



Hong Zhang, PhD

Professor, FIEEE, FCAE

Research Interests

Robotics, Computer Vision, Image Processing

Education

- 1986–87 **PDF**, *University of Pennsylvania*, Philadelphia, Pennsylvania, USA.
GRASP Laboratory, Department of Computer and Information Science
- 1982–86 **PhD.**, *Purdue University*, West Lafayette, Indiana, USA.
PhD in Electrical Engineering
Supervisor: Richard (Lou) Paul
- 1980–82 **BSc.**, *Northeastern University*, Boston, Massachusetts, USA.
Bachelor of Science in Electrical Engineering (with the Highest Class GPA)
- 1978–80 Beijing Polytechnic University, Beijing, China
Bachelor of Science in Automatic Control

Employment

- 2000–present Professor, Department of Computing Science, University of Alberta, Canada
- 2002–03 Senior Fellow, Nanyang Technological University, Singapore
- 1994–00 Associate Professor, Department of Computing Science, University of Alberta, Canada
- 1994–95 STA Fellow, Mechanical Engineering Laboratory, MITI, Japan
- 1988–94 Assistant Professor, Department of Computing Science, University of Alberta, Canada

Adjunct Appointments

- 2015–present 100-Scholar Chair Professor, Guangdong University of Technology, China
- 2008–11 100-Scholar Chair Professor, South China University of Technology, China
- 2006–11 985 Professor, Northeast University, China
- 2002–03 Peking University, China
- 2001–04 Beijing Institute of Technology, China

Research Chair

- 2003–17 Senior NSERC Industrial Research Chair in Intelligent Sensing Systems

Centre Director

- 2000–17 Director, the Centre for Intelligent Mining Systems, University of Alberta

Awards and Distinctions

- 2018 **Distinguished Visiting Scholar**, *Centre for Autonomous Systems*, University of Technology Sydney, Sydney, Australia.
- 2015 **Best Conference Paper**, *The 7th IEEE International Conference on Robotics, Automation and Mechatronics (RAM)*, Angkor Wat, Cambodia.
- 2015 **Fellow**, *Canadian Academy of Engineering*, CAE.
- 2014 **Fellow**, *Institute of Electrical and Electronic Engineering*, IEEE.
- 2009 **Best Student Paper**, *2008 IEEE International Conference on Robotics and Biomimetics*, Bangkok, Thailand.
- 2008 **Alberta Science/Technology Award**, *Syncrude/ASTech Innovation in Oil Sands Research*, ASTech Foundation, Alberta.
- 2008 **Member of the Year**, *Association of Chinese Canadian Professors*, ACCP.
- 2007 **Best Paper in Robotics**, *2007 IEEE International Conference on Mechatronics and Automation (ICMA)*, Harbin, China.
- 2006 **Award for Research Excellence and Service to the Research Community**, *Canadian Information Processing and Pattern Recognition Society*, CIPPRS.
- 2004 **Best Student Paper**, *2004 IEEE International Conference on Robotics and Biomimetics (ROBIO)*, Shenyang, China.
- 2004 **Member of the Year**, *Association of Chinese Canadian Professors*, ACCP.
- 2003 **Best Student Paper**, *16th International Conference on Vision Interface*, Nova Scotia, Canada.
- 2002 **Award for Excellent Teaching**, *Faculty of Science*, University of Alberta.
- 2002 **Member of the Year**, *Association of Chinese Canadian Professors*, ACCP.
- 2000 **IEEE Millennium Medal**, IEEE.

