

1. In the box at right,
for $H = [[0,1,2], [1,0,2], [1,0,2]]$
and $R = [[1,2,0], [0,1,2], [2,1,0]]$,
show the output printed by `m=propose_reject(H,R)`.

```
def propose_reject(H,R):
    n = pref_system_size(H,R)
    F,C = [None] * n, [0 for j in range(n)]
    rejection = True
    while rejection:
        rejection = False
        for j in range(n):
            h_choice = H[j][C[j]] # current H proposal
            if F[h_choice] == None: #R has no prop'ls
                F[h_choice] = j
                print(' ',j,' prop ',h_choice,': maybe')
            elif F[h_choice] != j: #R has 2 prop'ls
                r_maybe = F[h_choice] #R's current prop'l
                if prefers(R[h_choice], j, r_maybe):
                    r_reject, r_maybe = r_maybe, j
                    F[h_choice] = r_maybe
            else:
                r_reject = j
            print(' ',j,'prop',h_choice,
                  ':pref',r_maybe,',rej',r_reject)
            C[r_reject] += 1 # H[j_rej.]: next pref
            rejection = True # a prop'l was rejected
    P = [H[j][C[j]] for j in range(n)]
    print('\nj  P  C  F')
    [print(j, P[j], C[j], F[j]) for j in range(n)]
    return P
```

Show your rough work here.

2. Give a matching preference system with size 3 for which the propose-reject algorithm always finds a stable matching, or explain why this is not possible.

```
3. def myunion(x,y,P):
    rootx = findGP(x,P)
    rooty = findGP(y,P)
    P[rootx] = rooty
```

P represents 8 components of size 1:

```
j      0  1  2  3  4  5  6  7
P[j]  0  1  2  3  4  5  6  7
```

```
def findGP(x, P):
    px = P[x]
    if x==px: return x
    gx = P[px] #grandparent
    while px != gx:
        P[x] = gx
        x = px
        px = gx
    gx = P[gx]
    return px
```

Now show P after myunion(2,3,P):

```
P[j]  __ __ __ __ __ __ __ __
```

... and then after myunion(3,4,P):

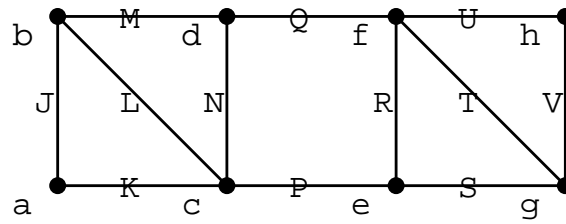
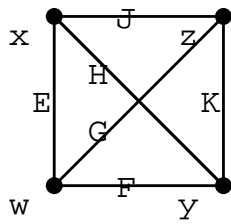
```
P[j]  __ __ __ __ __ __ __ __
```

... and then after myunion(4,5,P):

```
P[j]  __ __ __ __ __ __ __ __
```

... and then after myunion(5,6,P):

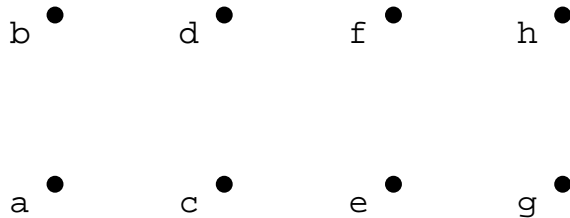
```
P[j]  __ __ __ __ __ __ __ __
```



Recall: a *cut* of a graph is a partition of the node set into two non-empty subsets. E.g. on the small graph (above left), $\{\{w,x\}, \{y,z\}\}$ is a cut with cross-edges $\{F,G,H,J\}$. RKMC is the randomized Kruskal min cut algorithm: unless otherwise stated, its input is a uniform-random permutation of the edges.

4. For the big graph, give each min cut (partition and cross-edges) ...

5. ...and give the forest (draw on the nodes below) and cut (partition and cross-edges) found by RKMC when edges are input in order LUQRKNTVSJMP.



6. Let G be a connected graph with a cut $\{X, Y\}$ with $G[X]$ (the subgraph of G on the node set X) connected but $G[Y]$ disconnected, with exactly two components $G[Y_1]$ and $G[Y_2]$. Prove or disprove: $\{X, Y\}$ is a min cut of G .

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for $H = [[1,2,0], [2,1,0], [2,1,0]]$
and $R = [[0,1,2], [1,2,0], [0,2,1]]$,
show the output printed by `m=propose_reject(H,R)`.

