### 11.1 An LP Rounding Algorithm for the Multiway Cut Problem

In the last lecture, we introduced an LP relaxation and the corresponding LP rounding algorithm for the Multiway Cut problem.

### 11.1.1 Recall: Definition and the Linear Program

Definition 1 Multiway Cut Problem: Given an undirected graph $G=(V, E)$, a cost function $c: E \rightarrow \mathbb{Q}^{+}$ on edges, and $k$ distinguished terminals, $s_{1}, s_{2}, \ldots, s_{k}$, where $s_{i} \in V$, for all $i=1,2, \ldots, k$, the goal is to find $a$ minimum-cost set of edges, $E^{\prime} \subseteq E$, whose removal disconnects all terminals from each other.

The linear program (LP) of the Multiway Cut problem we talked about in the last lecture is as follows:

$$
\begin{array}{rll}
\operatorname{minimize} & \sum_{e=(u, v) \in E} c_{e} \cdot\left\|x_{u}-x_{v}\right\|_{1} &  \tag{11.1}\\
\text { subject to } & x_{s_{i}}=e_{i} & i=1,2, \ldots, k, \\
& x_{u} \in \Delta_{k} & \forall u \in V .
\end{array}
$$

where $e_{i}=(0, \ldots, 0,1,0, \ldots, 0)$ is the vector with 1 in the $i$ th coordinate and zeros elsewhere, and $\Delta_{k}$ is the $k$-simplex, i.e., $\Delta_{k}=\left\{x \in \mathbb{R}^{k} \mid \sum_{i=1}^{k} x^{i}=1\right\}$.

### 11.1.2 Recall: The Randomized Rounding Algorithm

For any $r \geq 0$ and $1 \leq i \leq k$, let $B\left(s_{i}, r\right)$ be the set of vertices in a ball of radius $r$ in the $\ell_{1}$-metric around $s_{i}$, that is, $B\left(s_{i}, r\right)=\left\{u \in V \left\lvert\, \frac{1}{2}\left\|x_{s_{i}}-x_{u}\right\|_{1} \leq r\right.\right\}$. Note that $B\left(s_{i}, 1\right)=V$ for all $i$. Then, as we introduced in the last lecture, the following algorithm MWC2 is a randomized rounding algorithm for the Multiway Cut problem.

```
Algorithm MWC2: LP Rounding Algorithm for the Multiway Cut Problem
    1. Let \(x^{*}\) be an optimal fractional solution to (11.1)
    2. \(C_{i} \leftarrow \emptyset\) for all \(1 \leq i \leq k\)
    3. Pick \(r \in(0,1)\) uniformly at random
    4. Pick a random permutation \(\pi\) of \(\{1,2, \ldots, k\}\)
    5. for \(i \leftarrow 1\) to \(k-1\) do
    6. \(\quad C_{\pi(i)} \leftarrow B\left(s_{\pi(i)}, r\right)-\bigcup_{j<i} C_{\pi(j)}\)
    7. \(C_{\pi(k)} \leftarrow V-\bigcup_{j<k} C_{\pi(j)}\)
    8. return \(F=\bigcup_{i=1}^{k} \delta\left(C_{i}\right)\)
```


### 11.1.3 Analysis of the Randomized Rounding Algorithm

Lemma 1 For each $e=(u, v)$, the probability of $e$ belonging to the cut, i.e., $\operatorname{Pr}[e$ is in cut $] \leq \frac{3}{4}\left\|x_{u}-x_{v}\right\|_{1}$.
Lemma 1 implies the following theorem and we will prove the lemma later.
Theorem 1 Algorithm MWC2 is a randomized $\frac{3}{2}$-approximation algorithm for the multiway cut problem.
Proof. Let $W$ be a random variable denoting the value of the cut, and $Z_{e}$ be a $0-1$ variable which is 1 if $e$ is in the cut, so that $W=\sum_{e \in E} c_{e} Z_{e}$. Let OPT be the optimum solution of the LP. Then, we have