Plenaries, Keynote Speeches and Invited Talks

- 2016 **Keynote**, *World Robot Conference*, Beijing, China, October 23, 2016.
- 2015 **Keynote**, *2015 IEEE International Conference on Robotics and Biomimetics*, Zhuhai, China, December 8, 2015.
 - Keynote**, *World Robot Conference*, Beijing, China, November 23, 2015.
 - Keynote**, *2015 Int'l Conference on Real-Time Computing and Robotics*, Changsha, China, June 26, 2015.
- 2014 **Semi-Plenary**, *The 13th International Conference on Control, Automation, Robotics and Vision (ICARCV)*, Singapore, December 11, 2014.
 - Plenary**, *The 4th Annual IEEE International Conference on Cyber Technologies in Automation, Robotics and Intelligent Systems (CYBER)*, Hong Kong, June 7, 2014.
- 2013 **Invited Talk**, *IFAC ICONS Workshop*, Chengdu, China, September 2, 2013.
- 2011 **Plenary**, *CVR 2011 International Vision Conference*, York University, Canada. June 15-18, 2011
- 2010 **Panelist**, *2010 IEEE International Conference on Robotics and Biomimetics*, Tianjin, China, December 2010.
 - Invited Talk**, *Institute of Robotics and Intelligent Information Processing*, Shanghai Jiaotong University, Shanghai, China, December, 2010.
 - Invited Talk**, *2nd Int'l Workshop on Recent Trends in Computer Vision*, Tokyo, Japan, September 2010.
 - Invited Talk**, *Computer Vision Workshop*, Beijing University, Beijing, China, July 2009.
- 2009 **Plenary**, *7th International Conference on Advances in Pattern Recognition*, Calcutta, India, February 6th, 2009.

- 2007 **Plenary**, *Chinese Process Control Conference*, Anshan, China, August 2007.
Public Talk, *iCORE Lecture*, Calgary, Canada, February 23, 2005.
- 2004 **Plenary**, *2004 International Conference on Intelligent Mechatronics and Automation*, Chengdu, China, August 31, 2004.
Plenary, *First Canadian Conference and Computer and Robot Vision*, London, Canada, June 2004.
Keynote, *Canadian Conference on Artificial Intelligence, Workshop on Agents Meet Robots*, London, Canada, June 2004.
Plenary, *First International Conference on Information Acquisition*, Hefei, China, June 2004.
- 2003 **Plenary**, *International Conference on Control Science and Engineering*, Harbin, China, December 2003.
- 2001 **Invited Talk**, *AI Seminar*, Department of Computing Science, University of Alberta, October 19, 2001.
Keynote, *2001 International Workshop on Bio-Robotics and Tele-operation*, Beijing, China, May 30, 2001.
- 1998 **Invited Talk**, *Robotics Department, MEL-MITI*, Japan, June 10, 1998.
- 1995 **Distinguished Lecture**, *Department of Computing Science*, University of Alberta, November 21, 1995.
Invited Talk, *IEEE Robotics and Automation Society, Tokyo Chapter*, Tokyo, Japan, January 12, 1995.
- 1994 **Invited Talk**, *Electrotechnical Laboratory (ETL)*, Tsukuba, Japan, December 14, 1994.

Research Grants – Individual

2017-18	<i>Motion Capture System and Mobile Robot Vehicle for Indoor Autonomous Navigation Research</i> , NSERC Research Tools and Infrastructure (RTI)	\$36,604
2016-19	<i>Oilsand Slurry Image and Video Analysis</i> , Syncrude Canada Ltd. Collaborative Research and Development	\$150,000
2016-19	<i>Oilsand Slurry Image and Video Analysis</i> , NSERC Collaborative Research and Development (CRD)	\$290,970
2016-21	<i>Developing Robot Autonomy via Invariant Representations</i> NSERC Discovery Grant	\$230,000
2011-16	<i>Scalable Appearance-Based Robot Navigation</i> , NSERC Discovery Grant Program	\$120,000
2010-15	<i>Intelligent Sensing Systems</i> , NSERC Industrial Research Chair Program	\$735,035
2010-15	<i>Intelligent Sensing Systems</i> , Syncrude Canada Ltd., Industrial Research Chair	\$750,000
2009-14	<i>Intelligent Sensing Systems</i> , Alberta Innovates Technology Future Industrial Chair Establishment Program	\$750,000
2006-11	<i>Collective Robotics</i> , NSERC Discovery Grant Program	\$195,000
2003-08	<i>Intelligent Sensing Systems</i> , NSERC Industrial Research Chair Program	\$806,045
2003-08	<i>Intelligent Sensing Systems</i> , Syncrude Canada Ltd., Industrial Research Chair	\$500,000
2003-08	<i>Intelligent Sensing Systems</i> , Matrikon, Industrial Research Chair	\$250,000
2003-08	<i>Intelligent Sensing Systems</i> , iCORE Industrial Chair Establishment Program	\$750,000
2003-04	<i>Experimental Testbed for Multi-Robot System Research</i> , NSERC Research Tools and Instruments (RTI)	\$44,602
2001-06	<i>Cooperative Multi-Robot Systems</i> , NSERC Research Grant	\$189,900
2000-02	<i>Sensing Large Lumps in the Hydrotransport System</i> , NSERC Collaborative Research and Development Grant	\$53,800
2000-01	<i>Mobile Robot for Experimental Research</i> , NSERC Equipment Grant	\$28,785

