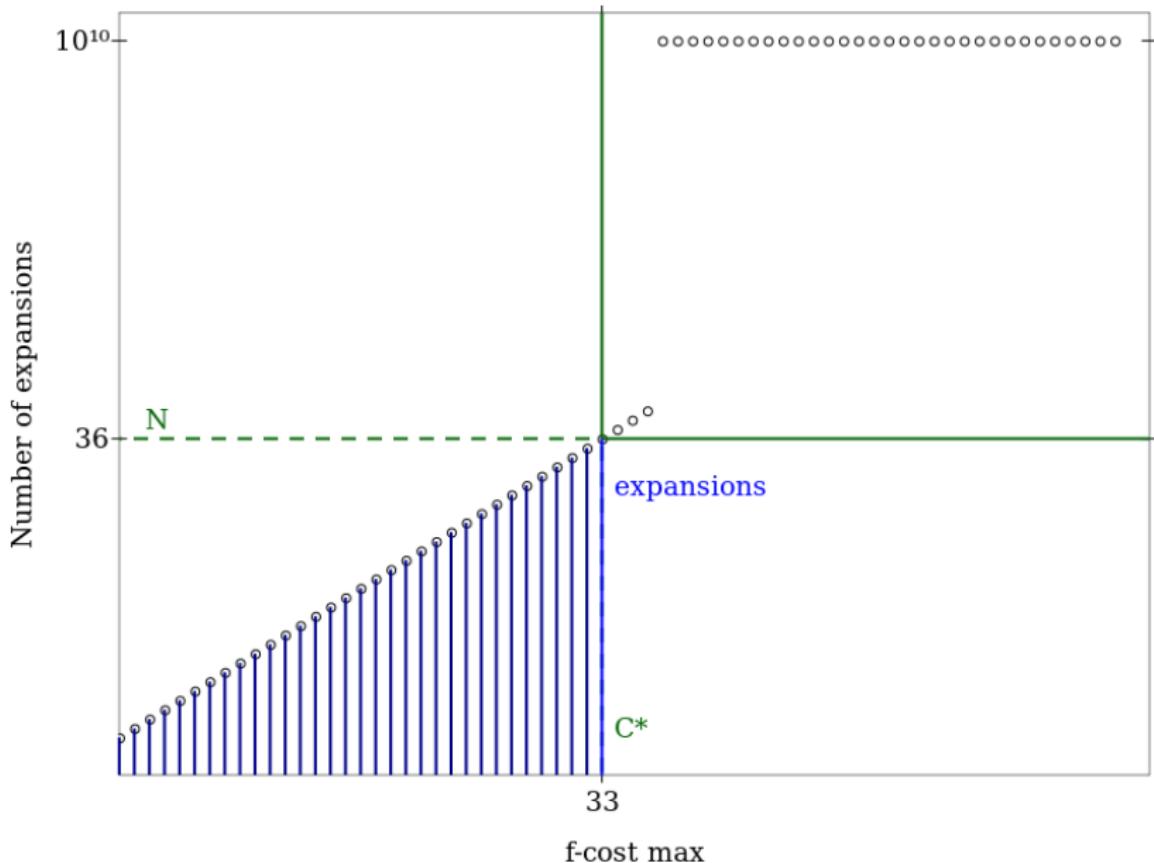
IDA* — Bad Case



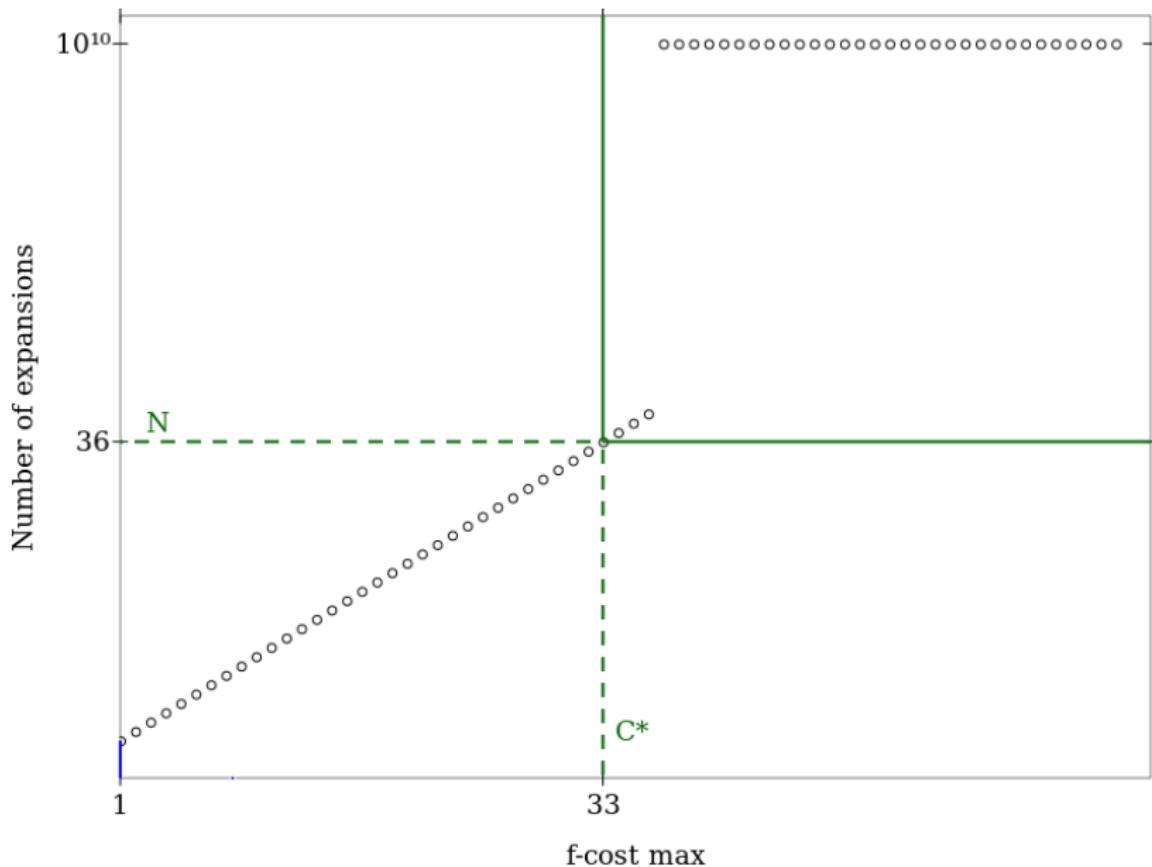
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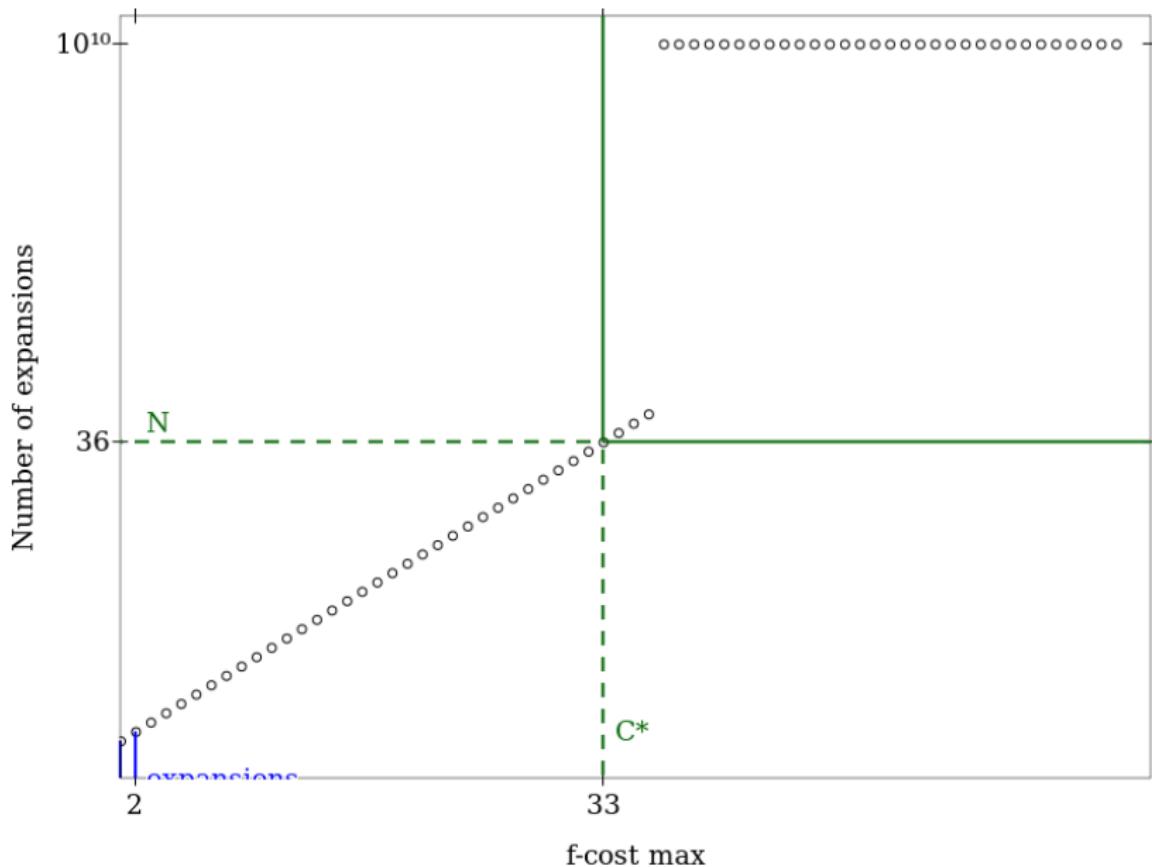
IDA* — Bad Case