$$
\begin{aligned}
E[W]=E\left[\sum_{e \in E} c_{e} Z_{e}\right]=\sum_{e \in E} c_{e} E\left[Z_{e}\right] & =\sum_{e \in E} c_{e} \operatorname{Pr}[e \text { is in cut }] \\
& \leq \sum_{e=(u, v) \in E} c_{e} \frac{3}{4}\left\|x_{u}-x_{v}\right\|_{1} \quad \triangleleft \text { by Lemma } 1 \\
& =\frac{3}{2} \cdot \frac{1}{2} \sum_{e=(u, v) \in E} c_{e}\left\|x_{u}-x_{v}\right\|_{1} \\
& =\frac{3}{2} \cdot \mathrm{OPT} .
\end{aligned}
$$

Before proving Lemma 1, we first prove the following two lemmas.
Lemma 2 For any index $\ell$ and any two vertices $u, v \in V,\left|x_{u}^{\ell}-x_{v}^{\ell}\right| \leq \frac{1}{2}\left\|x_{u}-x_{v}\right\|_{1}$.
Proof. Without loss of generality, assume that $x_{u}^{\ell} \geq x_{v}^{\ell}$. Then

$$
\left|x_{u}^{\ell}-x_{v}^{\ell}\right|=x_{u}^{\ell}-x_{v}^{\ell}=\left(1-\sum_{j \neq \ell} x_{u}^{j}\right)-\left(1-\sum_{j \neq \ell} x_{v}^{j}\right)=\sum_{j \neq \ell}\left(x_{v}^{j}-x_{u}^{j}\right) \leq \sum_{j \neq \ell}\left|x_{u}^{j}-x_{v}^{j}\right|
$$

Add $\left|x_{u}^{\ell}-x_{v}^{\ell}\right|$ to both sides, we have

$$
2\left|x_{u}^{\ell}-x_{v}^{\ell}\right| \leq\left\|x_{u}-x_{v}\right\|_{1} \Rightarrow\left|x_{u}^{\ell}-x_{v}^{\ell}\right| \leq \frac{1}{2}\left\|x_{u}-x_{v}\right\|_{1} .
$$

Lemma $3 u \in B\left(s_{i}, r\right) \Leftrightarrow 1-x_{u}^{i} \leq r$.

Proof.

$$
\begin{aligned}
u \in B\left(s_{i}, r\right) & \Leftrightarrow \frac{1}{2}\left\|x_{s_{i}}-x_{u}\right\|_{1} \leq r \\
& \equiv \frac{1}{2} \sum_{j=1}^{k}\left|x_{s_{i}}^{j}-x_{u}^{j}\right| \leq r \\
& \equiv \frac{1}{2} \sum_{j=i} x_{u}^{j}+\frac{1}{2}\left(1-x_{u}^{i}\right) \leq r \\
& \equiv 1-x_{u}^{i} \leq r . \\
& \triangleleft \text { since } \sum_{j=i} x_{u}^{j}=1-x_{u}^{i}
\end{aligned}
$$

Now we can prove Lemma 1 based on the above two lemmas.
Proof. Consider an edge $e=(u, v)$, define the following two events:

- Event $S_{i}$ : we say that index $i$ settles $e$ if $i$ is the first index such that at least one of $u, v \in B\left(s_{\pi(i)}, r\right)$;
- Event $X_{i}$ : we say that index $i$ cuts $e$ if exactly one of $u, v \in B\left(s_{\pi(i)}, r\right)$.

Then, we have $\operatorname{Pr}[e$ is in cut $]=\sum_{i=1}^{k} \operatorname{Pr}\left[S_{i} \wedge X_{i}\right]$. By Lemma 3, we get

$$
\operatorname{Pr}\left[X_{i}\right]=\operatorname{Pr}\left[\min \left\{1-x_{u}^{i}, 1-x_{v}^{i}\right\} \leq r<\max \left\{1-x_{v}^{i}, 1-x_{u}^{i}\right\}\right]=\left|x_{u}^{i}-x_{v}^{i}\right|
$$