1999-01	<i>Oil Sand Lump Size Estimation (LSE) by 3-D Sensing</i> , Syncrude Canada Ltd. Research Grant	\$27,000
1999-01	<i>Oil Sand Lump Size Estimation (LSE) by 3-D Sensing</i> , COURSE University Research Program (Alberta), Research Grants	\$120,000
1999-00	<i>Wireless Ethernet Link for Robotics Research</i> , NSERC Equipment Grant	\$11,659
1999-00	<i>Hybrid Tactile Sensing</i> , Foundation for Promotion of Advanced Automation Technology (FANUC), Japan	\$8,741
1998-99	<i>Intelligent Sensing and Pattern Recognition for Measuring Gas Liquid Ratio in Two Phase Flow</i> , Precarn/Alberta Research Council	\$25,387
1997-01	<i>Robot Dextrous Manipulation: Planning, Sensing, and Control</i> NSERC Research Grant	\$97,020
1995-96	<i>Dextrous Robot Hand and Its Controller</i> , NSERC Equipment Grant	\$44,260
1993-97	<i>Tactile Sensing in Robot Manipulation and Robot Sensor Planning</i> NSERC Operating Grant	\$72,000
1993-94	<i>Collective Robotics</i> , Central Research Fund, University of Alberta	\$4,500
1993-94	<i>Neural Network Based Control of Active Suspension</i> , Dendronic Decisions Limited	\$28,750
1993-94	<i>Torque Control of Robot Joints</i> , Kajima Foundation, Japan	\$7,800
1992-95	<i>Travel Grants</i> , Central Research Fund, University of Alberta	\$5,000
1992-93	<i>Sensorized Gripper for Robotic Object Manipulation</i> , NSERC Equipment Grant	\$19,922
1991-93	<i>Tactile-guided robot fine manipulation</i> , Foundation for Promotion of Advanced Automation Technology (FANUC), Japan	\$21,252
1991-92	<i>An Experimental Teaching Methodology for an Undergraduate Robotics Course</i> , University of Alberta Teaching Research Fund	\$7,400
1991-92	<i>Control of Robot Joints</i> , Central Research Fund, University of Alberta	\$1,800
1990-93	<i>Force Control of Robot Manipulators</i> , NSERC Operating Grant	\$48,000
1989-90	<i>Robust Compliant Motion of Robot Manipulators</i> , Central Research Fund University of Alberta	\$2,179
1988-89	<i>A Sun/Unix Based Robot Control System</i> , Central Research Fund University of Alberta	\$9,000

Research Grants – Group

2012-17	<i>NSERC Canadian Field Robotics Network Strategic Grant</i> , NSERC Gregory Dudek (PI) and 9 other co-PI's	\$5,000,000
2008-10	<i>Collaborative Research with Beijing Genomics Institute - Shenzhen, China</i> Institute Grant, University of Alberta Gane Ka-Shu Wong (PI) and 4 co-PI's	\$129,446
1998-99	<i>Laboratory for Advanced Visualization and Multimedia Research</i> NSERC Major Installation Grant Mark Green (PI) and 8 co-PI's	\$430,000
1998-99	<i>Imaging Systems Equipment for Collaborative Multimedia Projects</i> University of Alberta AECD Internal Allocation Committee Anup Basu (PI)	\$140,000
1997-98	<i>Panoramic Viewing for Telepresence</i> , NSERC Collaborative Research and Development (CRD), Anup Basu (PI) and 1 co-PI	\$50,000
1994-97	<i>Experimental Computing Research Group</i> , NSERC Infrastructure Xiaobo Li (PI) and 8 co-PI's	\$120,000
1993-94	<i>Robots in Hazardous Environments under Poor Visibility</i> , NSERC CRD Anup Basu (PI)	\$87,000
1991-94	<i>Artificial Intelligence - Robotics - Vision Group</i> , NSERC Infrastructure	\$135,000