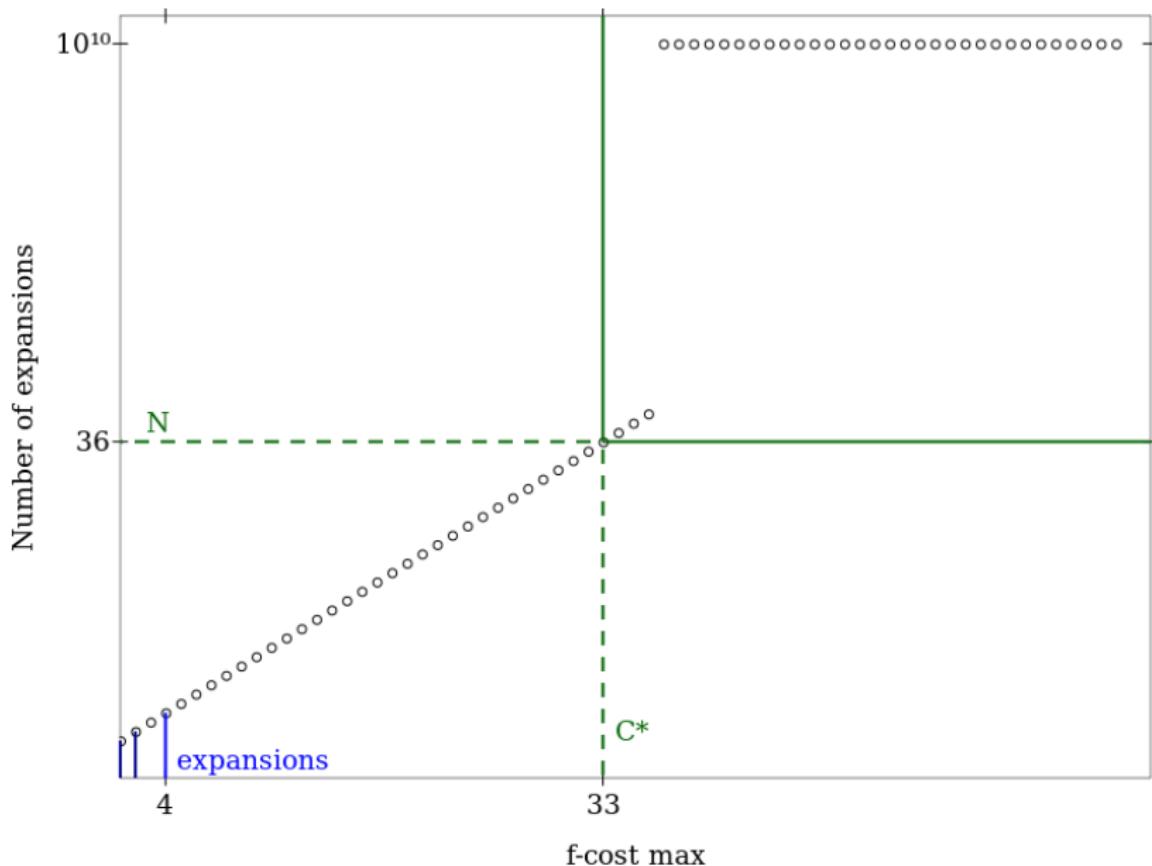
EDA*



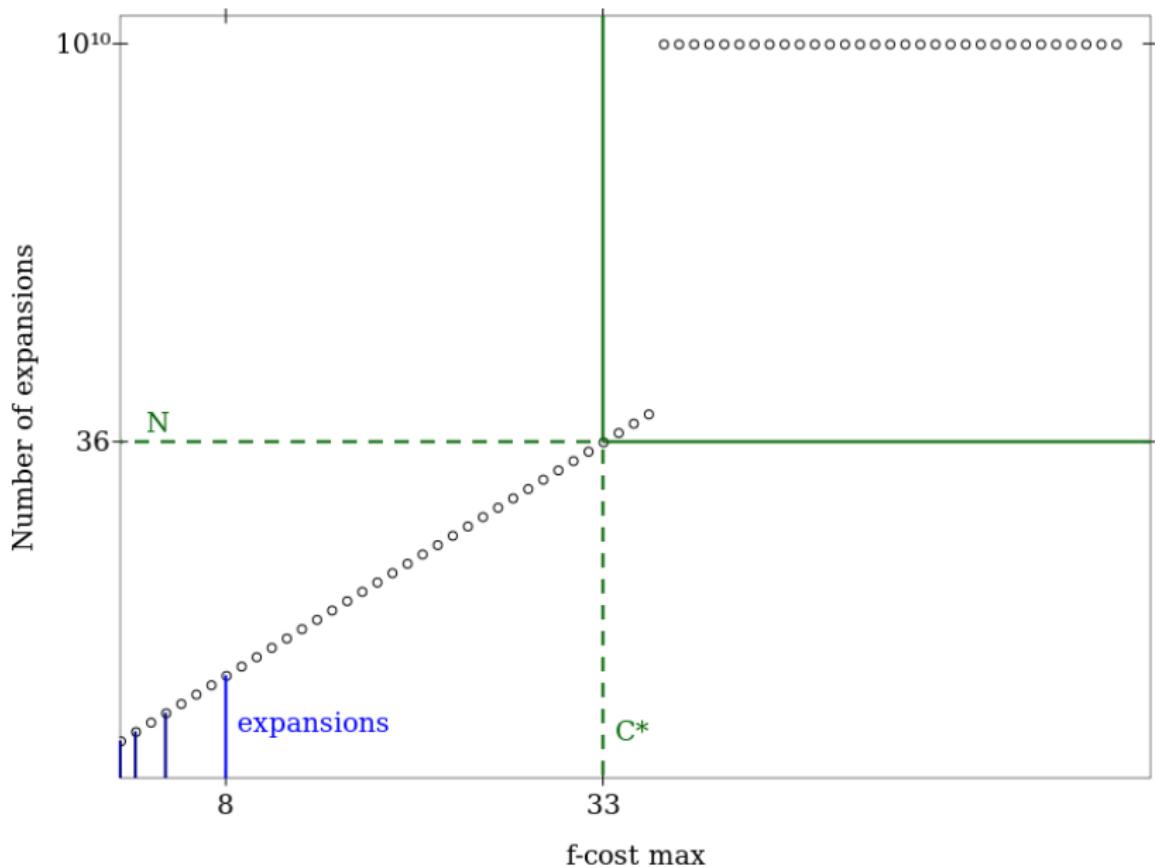
EDA*



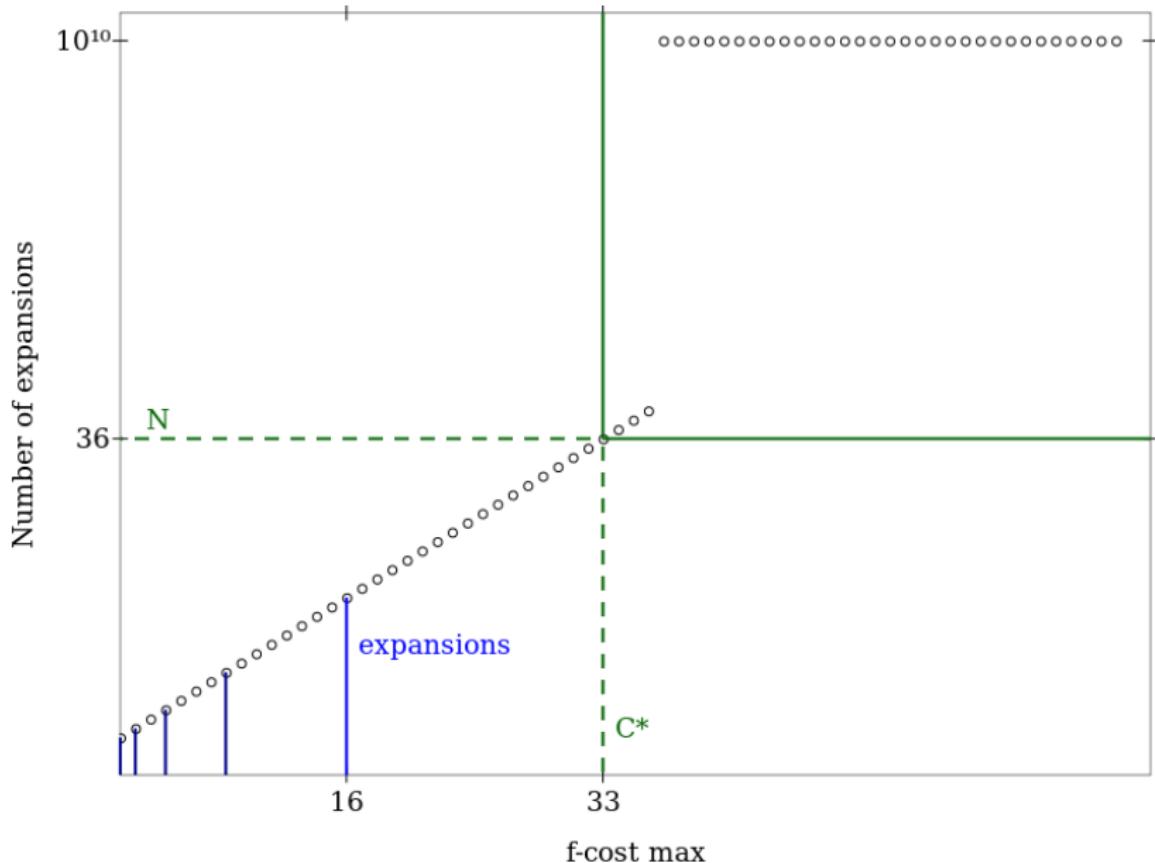
EDA*



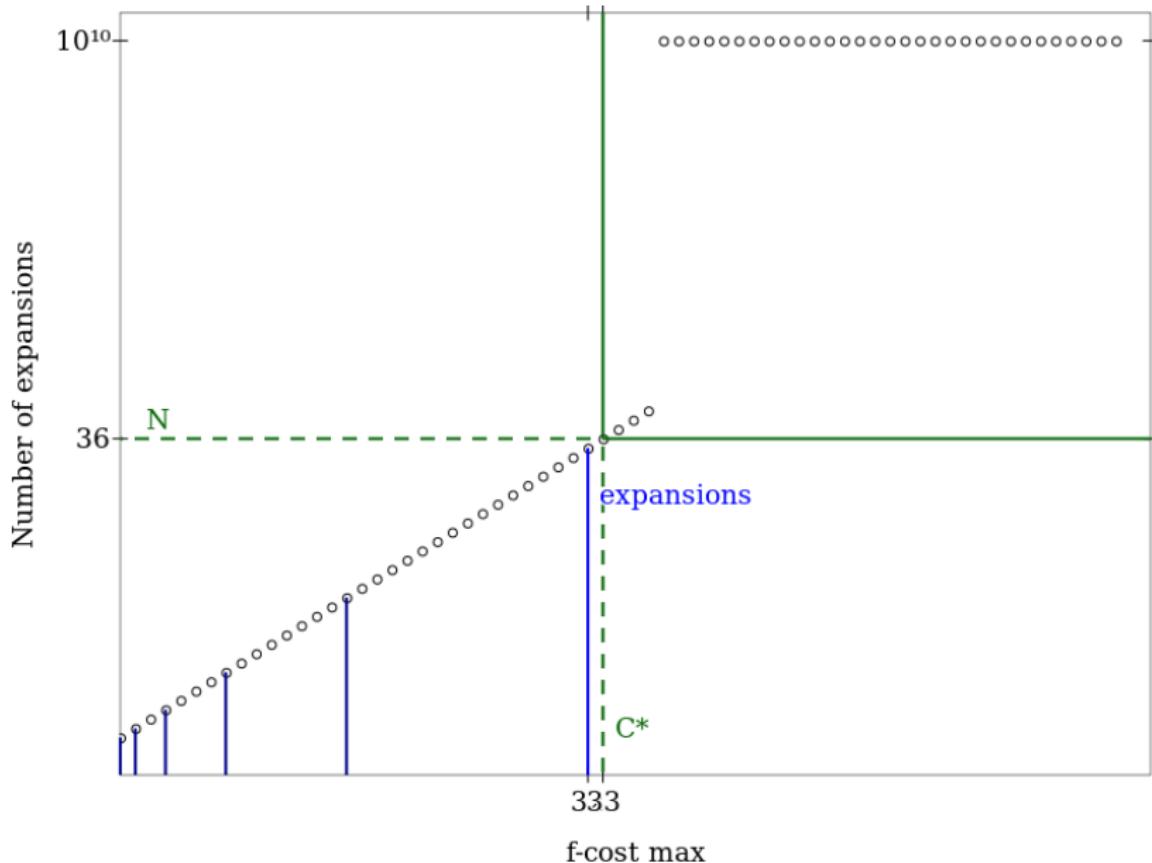
EDA*



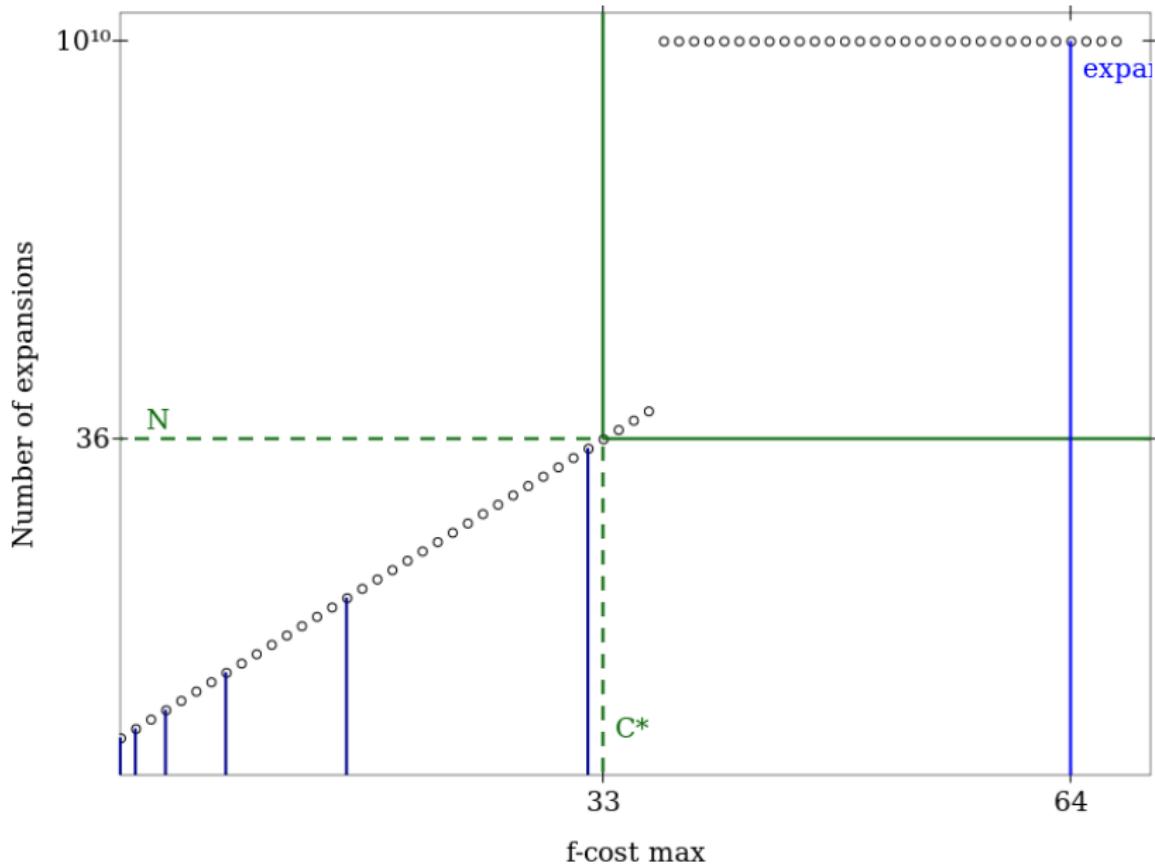
EDA*



EDA*



