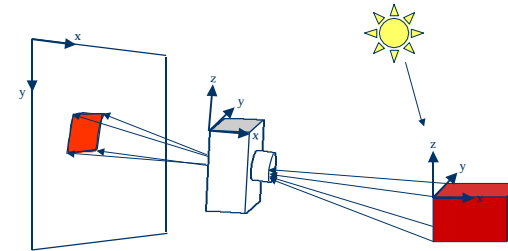


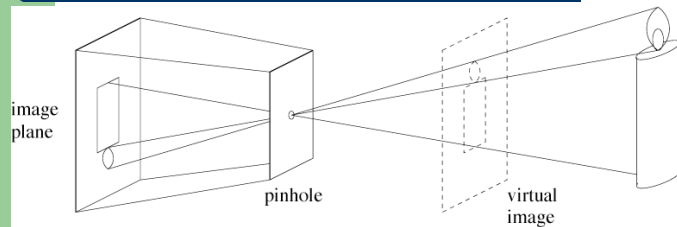
Image Point Operations

C306
Fall 2001
Martin Jagersand

Last time:
3D reality -> captured 2D image



Pinhole cameras



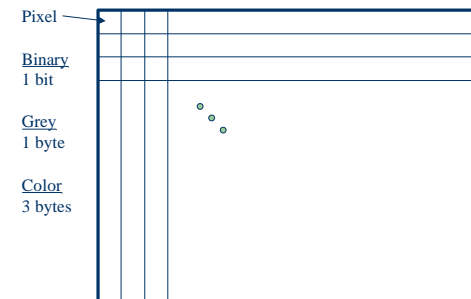
Examples of image sources:

- Analog cameras
- Digital cameras
- Optic Scanners (linear image sensors)
- Laser scanners (2 and 3D images)
- Radar
- X-ray
- NMRI

Image display

- VDU
 - Raster
 - Vector
- LCD
- Printer
- Photo process
- Plotter (x-y table type)

THE ORGANIZATION OF A 2D IMAGE



Mathematical / Computational image models

- Continuous mathematical:
 $I = f(x,y)$
- Discrete (in computer) adressable 2D array:
 $I = \text{matrix}(i,j)$
- Discrete (in file) e.g. ascii or binary sequence:

```
023 233 132 232
125 134 134 212
```

Image representation for display

- True color, RGB,

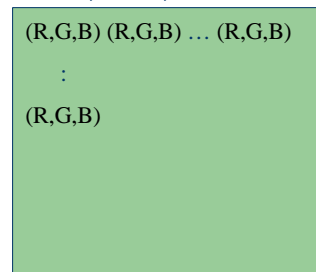
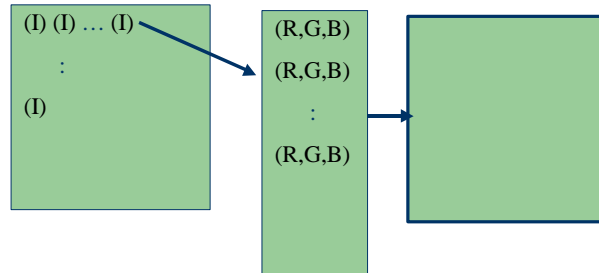


Image representation for display

- Indexed image



Point operations on images

- Point operations perform some operation on one pixel at a time (independent on the neighboring pixels)

For each (x,y)

$$I_2(x,y) = f(I(x,y))$$

- Contrast to image transforms (later in course) perform operations on the whole image

Common point operations

- Brightness adjustment
- Contrast adjustment
 - Dynamic range compression
 - Gray level slicing
- Histogram equalization
- Image (sequence) averaging
- Background subtraction

Linear brightness and contrast adjustment

- As seen on TV!

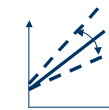
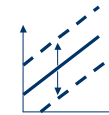
- Brightness

For each (x,y)

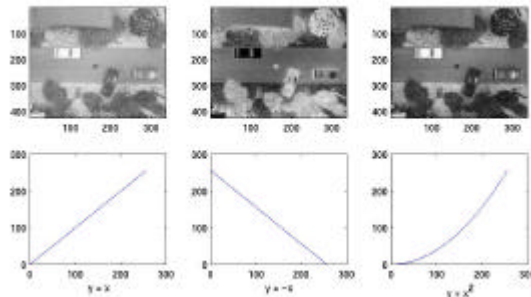
$$I_2(x,y) = I(x,y) + \text{const}$$

- Contrast

$$I_2(x,y) = \text{const} * I(x,y)$$



Contrast adjustment example



Special purpose contrast adjustments

- Dynamic range limitation

$$I_2(x,y) = \sqrt{I(x,y)}$$

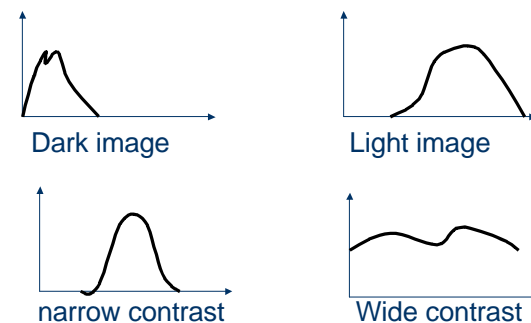
$$I_2(x,y) = \log(I(x,y))$$
- Inverted image

$$I_2(x,y) = 1 - I(x,y)$$
- Gray level slicing

Image histogram

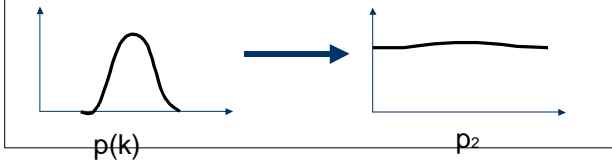
- For a discrete image quantized e.g. on $[0..255]$
 - Let n = total number of pixels
 - Let n_k = number of pixels with value k
 - Histogram: $p_k = n_k / n$
- Analogy: Consider the image a sample of a random variable. Then p_k is probability of a pixel having value k

Histogram examples



Histogram equalization

- Let $p(k)$ = image histogram on $k = [0..1]$
- Goal: find a contrast stretching transform $T(k)$ so that $I_2 = T(I)$ and $p_2 = 1$ (uniform)



Next time:

- Derive histogram equalization formula
- Finish up with point operations