	Randy Goebel (PI) and 8 co-PI's	
1990-91	<i>Multiprocessor CPU and File/Backup Server Replacement</i> , NSERC Major Equipment, Tony Marsland (PI) and 26 co-PI's	\$194,300
1990-91	<i>Artificial Intelligence - Robotics - Vision Group</i> , NSERC Infrastructure, Renee Elio (PI)	\$45,000
1990-91	<i>Artificial Intelligence Research Laboratory/Robotics Research Laboratory</i> , NSERC Equipment, Randy Goebel (PI) and 5 co-PI's	\$36,984
1990-91	<i>Network File Server</i> , NSERC Equipment, Tony Marsland (PI) and 1 co-PI	\$21,279

Service – Conference Organization

- 2019 **Senior Program Committee (SPC) Member**, 2019 *IEEE International Conference on Robotics and Automation (ICRA)*.
Travel Award Chair, 2019 *IEEE International Conference on Robotics and Automation (ICRA)*.
- 2018 **General Chair**, 2018 *IEEE International Conference on Robotics and Biomimetics (ROBIO)*.
- 2017 **General Chair**, 2017 *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*.
- 2016 **Senior Program Committee (SPC) Member**, 2016 *IEEE/RSJ International Conference on Intelligent Robots Systems (IROS)*.
- 2015 **Program Chair**, 2015 *IEEE International Conference on Cyber Technologies in Automation, Robotics and Intelligent Systems*.
Awards Co-Chair, 2015 *IEEE/RSJ International Conference on Robots and Intelligent Systems (IROS)*.
Awards Chair, 2015 *IEEE International Conference on Mechatronics and Automation (ICMA)*.
- 2014 **Awards Co-Chair**, 2014 *IEEE International Conference on Robotics and Automation (ICRA)*.
- 2013 **Senior Program Committee (SPC) Member**, 2013 *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*.
- 2012 **General Chair**, 2012 *IEEE International Conference on Robotics and Biomimetics (ROBIO)*.
- 2011 **Video Chair**, 2011 *IEEE International Conference on Robotics and Automation (ICRA)*.
Area Chair, 2011 *IEEE International Conference on Computer Vision and Pattern Recognition (CVPR)*.
Awards Committee Chair, 2011 *IEEE International Conference on Control and Logistics (ICAL)*.
Program Co-Chair, 2011 *IEEE International Conference on Systems, Man, and Cybernetics*.
- 2010 **General Chair**, 2010 *IEEE International Conference on Mechatronics and Automation (ICMA)*.
Video Co-Chair, 2010 *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*.
Area Chair, 2010 *Asian Conference on Computer Visios (ACCV)*.
- 2009 **General Chair**, 2009 *IEEE International Conference on Information and Automation (ICIA)*.
Award Committee Chair, 2009 *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*.
Area Chair, 2009 *Asian Conference on Computer Visios (ACCV)*.
- 2008 **Award Committee Chair**, 2008 *IEEE International Conference on Automation and Logistics (ICAL)*.
Award Committee Chair, 2008 *IEEE International Conference on Information Acquisition*.
Program Co-Chair, 2008 *World Congress on Intelligent Control and Automation*.

- 2007 **Program Co-Chair**, 2007 *IEEE International Conference on Automation and Logistics*.
- 2006 **General Chair**, 2006 *IEEE International Conference on Robotics and Biomimetics*.
Workshop/Tutorial Chair, 2006 *IEEE/RSJ International Conference on Intelligent Robots and Systems*.
- 2005 **Program Chair**, 2005 *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*.
General Co-Chair, 2005 *IEEE International Conference on Robotics and Biomimetics*.
- 2004 **Program Co-Chair**, 2004 *IEEE International Conference on Information Acquisition*.
Invited Sessions Chair, 2004 *IEEE International Conference on Robotics and Biomimetics*.
- 2003 **Tutorial and Workshop Co-Chair**, 2003 *CIRA*.
Publication Chair, *RISSP 2003*.
- 2002 **Program Co-Chair**, *Vision Interface 2002*.
- 2001 **Program Chair**, 2001 *IEEE International Symposium on Computational Intelligence in Robotics and Automation*.
- 1999 **Local Arrangement Chair**, 1999 *IEEE Canadian Conference on Electrical and Computer Engineering*.