Let $\ell=\arg \min _{i}\left\{1-x_{u}^{i}, 1-x_{v}^{i}\right\}$, that is, $s_{\ell}$ is the nearest terminal to either $u$ or $v$. Then we can claim that index $i \neq \ell$ cannot settle $e=(u, v)$ if $\ell$ comes before $i$ in $\pi$, since by Lemma 3, if at least one of $u, v \in B\left(s_{\pi(i)}, r\right)$, then at least one of $u, v \in B\left(s_{\pi(\ell)}, r\right)$. Note that $\operatorname{Pr}[\ell$ comes after $i]=\frac{1}{2}$. Thus,

- for $\ell \neq i$, we have

$$
\begin{aligned}
\operatorname{Pr}\left[S_{i} \wedge X_{i}\right] & =\frac{1}{2} \operatorname{Pr}\left[S_{i} \wedge X_{i} \mid \ell \text { comes after } i\right]+\frac{1}{2} \operatorname{Pr}\left[S_{i} \wedge X_{i} \mid \ell \text { comes before } i\right] & \\
& \leq \frac{1}{2} \operatorname{Pr}\left[X_{i} \mid \ell \text { comes after } i\right]+0 & \\
& =\frac{1}{2} \operatorname{Pr}\left[X_{i}\right] & \triangleleft X_{i} \text { is independent of } \pi \\
& =\frac{1}{2}\left|x_{u}^{i}-x_{v}^{i}\right| . &
\end{aligned}
$$

- for $\ell=i$, we have

$$
\operatorname{Pr}\left[S_{\ell} \wedge X_{\ell}\right] \leq \operatorname{Pr}\left[X_{\ell}\right]=\left|x_{u}^{\ell}-x_{v}^{\ell}\right| .
$$

Therefore,

$$
\begin{aligned}
\operatorname{Pr}[e \text { is in cut }]=\sum_{i=1}^{k} \operatorname{Pr}\left[S_{i} \wedge X_{i}\right] & \leq\left|x_{u}^{\ell}-x_{v}^{\ell}\right|+\frac{1}{2} \sum_{i \neq \ell}\left|x_{u}^{i}-x_{v}^{i}\right| \\
& =\frac{1}{2}\left|x_{u}^{\ell}-x_{v}^{\ell}\right|+\frac{1}{2}\left\|x_{u}-x_{v}\right\|_{1} \\
& \leq \frac{1}{4}\left\|x_{u}-x_{v}\right\|_{1}+\frac{1}{2}\left\|x_{u}-x_{v}\right\|_{1} \quad \triangleleft \text { by Lemma } 2 \\
& =\frac{3}{4}\left\|x_{u}-x_{v}\right\|_{1} .
\end{aligned}
$$

### 11.1.4 Best Known Results

Theorem 2 There is a Multiway Cut randomized approximation algorithm with an approximation guarantee of 1.3438 . [K04]

Theorem 3 There exists a (1.32388- $\frac{1}{2 k}$ )-approximation algorithm for the Multiway Cut problem. [BNS13]
Theorem 4 There is an algorithm that provides a 1.2965-approximation for the Multiway Cut problem. [SV14]

### 11.2 The Multi-Cut Problem

Definition 2 Multi-Cut Problem: Given an undirected graph $G=(V, E)$, a cost function $c: E \rightarrow \mathbb{Q}^{+}$on edges, and $k$ distinguished source-sink pairs of vertices, $\left(s_{1}, t_{1}\right),\left(s_{2}, t_{2}\right), \ldots,\left(s_{k}, t_{k}\right)$, where $s_{i}, t_{i} \in V$, for all $i=1,2, \ldots, k$, the goal is to find a minimum-cost set of edges, $E^{\prime} \subseteq E$, whose removal disconnects all pairs of $s_{i}, t_{i}$, for every $i=1,2, \ldots, k$. Note that there can be paths connecting $s_{i}$ and $s_{j}$ or $s_{i}$ and $t_{j}$ for $i \neq j$.