EDA*



IBEX (main idea)

For budget = 2, 4, 8, 16, ...:

```
cost_bound = Oracle(budget)
```

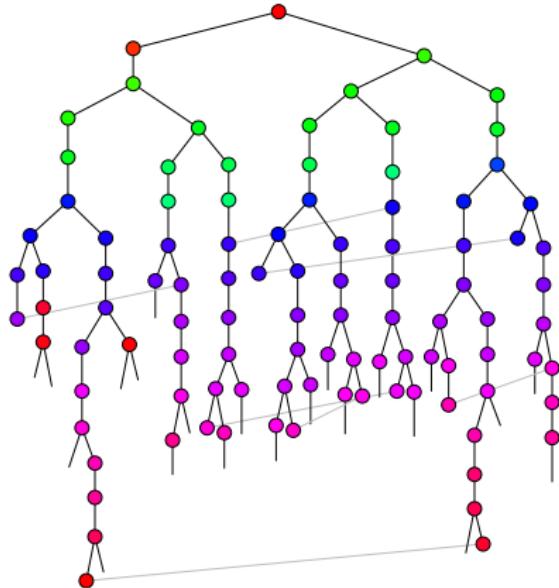
```
search within cost_bound and within budget
```

Oracle(budget) returns largest cost for which budget is sufficient.