Service – Program Committee Members

- 2017–18 Robotics: Science and Systems (RSS)
 2017 Annual Conference on Robot Learning (CoRL)
- 2006–11 IEEE International Conference on Robotics and Automation (ICRA)
- 2000–01 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
- 2004–11 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
- 2005–11 IEEE International Conference on Robotics and Biomimetics (ROBIO)
- 2006, 2008 International Conference on Control, Automation, Robotics and Vision (ICARCV)
- 2006, 2008 World Congress on Intelligent Control and Automation (WCICA)
- 2005–07 IEEE International Conference on Systems, Man and Cybernetics (SMC)
 2005 IEEE/ASME Advanced Intelligent Mechatronics (AIM)
- 2005–07 IEEE International Conference on Mechatronics and Automation (ICMA)
 2004 IEEE International Conference on Intelligent Mechatronics and Automation
- 2004–06 International Conference on Information and Automation (ICIA)
 2004 IEEE International Conference on Robotics, Automation and Mechatronics (RAM)
- 2004-2017 Canadian Conference on Computer and Robot Vision (CRV)
- 2004–05 Canadian Conference on Artificial Intelligence (AI)
- 2001–03 Vision Interface (VI)
 2003 CIAC (Chinese Intelligent Automation Conference (CCC))
 2002 IASTED International Conference on Robotics and Applications
 2001 First International Workshop on Bio-Robotics and Teleoperation
- 2004, 2005 Canadian Conference on Artificial Intelligence
- 2000 Canadian Conference on Electrical and Computer Engineering (CCECE)
- 1999 International Conference on Advanced Robotics (ICAR)
- 1999 IEEE International Conference on Systems, Man, and Cybernetics (SMC)
- 1998 IARP Workshop on Humanoid and Human Friendly Robotics

Service – Journal Editorial Boards

- 2013–present **Associate Editor**, *IEEE Transaction on Cybernetics*, IEEE.
- 2003–13 **Associate Editor**, *IEEE Transaction on Systems, Man, and Cybernetics*, IEEE.

- 2011–present **Member of Editorial Board**, *Robotics*, MDPI.
- 2013–present **Member of Editorial Board**, *RoboMech*, Springer Open.
- 2013–present **Member of Editorial Board**, *Robotics and Biomimetics*, Springer Open.
- 2003–12 **Member of the Editorial Board**, *International Journal of Humanoid Robotics*, World Scientific.
- 2011–present **Member of the Editorial Board**, *International Journal of Mechatronics and Automation*, Inderscience Publishers.
- 2006 **Guest Editor**, *Advanced Robotics, Volume 20, Number 11*, Taylor & Francis Online.
- 2004 **Guest Editor**, *Journal of Advanced Computational Intelligence and Intelligent Informatics, Volume 20, Number 3*, Fuji Technology Press.
- 2003 **Guest Editor**, *IEEE Transactions on Systems, Man, and Cybernetics:Part A*, “*Collective Intelligence*”, IEEE.
- 2002 **Guest Editor**, *Journal of Image and Vision Computing*, Vision Interface 2002, Elsevier.

Service – Others

- 2018–2020 **Secretary**, *Administrative Committee*, IEEE Robotics and Automation Society.
- 2017–Present **Graduate Admissions Chair**, *Department of Computing Science*, University of Alberta.
- 2017–18 **Member**, *Canada Research Chair Advisory Committee*, Faculty of Science, University of Alberta.
- 2016–19 **Member**, *Computer Science Evaluation Group, Discovery Grants Program, NSERC*.
- 2015–Present **Member**, *IEEE Medal for Environmental and Safety Technologies Committee*.
- 2014–16 **Member**, *Administrative Committee, IEEE Robotics and Automation Society*.
- 2013–14 **Graduate Admissions Chair**, *Department of Computing Science*, University of Alberta.
- 2012–present **Founding Council Chair**, *IEEE International Conference on Mechatronics and Automation*.
- 2012 **Member**, *Conference Management Committee, IEEE Society on Systems, Man, and Cybernetics*.
- 2005–15 **Chair**, *Robotics and Intelligent Sensing Technical Committee, IEEE Society on Systems, Man, and Cybernetics*.