Let $\mathcal{P}_{i}$ be the set of all paths from $s_{i}$ to $t_{i}$. Then an LP of this problem is as follows:

$$
\begin{align*}
\operatorname{minimize} & \sum_{e \in E} c_{e} x_{e}  \tag{11.2}\\
\text { subject to } & \sum_{e \in P} x_{e} \geq 1, \quad \forall P \in \mathcal{P}_{i}, 1 \leq i \leq k, \\
& x_{e} \geq 0, \quad \forall e \in E .
\end{align*}
$$

Although this LP has exponentially many constraints, we can solve it in polynomial time by considering a polynomial-time separation oracle, which is defined as follows:

Separation oracle: Given a solution of $x_{e}$ values, either say it is indeed a feasible solution to the LP or, if it is infeasible, find a violating constraint.

The separation oracle for this LP works as follows: Consider $x_{e}$ as the length of each edge in $G$, compute the length of the shortest $s_{i}-t_{i}$ path for each $i, 1 \leq i \leq k$. If for each $i$, the length of the shortest $s_{i}-t_{i}$ path is at least 1 , then the length of every path $P \in \mathcal{P}_{i}$ is at least 1 , indicating that the solution is feasible; if for some $i$, the length of the shortest $s_{i}-t_{i}$ path $P$ is less than 1 , we return it as a violated constraint, since we have $\sum_{e \in P} x_{e}<1$ for $P \in \mathcal{P}_{i}$.

### 11.2.1 The Region Growing Algorithm

Now we introduce an approximation algorithm based on a region growing method presented by Garg, Vazirani, and Yannakakis (GVY) for solving this problem. First, we restate this problem as a pipe system with some denotations as follows:

- $x_{e}$ : length of a pipe
- $c_{e}$ : cross-sectional area of a pipe
- $c_{e} x_{e}$ : volume of a pipe
- $d_{x}(u, v)$ : length of the shortest $u-v$ path with edge length $x_{e}$
- $B_{x}(v, r)=\left\{u \mid d_{x}(v, u) \leq r\right\}$ : ball of radius $r$ around vertex $v$

The LP objective is then the minimum-volume pipe system such that for every $s_{i}-t_{i}$ path, $s_{i}$ and $t_{i}$ are at least 1 unit apart, i.e., $d_{x}\left(s_{i}, t_{i}\right) \geq 1$. See Figure 11.1 for an illustration of a pipe system.

Let $V^{*}$ be the optimum total volume of the pipes to the LP, we define the volume of pipes within distance $r$ of $s_{i}$ plus an extra term $\frac{V^{*}}{k}$ as follows:

$$
V_{x}\left(s_{i}, r\right)=\frac{V^{*}}{k}+\sum_{e=(u, v), u, v \in B_{x}\left(s_{i}, r\right)} c_{e} x_{e}+\sum_{e=(u, v), u \in B_{x}\left(s_{i}, r\right), v \notin B_{x}\left(s_{i}, r\right)} c_{e}\left(r-d_{x}\left(s_{i}, u\right)\right)
$$



Figure 11.1: An illustration of a pipe system.

Let $\delta(S)$ be the set of edges between $S$ and $V \backslash S$ for all $S \subset V$. The following algorithm GVY is a region growing algorithm for the Multi-Cut problem.

```
Algorithm GVY: The Region Growing Algorithm for the Multi-Cut Problem
    1. \(C \leftarrow \emptyset\)
    2. Let \(x\) be an optimal fractional solution to (11.2)
    3. while there is a connected \(s_{i}, t_{i}\) do
    4. \(\quad S \leftarrow B_{x}\left(s_{i}, r\right)\) for some \(r<\frac{1}{2}\)
    5. \(C \leftarrow C \cup \delta(S)\)
    6. \(V \leftarrow V \backslash S\)
        \(\triangleleft \delta(S)\) Remove the ball from the \(G\)
    7. return \(C\)
```


### 11.2.2 Analysis of the GVY Region Growing Algorithm

Lemma 4 Algorithm GVY terminates in polynomial time.

Proof. In each iteration of the while loop, lines 4 and 5 indicate that $\delta(S)$ will separate at least one pair of $\left(s_{i}, t_{i}\right)$, thus there are at most $k$ iterations. Therefore, algorithm GVY terminates in polynomial time.