IBEX (main idea): With an oracle

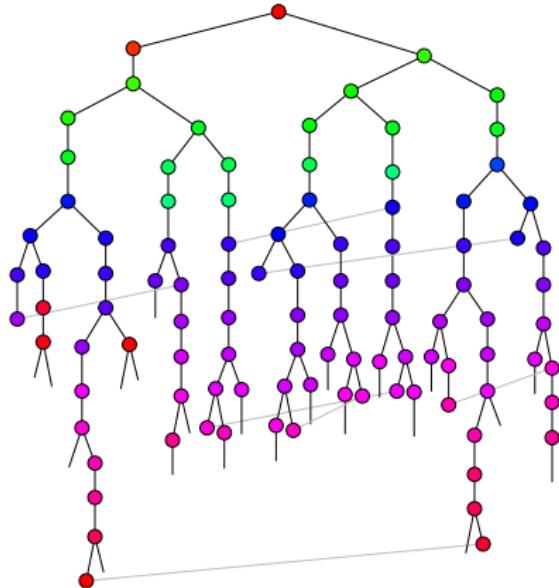
budget f -cost expansions

2



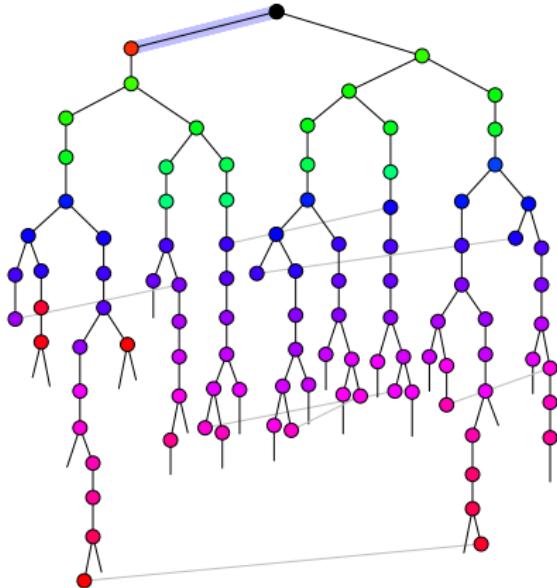
IBEX (main idea): With an oracle

budget	$f\text{-cost}$	expansions
2	11.2	



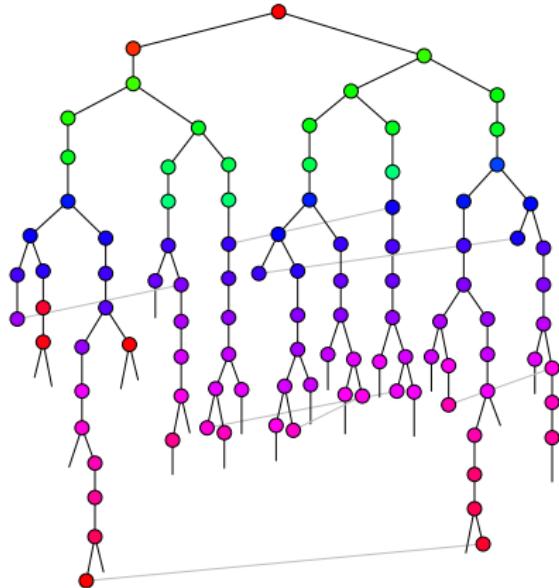
IBEX (main idea): With an oracle

budget f -cost expansions



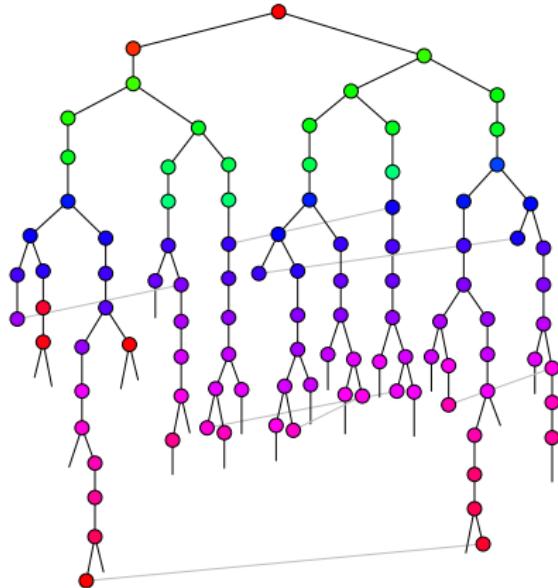
IBEX (main idea): With an oracle

budget	f -cost	expansions
2	11.2	2
4		



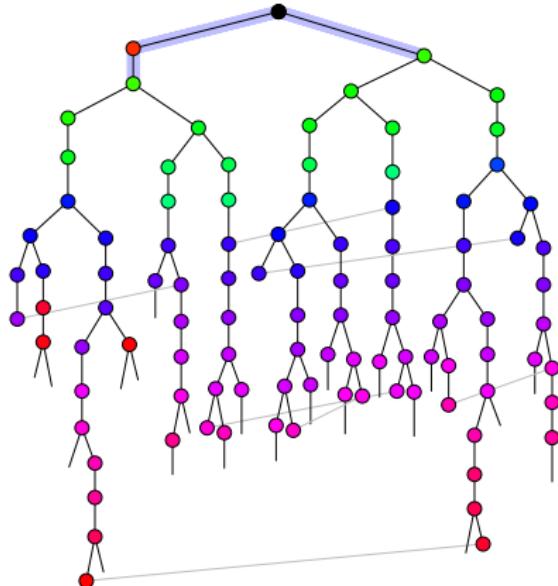
IBEX (main idea): With an oracle

budget	f -cost	expansions
2	11.2	
4	13.5	2



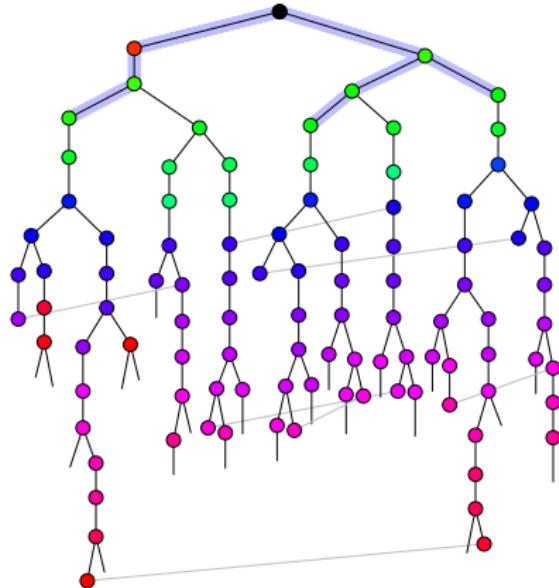
IBEX (main idea): With an oracle

budget	f -cost	expansions
2	11.2	2
4	13.5	4



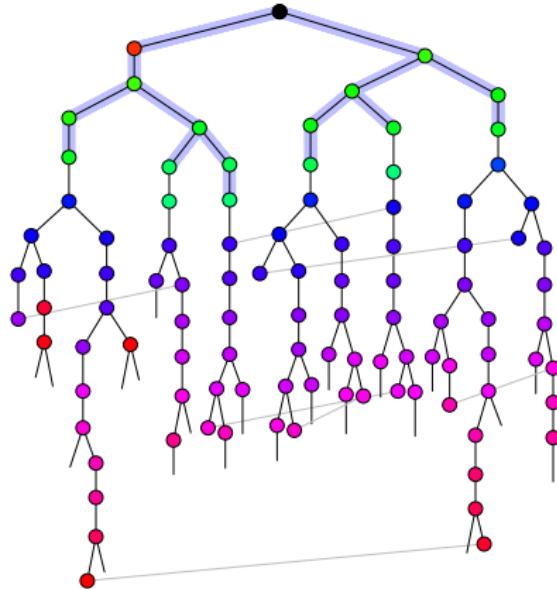
IBEX (main idea): With an oracle

budget	f -cost	expansions
2	11.2	2
4	13.5	4
8	13.9	8



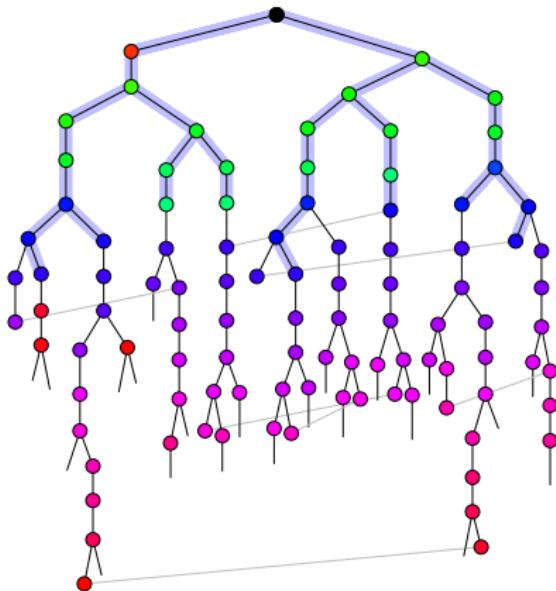
IBEX (main idea): With an oracle

budget	f -cost	expansions
2	11.2	2
4	13.5	4
8	13.9	8
16	14.4	16



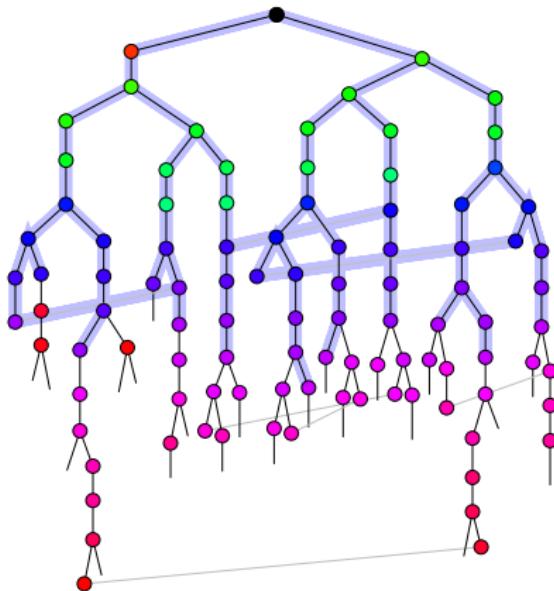
IBEX (main idea): With an oracle

budget	f -cost	expansions
2	11.2	2
4	13.5	4
8	13.9	8
16	14.4	16
32	16.8	30



IBEX (main idea): With an oracle

budget	f -cost	expansions
2	11.2	2
4	13.5	4
8	13.9	8
16	14.4	16
32	16.8	30
64	17.7	62



IBEX (main idea)

```
For budget = 2, 4, 8, 16, ...:  
    cost_bound = Oracle(budget)  
    search within cost_bound and within budget
```

IBEX (main idea)

For budget = 2, 4, 8, 16, ...:

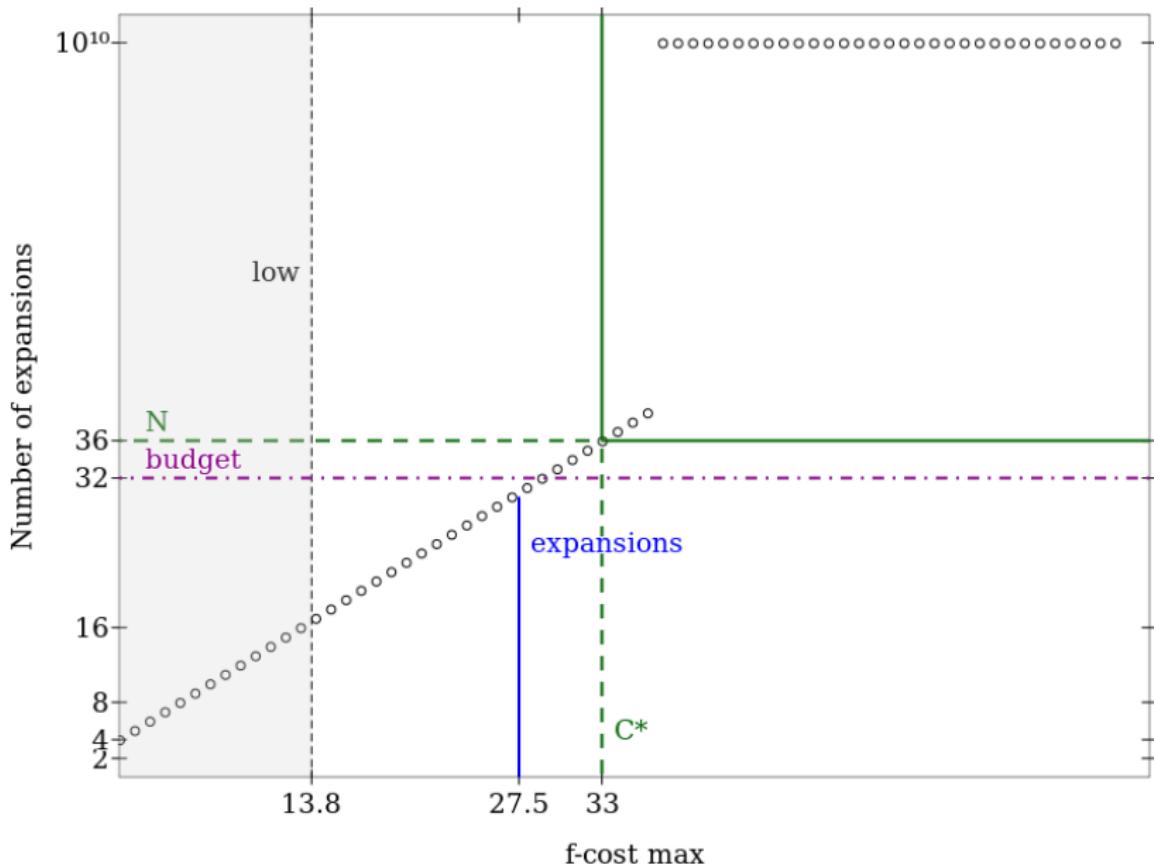
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search within cost_bound and within budget

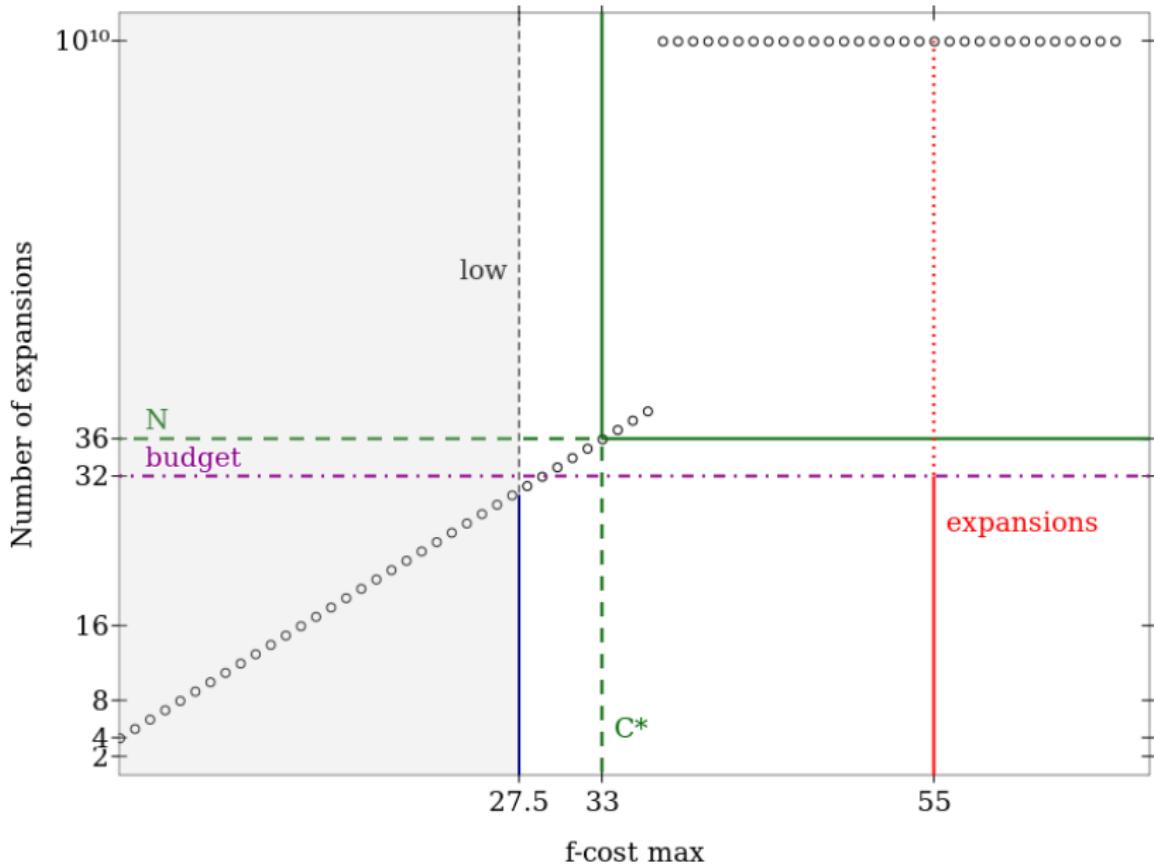
Oracle(budget) returns largest cost for which budget is sufficient.

