

Preliminary Results on Exploration-Driven Satisfiability Solving Md Solimul Chowdhury, Martin Müller and Jia-Huai You Department of Computing Science, The University of Alberta, Edmonton, Alberta, Canada.

Introduction

General Issues with Heuristics Search

- In heuristics search, heuristics are often inaccurate.
 - \succ Can lead to <u>early mistakes</u> \rightarrow inefficient search.
- Exploration can *compensate* \rightarrow *more robust search*.
- Successful Application of Exploration: Game-playing and Deterministic planning.

Contributions:

LBD Score and Goal of Exploration

- Literal Block Distance (LBD) score of a learned clause c.
 - Number of *distinct decision* levels in c.
 - Lower LBD score means better quality clause.
- The goal of exploration in expSAT is to identify branching variables, which quickly lead to *high-quality* conflicts.
 - expVSIDS exploration scores are derived from sampling future search states, not from the tree.

Empirical Evaluation

Implementation:

- Two prototype solver implementations:
 - ➢ MiniSAT → expMiniSAT
 - ➢ Glucose → expGlucose

Setting Exploration Parameters:

	I	
	Parameters	Values
	nW	5,7,8,10,15
	lW	4,5
Parameter Values:	θ_{stop}	0.5, 0.6, 0.7, 0.8,0.9

- study exploration of SAT search space via random sampling → a novel CDCL SAT solver named *expSAT*.
- expSAT uses intermittent exploration of the search space to find valuable statistics to guide the search.
- *expSAT* uses a novel branching heuristic *expVSIDS*.
- expVSD/S combines standard VSIDS score and exploration score from expSAT statistics.
- Empirical evaluation shows *performance gain*.

Background

<u>A SAT formula</u>: Conjunction of *clauses*

The

a clause is disjunction of Boolean *literals*,
 a literal is either a *variable or its negation*.

- expVSIDS rewards a variable based on the quality of conflicts it generates during sampling.
- It favors variables assignment of which lead to generation of high-quality clauses with low LBD in sampling.

The expSAT Solver

Random Exploration and Statistics Collection

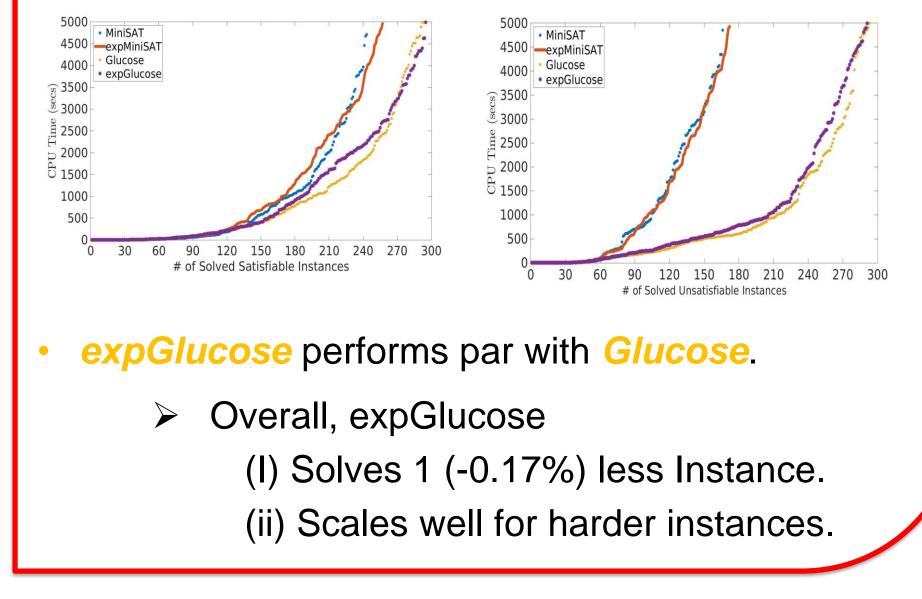
- In upper part of the search tree, before some branching decisions, with a probability p_{exp}, expSAT performs an exploration episode.
- Exploration consists of fixed (IW) number of random walks.
- Random Walk consists of *random steps*.
 - \succ Random step \rightarrow random selection of variable + UP
- A Walk *terminates*, if *mS* random steps are taken or a conflict occurs.
- Statistics for walks that terminate with a conflict :

p_{exp}	2, 3, 4, 5, 6
ω	0.81,0.90

- Parameters are obtained from experiments with *a small subset of satisfiable instances* from SATRACE -2015.
- Constitute a set of **500 parameter settings** for these parameter values.
- We have selected 20 parameter settings out of 500 parameter settings to run experiment.
- **755 application** instances from SAT Competition-2014, SATRACE-2015 and SAT Competition-2016.