Teaching

Undergraduate

ENCMP 100	Computer Programming for Engineers	1988-89
CMPUT 215	Programming with Data Structures	1989
CMPUT 229	Computer Organization and Architecture I	13 semesters, 1988-2005
CMPUT 329	Computer Organization and Architecture II	15 semesters, 1989-2013
CMPUT 412	Experimental Mobile Robotics	9 semesters, 1993-2017
CMPUT 498	Topics in Computing Science - Individual Studies	

Graduate

CMPUT 605	Topics in Computing Science - Individual Studies	
CMPUT 512	Introduction to Robotics	6 semesters, 1988 - 2002
CMPUT 631	Robotics and Multi-Robot Systems	2004
CMPUT 631	Introduction to Robotics: Sensing and Navigation	2006
CMPUT 631	Visual Robot Navigation	4 semesters, 2008-14
CMPUT 631	Autonomous Robot Navigation	2017

Publications – in Archival Journals

- 2018 Li He and Hong Zhang, “Kernel K-means Sampling for Nystrom Approximation”, to appear in IEEE Transactions on Image Processing.
- 2018 Li He, Nilanjan Ray, and Hong Zhang, “Fast Large-Scale Spectral Clustering via Explicit Feature Mapping”, to appear in IEEE Transactions on Cybernetics.
- 2018 Haifei Zhu, Shichao Gu, Li He *, Yisheng Guan, and Hong Zhang, “Transition Analysis and Its Application to Global Path Determination for a Biped Climbing Robot”, to appear in Applied Sciences.
- 2018 Weinan Chen, Shichao Gu, Yisheng Guan*, Hong Zhang, Haifei Zhu, and Lei Zhu, “Representation of Truss-style Structures for Autonomous Climbing of Biped Pole-climbing Robots”, to appear in Robotics and Autonomous Systems.
- 2018 Homa Foroughi, Nilanjan Ray, and Hong Zhang, “Object Classification with Joint Projection and Low-rank Dictionary Learning”, IEEE Transactions on Image Processing, Volume 27, Issue 2, February 2018, pp. 806–821.
- 2017 Yi Hou, Hong Zhang, and Shilin Zhou, “BoCNF: Efficient Image Matching with Bag of ConvNet Features for Scalable and Robust Visual Place Recognition”, Autonomous Robots, <https://doi.org/10.1007/s10514-017-9684-3>.
- 2017 Xiao-Long Wang, Hong Zhang, and Guohua Peng, “Combining Multiple Image Descriptions for Loop Closure Detection”, Journal of Intelligent & Robotic Systems, <https://doi.org/10.1007/s10846-017-0755-7>.
- 2017 Yi Hou, Hong Zhang, and Shilin Zhou, “Evaluation of Object Proposals and ConvNet Features for Landmark-Based Visual Place Recognition”, Journal of Intelligent & Robotic Systems, <https://doi.org/10.1007/s10846-017-0735-y>.
- 2017 Yi Hou, Hong Zhang, Shilin Zhou and Huanxin Zou, “Efficient ConvNet Feature Extraction with Multiple RoI Pooling for Landmark-based Visual Localization of Autonomous Vehicles”, Mobile Information Systems, Volume 2017 (2017), Article ID 8104386, 14 pages.
- 2017 Xiaolong Wang, Hong Zhang and Guohua Peng, “A Chordigram Image Descriptor Using Local Edgels”, Journal of Visual Communication and Image Representation, Volume 49, November 2017, pp. 129–140.
- 2017 Li He, Nilanjan Ray, and Hong Zhang, “Error Bound of Nystrom-approximated NCut Eigenvectors and Its Application to Training Size Selection”, Neurocomputing, May 24, 2017, pp. 130-142.
- 2017 Yi Hou, Hong Zhang, and Shilin Zhou, “Tree-based Indexing for Real-time ConvNet Landmark-Based Visual Place Recognition”, International Journal of Advanced Robotic Systems, Volume 14, January 2017, pp. 1-13.
- 2016 Moein Shakeri and Hong Zhang, “COROLA: A Sequential Solution to Moving Object Detection Using Low-rank Approximation”, Computer Vision and Image Understanding, Volume 146, May 2016, pp. 27-39.
- 2016 Li He and Hong Zhang, “Iterative Ensemble Normalized Cuts”, Pattern Recognition, Vol. 52, April 2016, pp. 274–286.
- 2016 Jing Yang, Hong Zhang, and Guo Hua Peng, “Time-Domain Period Detection in Short-Duration Videos”, Signal, Image and Video Processing, Vol. 10, No. 4, April 2016, pp. 695-702.
- 2015 Homa Foroughi, Nilanjan Ray, and Hong Zhang, “Robust People Counting using Sparse Representation and Random Projection”, Pattern Recognition, Vol. 45, No. 10, October 2015, pp. 3038–3052.
- 2015 Haifei Zhu, Yisheng Guan, Wenqiang Wu, L Zhang, Xuefeng Zhou, and Hong Zhang, “Autonomous Pose Detection and Alignment of Suction Modules of a Biped Wall-Climbing Robot”, IEEE-ASME Transactions on Mechatronics, Vol. 2, No. 2, April 2015, pp. 653-662.
- 2014 Xuefeng Zhou, Yisheng Guan, Haifei Zhu, Wenqiang Wu, Xin Chen, Hong Zhang, and Yuli Fu, “Bibot-U6: A Novel 6-DoF Biped Active Walking Robot - Modeling, Planning and Control”, International Journal of Humanoid Robotics, Vol. 11, No. 2, April 2014.