Oracle(budget) = (budgeted) exponential search

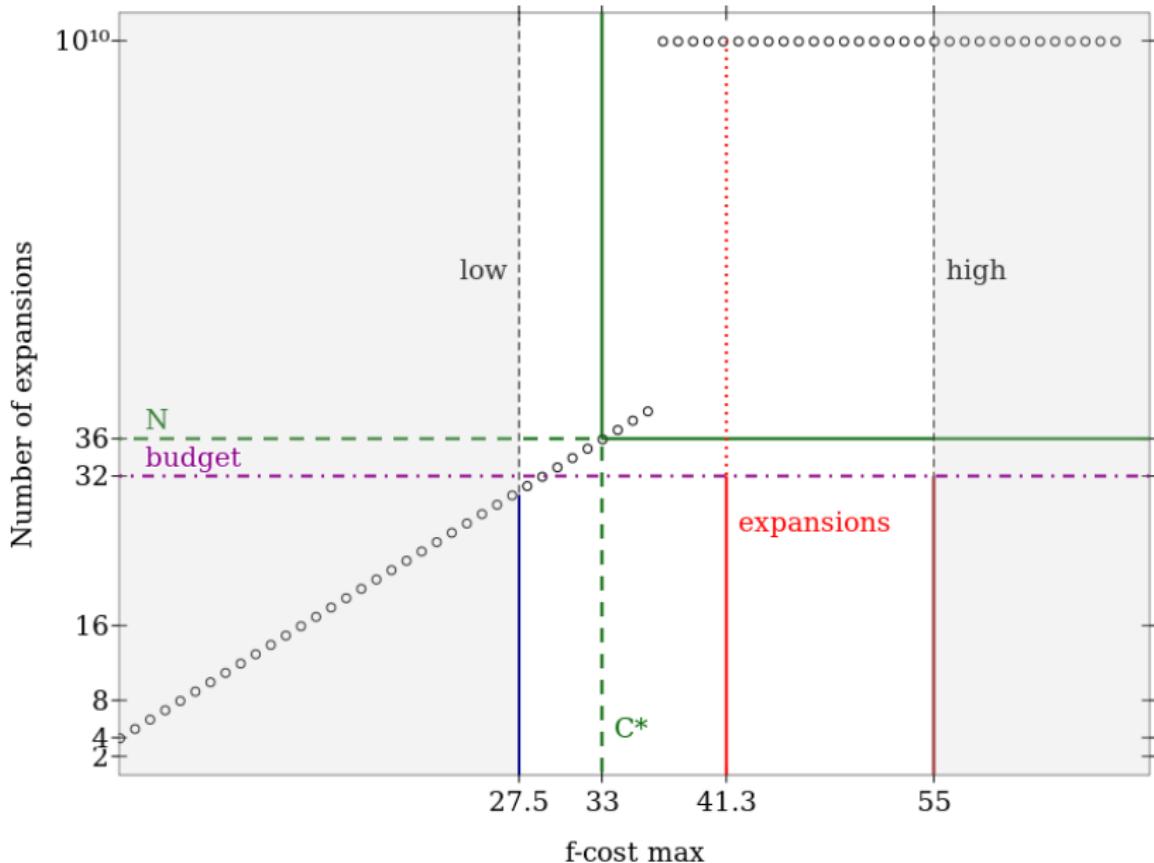
IBEX (main idea)