Experimental Results:

 expMiniSAT solves 21 (+5.31%) more instances than MiniSAT.



Satisfiability

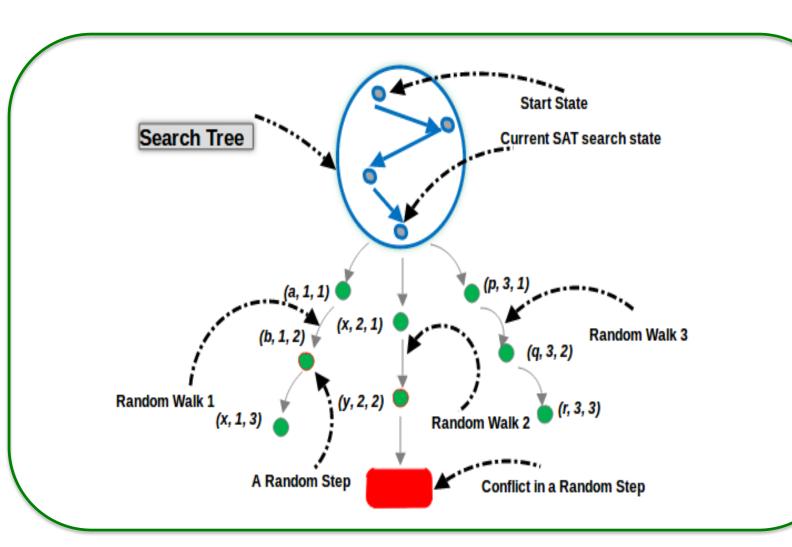
Satisfiability

(SAT)

Solving

- ProblemThe SAT problem: Given a formula of Boolean
variables, is there an assignments of those
variables, which satisfies that formula?
 - Modern SAT solvers employ *tree search* to solve a given formula.
 - ▶ Branch → Unit Propagation → Branch → …
 ▶ Branch → Unit Propagation → Conflict → Backtrack → Branch → Unit Propagation →…
 - Dominant SAT solvers are Conflict Driven Clause
 Learning (CDCL)
 - branching heuristics, conflict analysis, clause learning, back jumping.
 - Which variable to select from the set of unassigned variables?
- Branching
Heuristics• Dominant CDCL branching heuristics:
VSIDS (and recently LRB)
 - VSIDS:
 - Select variable, which participated in recent conflicts.
 - If unit propagation derives an empty clause,

LBD of the learned from that conflict



Computation of Exploration Score

- Exploration score expScore is computed for each variable that participated in the last exploration episode.
- expScore of v is the average of the walk scores ws(v) of the walks, where v appears as step variable.
- ws(v) is computed as follows:

ws(v) = 0, if the walk ended without a conflict.

Otherwise, $ws(v) = \omega^d / Ibd(c)$,

- > d >= 0 is the decision distance
- \succ **Example:** d=1 for the node (x,2,2)
- $\succ \omega < 1$ is the exponential decay factor.

Discussion and Future Work

Discussion:

- Performance is dependent on *parameter settings*.
- Faster conflict generation rate with expVSIDS
- *More* improvement on *satisfiable instances* than on unsatisfiable instances.

Future Work:

then a conflict occurs.



conflict analysis identifies the *root cause* of that conflict and *learns* a clause

a learned clause prunes the future search space.

expVSIDS:

expScore of v.

expVSIDS: new heuristics, combines VSIDS score and

expVSIDS scroe of v = g^z * expScore(v) + VSIDS(v).

For branching, selects v^{*} with *highest expVSIDS score*.

Make parameter settings adaptive during the

search.

 Uniform random selection → use other methods, such soft-max method for step variable selection.