- 2014 Haifei Zhu, Yisheng Guan, W. Wu, X. Chen, X. Zhou, and Hong Zhang, “A Binary Approximating Method for Graspable Region Determination of Biped Climbing Robots”, *Advanced Robotics*, Vol. 28, No. 21, 2014, pp. 1405-1418.
- 2014 Mohamed Bensalah, Ismail Ben Ayed, Jing Yuan, and Hong Zhang, “Convex-Relaxed Kernel Mapping for Image Segmentation”, *IEEE Transactions on Image Processing*, Vol. 23, Issue 3, March 2014, pp. 1143-1153.
- 2014 Zhijie Wang, Mohamed Bensalah, and Hong Zhang, “Object Joint Detection and Tracking Using Adaptive Multiple Motion Models”, *The Visual Computer*, Vol. 30, Issue 2, February 2014, pp. 173-187.
- 2013 Hui Wang, Hong Zhang, and Nilanjan Ray, “Adaptive Shape Prior in GraphCut Image Segmentation”, *Pattern Recognition*, Vol. 46, Issue 5, May 2013, pp. 1409-1414.
- 2013 Xuefeng Zhou, Yisheng Guan, Li Jiang, Haifei Zhu, Chuanwu Cai, Wenqiang Wu and Hong Zhang, “Stability of Biped Robotic Walking with Frictional Constraints”, *Robotica*, Volume 31, Issue 04, July 2013, pp. 573-588.
- 2013 Guan, Y., Zhu, H., Wu, W., Zhou, X., Jiang, L., Cai, C., Zhang, L., and Zhang, H., “A Modular Biped Wall-Climbing Robot with High Mobility and Manipulating Function”, *IEEE/ASME Transactions on Mechatronics*, Volume 18, Issue 6, December 2013, pp. 1787–1798.
- 2013 Robert Stewart and Hong Zhang, “A note concerning the distances of uniformly distributed points from the centre of a rectangle”, *Bulletin of the Australian Mathematical Society*, Vol. 87, No. 1, 2013.
- 2012 Zhengwei Zhang, Hong Zhang, and Yibin Li, “Biologically inspired collective construction with visual landmarks”, *Journal of Zhejiang University-SCIENCE C*, May 2012, Volume 13, Issue 5, pp.315-327.
- 2012 Zhijie Wang, Mohamed Bensalah, Hong Zhang, and Nilanjan Ray, “Shape based appearance model for kernel tracking”, *Image and Vision Computing*, Vol. 30, Issue 4-5, May 2012, pp. 332-344.
- 2012 Nilufar, S., Ray, N., and Zhang, H., “Object Detection with DoG Scale-Space: A Multiple Kernel Learning Approach”, *IEEE Transactions on Image Processing*, Vol. 21, Issue 8, pp. 3744-3756, 2012.
- 2012 Hui Wang, Hong Zhang and Nilanjan Ray, “Clump Splitting Via Bottleneck Detection and Shape Classification”, *Pattern Recognition*, Volume 24, Issue 7, July 2012, pp. 2780-2787.
- 2012 Baidya Nath Saha, Nilanjan Ray, Russell Greiner, Albert Murtha and Hong Zhang, “Quick Detection of Brain Tumors and Edemas: A Bounding Box Method Using Symmetry”, *Computerized Medical Imaging and Graphics*, Volume 36, Issue 2, March 2012, pp. 95-107.
- 2012 Jichuan Shi, Nilanjan Ray and Hong Zhang, “Shape Based Local Thresholding for Binarization of Document Images”, *Pattern Recognition Letters*, Volume 33, Issue 1, January 2012, pp. 24-32.
- 2011 Christopher A. C. Parker and Hong Zhang, “Biologically Inspired Collective Comparisons by Robotic Swarms”, *International Journal of Robotics Research*, April 2011, Vol.30, No. 5, pp. 524-535.
- 2011 Yisheng Guan, Hong Zhang, Xianmin Zhang and Zhangjie Guan, “Workspace Generation of Multi-fingered Manipulation”, *Advanced Robotics*, Vol. 25, No. 18, 2011, pp. 2293-2317.
- 2010 Christopher A. C. Parker and Hong Zhang, “Collective Unary Decision-Making by Decentralized Multiple-Robot Systems Applied to the Task-Sequencing Problem”, *Swarm Intelligence*, Volume 4, Number 3, May 2010, pp. 199-220.
- 2009 B. Saha, N. Ray, and H. Zhang, “Snake Validation: A PCA-Based Outlier Detection Method”, *IEEE Signal Processing Letters*, Vol. 16, No. 6, June 2009.
- 2009 D. P. Mukherjee, Y. Potapovich, I. Levner, I. and H. Zhang, “Ore Image Segmentation by Learning Image and Shape Features”, *Pattern Recognition Letters*, Volume 30, Issue 6, April 2009, pp. 615–622.