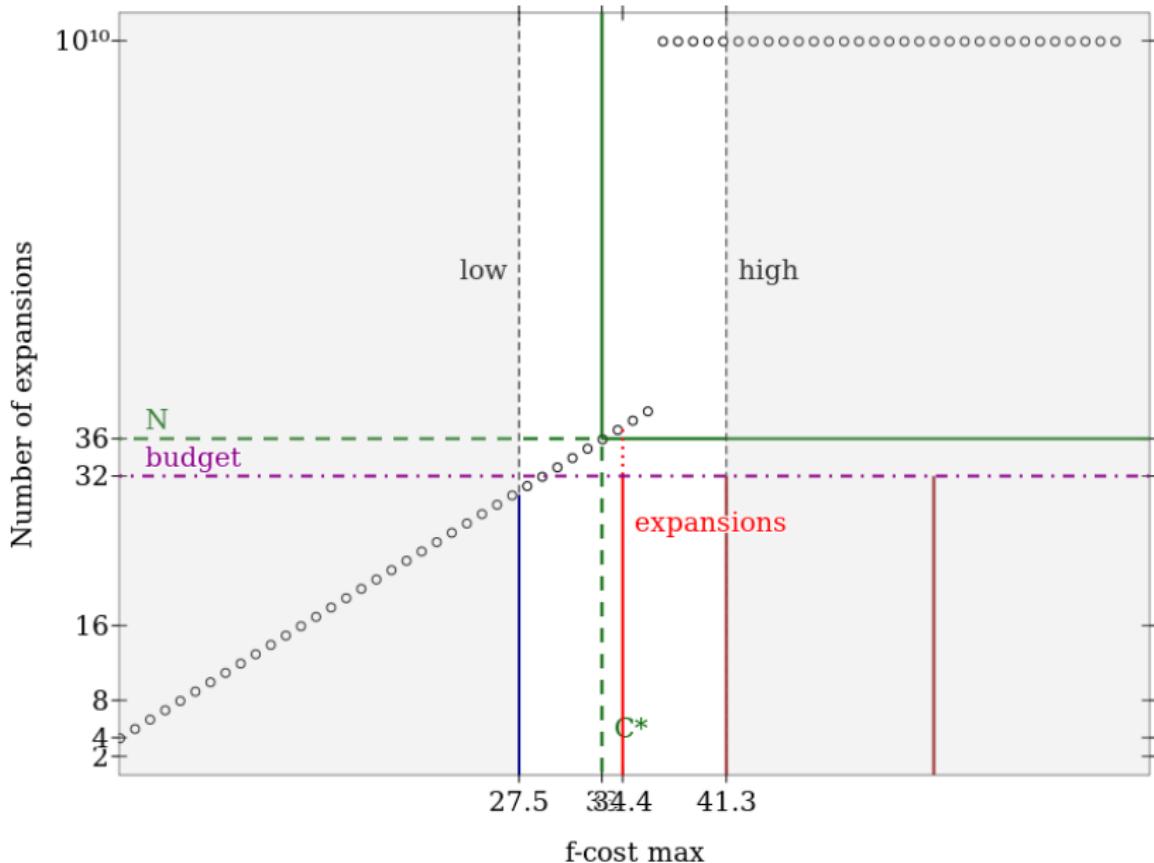
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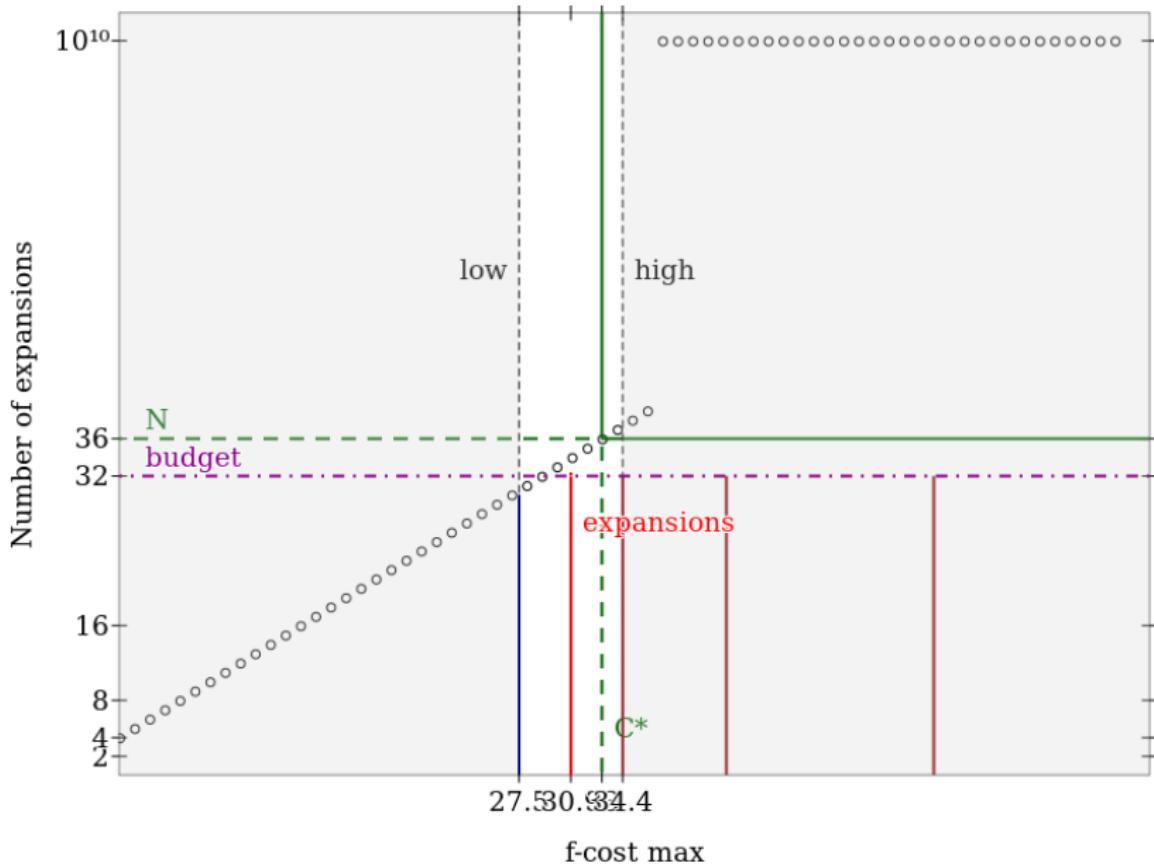
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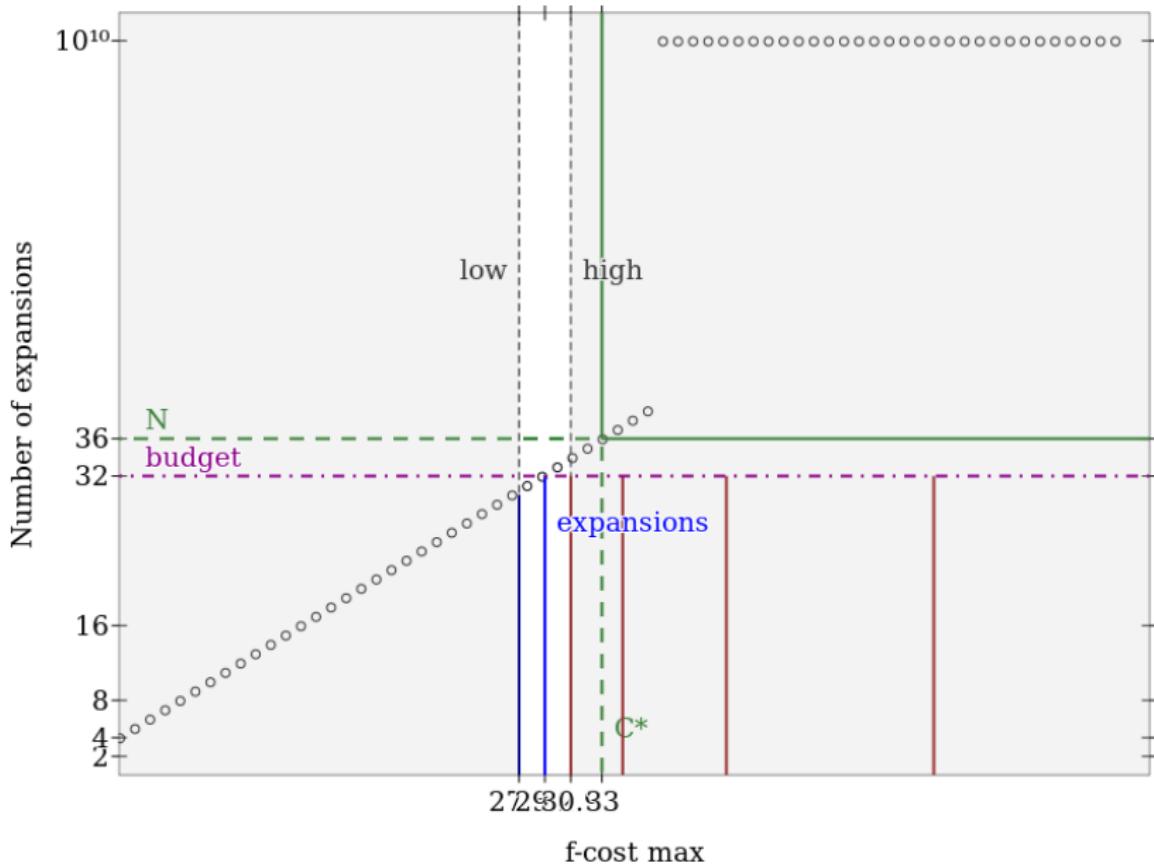