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    rejection = True
    while rejection:
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        for j in range(n):
            h_choice = H[j][C[j]] # current H proposal
            if F[h_choice] == None: #R has no prop'ls
                F[h_choice] = j
                print(' ',j,' prop ',h_choice,': maybe')
            elif F[h_choice] != j: #R has 2 prop'ls
                r_maybe = F[h_choice] #R's current prop'l
                if prefers(R[h_choice], j, r_maybe):
                    r_reject, r_maybe = r_maybe, j
                    F[h_choice] = r_maybe
                else:
                    r_reject = j
                print(' ',j,'prop',h_choice,
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                C[r_reject] += 1 # H[j_rej.]: next pref
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    P = [H[j][C[j]] for j in range(n)]
    print('\nj  P  C  F')
    [print(j, P[j], C[j], F[j]) for j in range(n)]
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Show your rough work here.

2. Give a matching preference system with size 3 for which the propose-reject algorithm always finds a stable matching, or explain why this is not possible.

3. `def myunion(x,y,P):`

`rootx = findGP(x,P)`

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`P[rootx] = rooty`

Here P represents 8 components of size 1:

j 0 1 2 3 4 5 6 7

P[j] 0 1 2 3 4 5 6 7

`def findGP(x, P):`

`px = P[x]`

`if x==px: return x`

`gx = P[px] #grandparent`

`while px != gx:`

`P[x] = gx`

`x = px`

`px = gx`

`gx = P[gx]`

`return px`

Show P after `myunion(3,4,P):`

P[j] -- -- -- -- -- -- --

... and then after `myunion(4,5,P):`

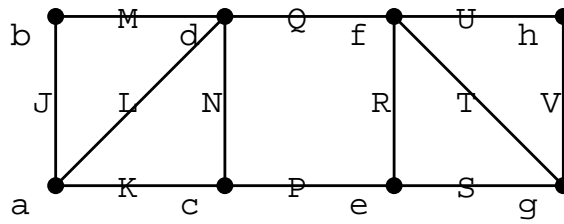
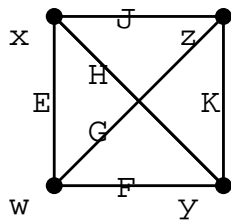
P[j] -- -- -- -- -- -- --

... and then after `myunion(5,6,P):`

P[j] -- -- -- -- -- -- --

... and then after `myunion(6,7,P):`

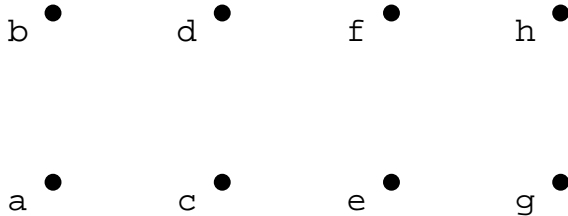
P[j] -- -- -- -- -- -- --



Recall: a *cut* of a graph is a partition of the node set into two non-empty subsets. E.g. on the small graph (above left), $\{\{w,x\}, \{y,z\}\}$ is a cut with cross-edges $\{F,G,H,J\}$. RKMC is the randomized Kruskal min cut algorithm: unless otherwise stated, its input is a uniform-random permutation of the edges.

4. For the big graph, give each min cut (partition and cross-edges) ...

5. ...and give the forest (draw on the nodes below) and cut (partition and cross-edges) found by RKMC when edges are input in order QPRKNTMLJUVS.



6. Let G be a connected graph with a cut $\{X,Y\}$ with $G[X]$ (the subgraph of G on the node set X) connected but $G[Y]$ disconnected, with exactly two components $G[Y_1]$ and $G[Y_2]$. Prove or disprove: $\{X,Y\}$ is a min cut of G .

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    print('\nj  P  C  F')
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`while px != gx:`

`P[x] = gx`

`x = px`

`px = gx`

`gx = P[gx]`

`return px`

Show P after `myunion(1,2,P):`

P[j] -- -- -- -- -- -- --

... and then after `myunion(2,3,P):`

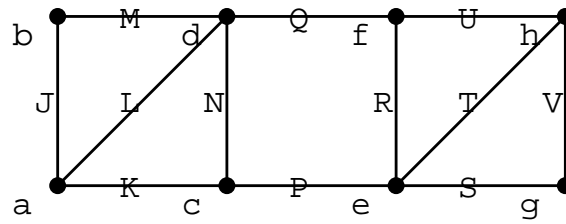
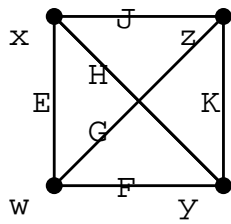
P[j] -- -- -- -- -- -- --

... and then after `myunion(3,4,P):`

P[j] -- -- -- -- -- -- --

... and then after `myunion(4,5,P):`

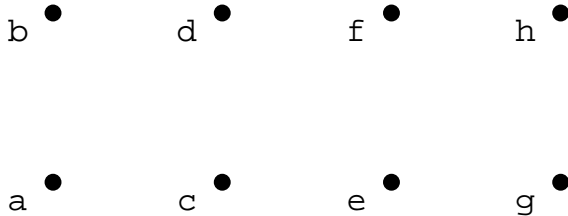
P[j] -- -- -- -- -- -- --



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