Lemma 5 Algorithm GVY returns a Multi-Cut.

Proof. If algorithm GVY does not return a Multi-Cut, then there must be some $s_{j}-t_{j}$ pair in a removed ball. Thus, we show that no $s_{j}-t_{j}$ pair remains connected within a ball that is removed by contradiction. If $\exists s_{j}, t_{j} \in B_{x}\left(s_{i}, r\right)$ for $r<\frac{1}{2}$, then $d_{x}\left(s_{j}, t_{j}\right) \leq 2 r<1$, which contradicts the constraints for $s_{j}, t_{j}$.

Let $V^{*}$ be the optimum total volume of the pipes to the LP, then as we introduced in the last lecture, define:

$$
\begin{aligned}
V_{x}\left(s_{i}, r\right) & =\frac{V^{*}}{k}+\sum_{e=(u, v), u, v \in B_{x}\left(s_{i}, r\right)} c_{e} x_{e}+\sum_{e=(u, v), u \in B_{x}\left(s_{i}, r\right), v \notin B_{x}\left(s_{i}, r\right)} c_{e}\left(r-d_{x}\left(s_{i}, u\right)\right), \\
C_{x}\left(s_{i}, r\right) & =\sum_{e=(u, v) \in \delta\left(B_{x}\left(s_{i}, r\right)\right)} c_{e}
\end{aligned}
$$

Observation: $V_{x}\left(s_{i}, r\right)$ is an increasing function of $r$. It is also piece-wise linear with possible discontinuity at values of $r$ when the ball includes a new vertex (see Figure 11.2 for an example of the discontinuity) and
differentiable between values $r$ in which vertices are added to the ball.



Figure 11.2: An example of when the function $V_{x}\left(s_{i}, r\right)$ of $r$ is discontinuous. The value of $V_{x}\left(s_{i}, r\right)$ can jump when a ball is growing with a radius from $r_{1}$ to $r_{2}$ and there is an edge between $u_{2}$ and $v_{2}$ which have the same distance $\left(r_{2}\right)$ to $s_{i}$, since we will also need to add the volume of pipe $\left(u_{2}, v_{2}\right)$ at the moment when $r$ reaches $r_{2}$.

So, we have

$$
\frac{\mathrm{d} V_{x}\left(s_{i}, r\right)}{\mathrm{d} r}=C_{x}\left(s_{i}, r\right)
$$

Lemma 6 There is some $r<\frac{1}{2}$ (and we can find it in polynomial time) such that $\frac{C_{x}\left(s_{i}, r\right)}{V_{x}\left(s_{i}, r\right)} \leq 2 \ln (k+1)$.
Lemma 6 implies the following theorem and we will prove the lemma later.
Theorem 5 Algorithm $G V Y$ is a $4 \ln (k+1)$-approximation algorithm for the Multi-Cut problem.
Proof. When we cut a ball $B_{x}\left(s_{i}, r\right)$, charging the cost of $\delta\left(B_{x}\left(s_{i}, r\right)\right)$ to the volume of $B_{x}\left(s_{i}, r\right)$, by Lemma 6 , we have

$$
\begin{aligned}
\sum_{e \in C} c_{e}=\sum_{i=1}^{k} \sum_{e \in C_{i}} c_{e} & \leq 2 \ln (k+1) \sum_{s_{i}, r \text { selected }} V_{x}\left(s_{i}, r\right) \\
& \leq 2 \ln (k+1)\left(V^{*}+k \cdot \frac{V^{*}}{k}\right) \\
& =4 \ln (k+1) V^{*}
\end{aligned}
$$

Now we prove Lemma 6.
Proof. Say we choose $r \in\left[0, \frac{1}{2}\right)$ uniformly at random. Recall the mean-value theorem: for a function $f(\cdot)$ continuous on an interval $[a, b]$ and differentiable on $(a, b), \exists c \in(a, b)$ such that $f^{\prime}(c)=\frac{f(b)-f(a)}{b-a}$ (see Figure 11.3 for the proof).