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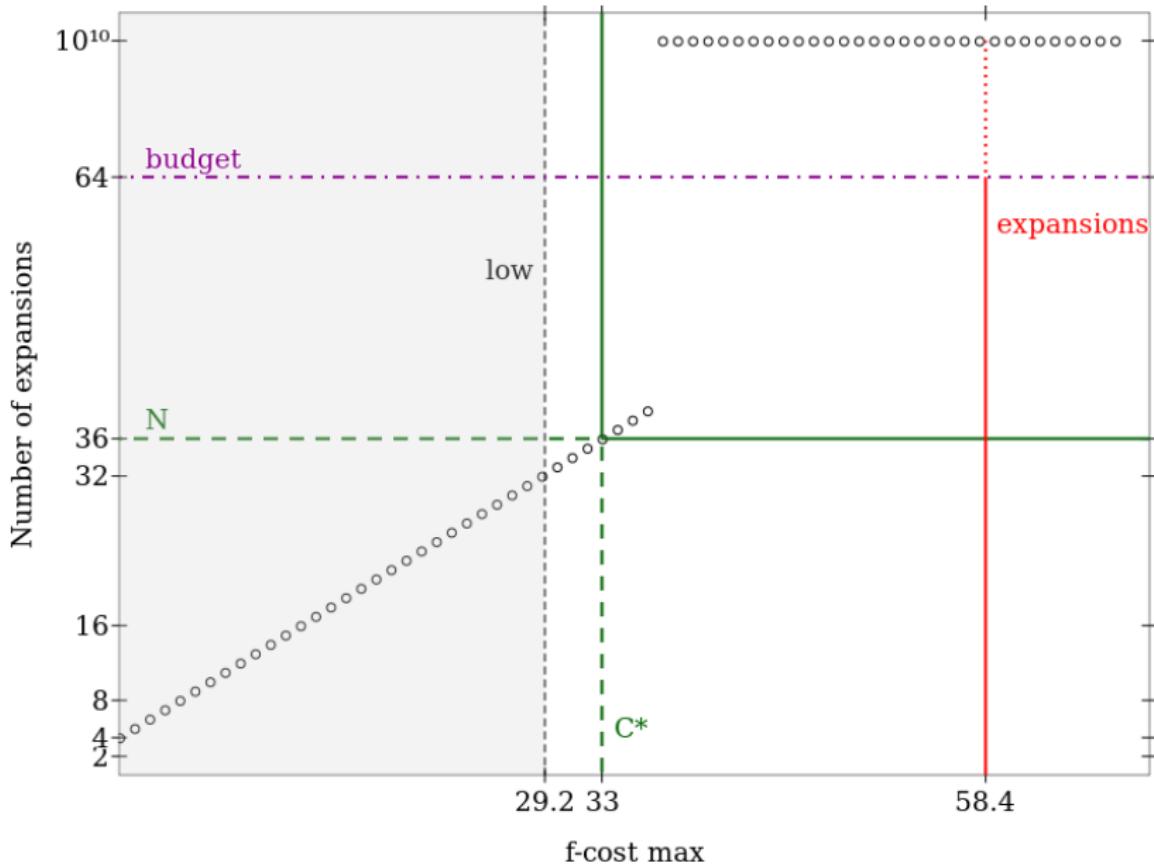
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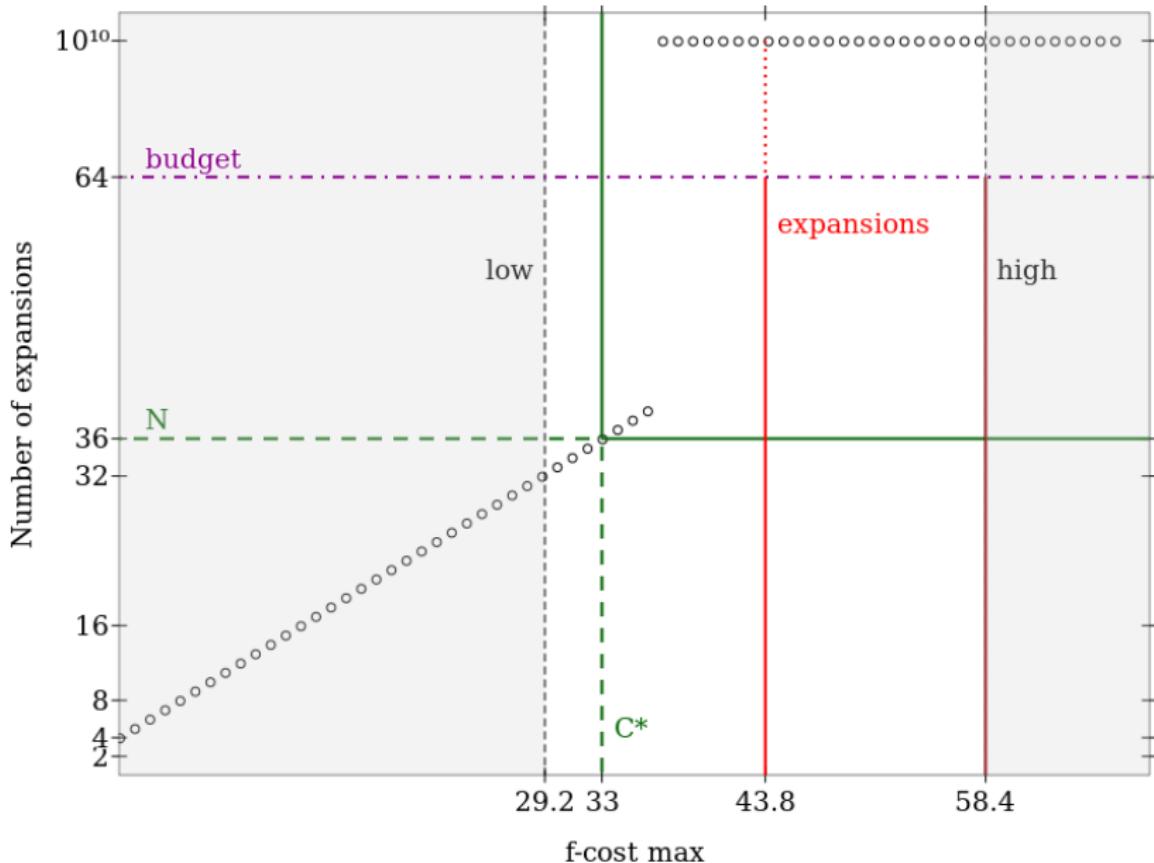
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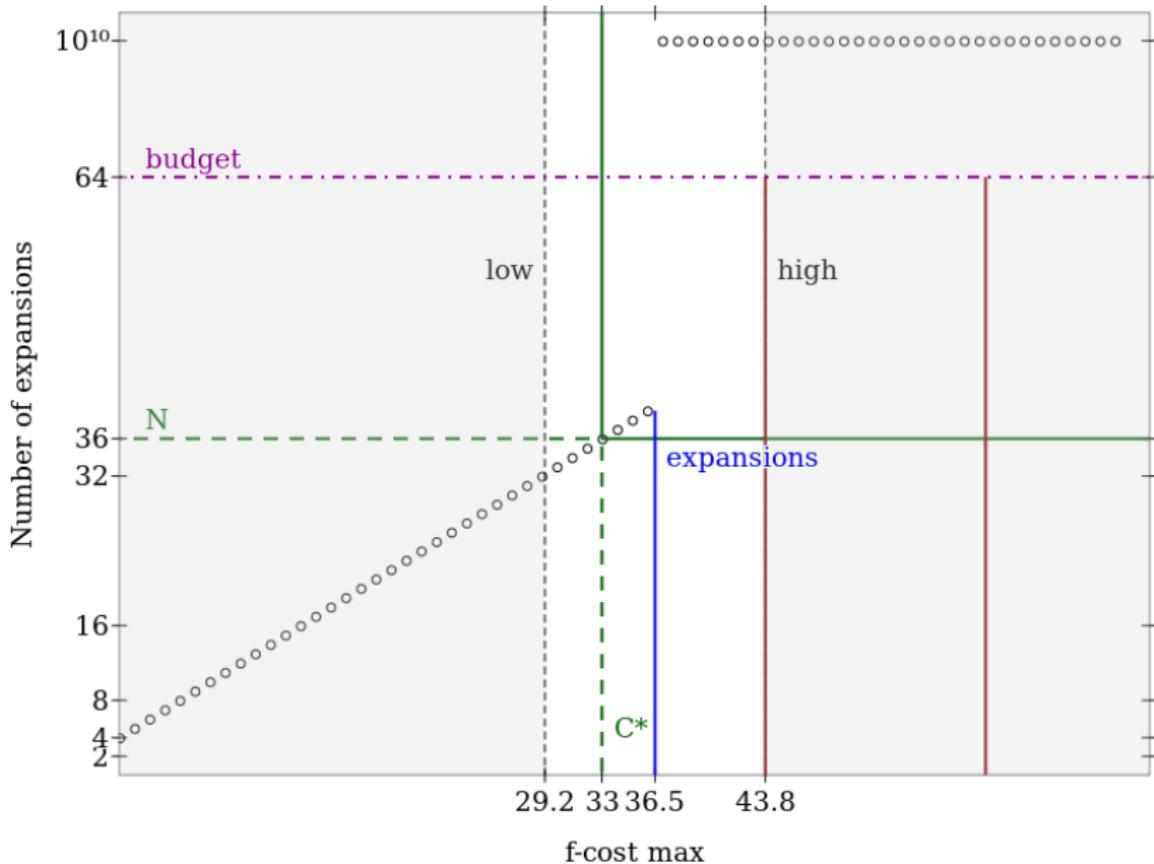
IBEX (main idea)