- 2009 M. Polak, H. Zhang, and M. Pi, "An Evaluation Metric for Image Segmentation of Multiple Objects", *Image and Vision Computing*, Volume 27, Issue 8, July 2009, pp. 1223-1227.
- 2009 Christopher Parker and Hong Zhang, "Cooperative Decision-Making in Decentralized Multi-Robot Systems: the Best-of-N Problem", *IEEE/ASME Transactions on Mechatronics*, Volume 14, Issue 2, April 2009, pp. 240-251.
- 2008 I. Levner, H. Zhang, and R. Greiner, "Heterogeneous Stacking for Classification Driven Watershed Segmentation", *EURASIP Journal on Advances in Signal Processing*, Special Issue on Machine Learning in Image Processing, January 2008, pp. 1 – 9.
- 2007 Ilya Levner and Hong Zhang, "Classification Driven Watershed Segmentation", *IEEE Transactions on Image Processing*, Volume 16, Number 5, May 2007, pp. 1437-1445..
- 2007 Ricardo Ferrari, Hong Zhang, and Ron Kube, "Real-Time Detection of Steam in Video Images", *Pattern Recognition*, Volume 40, Issue 3, March 2007, pp. 1148-1159..
- 2006 Mingong Pi, Chong Sze Tong, and Hong Zhang, "A Fast and Effective Model for Wavelet Subband Histograms and Its Application in Texture Image Retrieval", *IEEE Transactions on Image Processing*, Vol: 15, No.10, Oct. 2006, pp. 3078-3088.
- 2006 Christopher Parker and Hong Zhang, "Collective Robotic Site Preparation", *Journal of Adaptive Behavior*, 2006, 14:5-19.
- 2005 Yisheng Guan and Hong Zhang, "Feasibility of 2-D Multifingered Grasps," *International Journal of Robotics and Automation*, Vol. 20, No. 4, 2005.
- 2005 Feixiang Yan, Hong Zhang, and C. Ronald Kube, "Multistage Adaptive Thresholding Method", *Pattern Recognition Letters*, Volume 26, Issue 8, June, 2005, pp. 1183-1191.
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