Let $f(r)=\ln V(r), f^{\prime}(r)=\frac{\mathrm{d} \ln V(r)}{\mathrm{d} r}=\frac{C(r)}{V(r)}$, where $V(r)=V_{x}\left(s_{i}, r\right), C(r)=C_{x}\left(s_{i}, r\right)$. Note that $V\left(\frac{1}{2}\right) \leq V^{*}+\frac{V^{*}}{k}$ and $V(0)=\frac{V^{*}}{k}$. Thus, $\exists r_{0}$ such that

$$
f^{\prime}\left(r_{0}\right) \leq \frac{\ln V\left(\frac{1}{2}\right)-\ln V(0)}{\frac{1}{2}-0} \leq 2\left(\ln \left(V^{*}+\frac{V^{*}}{k}\right)-\ln \frac{V^{*}}{k}\right)=2\left(\frac{\ln \left(V^{*}+\frac{V^{*}}{k}\right)}{\ln \frac{V^{*}}{k}}\right)=2 \ln (k+1)
$$



Figure 11.3: Mean-value theorem

Consider vertices based on their increasing distances from $s_{i}: s_{i}=v_{1}, v_{2}, \ldots, v_{p}, 0=r_{0} \leq r_{1} \leq \cdots \leq r_{p}=\frac{1}{2}$. By contradiction, suppose for all $r \in\left[r_{j}, r_{j+1}\right), \frac{C(r)}{V(r)}>2 \ln (k+1)$. Then, we have

$$
\begin{aligned}
& \int_{r_{j}}^{r_{j+1}^{-}} \frac{\mathrm{d} V(r)}{\mathrm{d} r} \cdot \frac{1}{V(r)} \mathrm{d} x>\int_{r_{j}}^{r_{j+1}^{-}} 2 \ln (k+1) \mathrm{d} r \\
\Rightarrow & \ln V\left(r_{j+1}^{-}\right)-\ln V\left(r_{j}\right)>2 \ln (k+1)\left(r_{j+1}^{-}-r_{j}\right) .
\end{aligned}
$$

For all $j=0,1, \ldots, p-1$, we have

$$
\begin{gathered}
\ln V\left(r_{1}\right)-\ln V\left(r_{0}\right)>2 \ln (k+1)\left(r_{1}-r_{0}\right) \\
\vdots \\
\ln V\left(r_{p}\right)-\ln V\left(r_{p-1}\right)>2 \ln (k+1)\left(r_{p}-r_{p-1}\right) .
\end{gathered}
$$

Sum over all $j$, we get

$$
\begin{aligned}
& \ln V\left(r_{p}\right)-\ln V\left(r_{0}\right)>2 \ln (k+1)\left(r_{p}-r_{0}\right) \\
& \Rightarrow \ln V\left(\frac{1}{2}\right)-\ln V(0)>2 \ln (k+1)\left(\frac{1}{2}-0\right) \\
& \Rightarrow \ln V\left(\frac{1}{2}\right)>\ln (k+1)+\ln \frac{V^{*}}{k} \\
&=\ln \frac{(k+1) V^{*}}{k} \\
&=\ln \left(V^{*}+\frac{V^{*}}{k}\right) \\
& \Rightarrow V\left(\frac{1}{2}\right)>V^{*}+\frac{V^{*}}{k}
\end{aligned}
$$

which cannot happen. Therefore, there must be an $r$ such that $\frac{C(r)}{V(r)} \leq 2 \ln (k+1)$.
To find such $r$, note that between $r_{j}$ and $r_{j+1}^{-}, C(r)$ is constant while $V(r)$ is non-decreasing. So, the minimum value of $\frac{C(r)}{V(r)}$ occurs when $r=r_{j+1}^{-}$. So, it is enough to check the ratio $\frac{C(r)}{V(r)}$ for $r=r_{j+1}-\epsilon$. So, we only need to check $p \leq n$ vertices and their distances from $s_{i}$. Thus, we can find such $r$ in polynomial time.

Therefore, algorithm GVY is an $O(\log k)$-approximation algorithm for the Multi-Cut problem.

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