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IBEX (main idea)



IBEX (main idea)

N
↓

For budget = 2, 4, 8, 16, 32, 64 : $\leq 4N$

With **exponential search**:

Refine **lower** and **upper bound** on cost

Proves no solution when lower = upper

} $O(\log C^*)$

Application: Tree Search

IBEX + Depth-First Search = *Budgeted Tree Search (BTS)*

Alg.	Worst case
IDA* ₍₁₉₈₅₎	$\Theta(N^2)$
EDA* ₍₂₀₁₄₎	unbounded
BTS	$O(N \log C^*)$

C^* : cost of the optimal solution

N : number of nodes of cost at most C^*

All algorithms return an optimal solution (under usual assumptions).

Application: Graph Search

IBEX + Uniform-Cost Search = *Budgeted Graph Search (BGS)*

Alg.	Admissible Heuristic	
	Consistent	Inconsistent
A* ₍₁₉₆₈₎	$O(N)$	$\Omega(2^N)$
B ₍₁₉₇₇₎	$O(N)$	$\Theta(N^2)$
BGS	$O(N)^\dagger$	$O(N \log C^*)$

C^* : cost of the optimal solution

N : number of nodes of cost at most C^*

All algorithms return an optimal solution (under usual assumptions).

Enhancements: Tree search

- Recover IDA* when exponential unit-cost domains
 - 1) Infinite iteration at next f -cost
 - 2) If expansions grow exponentially, go to 1) else exponential search

Enhancements: Tree search

- Recover IDA* when exponential unit-cost domains
 - 1) Infinite iteration at next f -cost
 - 2) If expansions grow exponentially, go to 1) else exponential search
- Budget window [2, 8] to be more aggressive

Experiments

Algorithm	15-Puzzle (unit)		15-Puzzle (real)		Coconut	
	Solved	Exp. $\times 10^6$	Solved	Exp. $\times 10^6$	Solved	Exp. $\times 10^4$
BTS	100	242.5	100	673.1	100	84.7
EDA*	99	5 586.0	100	2 882.3	3	$\geq 554\ 249.0$
IDA*_CR	100	868.4	100	700.6	3	$\geq 516\ 937.7$
IDA*	100	242.5	57	62 044.3	100	5 484.2
<i>N</i>	100	100.8	100	258.1	100	2.7

BTS (*Budgeted Tree Search*) = IBEX + Depth-First Search

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BTS (*Budgeted Tree Search*) = IBEX + Depth-First Search

Conclusion

- IBEX: Budgeting $\rightarrow O(N \log C)$
- Tree search: drop-in replacement for IDA*
- DovIBEX: For applications where oracle returns only if a solution is found
 - Interleaves budget iterations

Do you have a problem where the current worst case is $O(N^2)$, due to being cautious?

Maybe (Dov)IBEX can help!

Come and see our poster!