Abhineet Singh

Contact Information	Robotics & Vision Lab (CSC-351) Computing Science Center University of Alberta Edmonton, AB T6G 2R3 Canada	Phone: (587) 596-0470 E-mail: asingh1@ualberta.ca Web: webdocs.cs.ualberta.ca/~asingh1 Code: github.com/abhineet123	
Research Interests	Computer vision and machine learning in general and application of deep learning to object detection, segmentation and tracking in particular		
Education	 University of Alberta, Edmonton, Alberta, Canada Doctor of Philosophy, Computing Science (CGPA: 4/4) Thesis: "End-to-End Multi-Object Tracking" 	Sept 2017 - Present	
	• Advisor: Nilanjan Ray and Hong Zhang		
	 University of Alberta, Edmonton, Alberta, Canada Master of Science, Computing Science (CGPA: 3.4/4) Thesis: "Modular Tracking Framework: A Unified Ap 	Sept 2013 - Feb 2017 proach to Registration-based Tracking"	
	• Advisor: Martin Jagersand		
	 Indian Institute of Information Technology, Allahaba Bachelor of Technology, Information Technology (CGPA: 8.3) Thesis: "Abandoned Object Detection in Video" Advisor: Anupam Agrawal 	d, India Jul 2009 - Jun 2013 21/10)	
	ind loost imapon ingrand		
Publications	To filter prune, or to layer prune, that is the question S. Elkerdawy, M. Elhoushi, A. Singh, H. Zhang and N. Ray	ACCV, Dec 2020	
	One-Shot Layer-Wise Accuracy Approximation for I S. Elkerdawy, M. Elhoushi, A. Singh, H. Zhang and N. Ray	Layer Pruning ICIP, Oct 2020	
	Animal Detection in Man-made Environments A. Singh, M. Pietrasik, G. Natha, N. Ghouaiel, K. Brizel an	d N. Ray WACV, Mar 2020	
	River Ice Segmentation with Deep Learning A. Singh, H. Kalke, M. Loewen and N. Ray	TGRS, Feb 2020	
	Modular Tracking Framework: A Fast Library for High Precision TrackingA. Singh and M. JagersandIROS, Sept 201		
	Real-Time Salient Closed Boundary Tracking via Li X. Qin, S. He, C. Quintero, A. Singh, M. Dehghan and M. J	ne Segments Perceptual Grouping Jagersand IROS Sept 2017	
	4-DoF Tracking for Robot Fine Manipulation Tasks M. Siam, A. Singh, C. Perez and M. Jagersand	CRV, May 2017	
	Unifying Registration based Tracking: A Case Study with Structural SimilarityA. Singh, M. Siam and M. JagersandWACV, Mar 2017		
	Modular Decomposition and Analysis of Registratio A. Singh, A. Roy, X. Zhang and M. Jagersand	n based Trackers CRV, June 2016	

RKLT: 8 DOF Real-Time Robust Video Tracking Combing Coarse Ransac Features and Accurate Fast Template Registration X. Zhang, A. Singh and M. Jagersand *CRV*, June 2015 Online signature verification using segment-level fuzzy modelling A. Ansari, M. Hanmandlu, J. Kour and A. Singh IET Biometrics, Sept 2014 An interactive framework for abandoned and removed object detection in video INDICON, Dec 2013 A. Singh and A. Agrawal An Assessment of the Impact of Dimensionality Reduction on the Speed and Accuracy

of Hyperspectral Image Classification IJACR, Sept 2013 A. Singh, S. Verma, M. Raj and A. Agrawal

Projects Rock detection in fields

Supervisor: Mojtaba Hedavatpour, Mojow Autonomous Solutions

- Developing a rock detector capable of real-time operation on low-power mobile computing devices
- Creating a synthetic data generation pipeline to increase training data variance

Stem Cell Viability Prediction from Time-Lapse Microscopy Images May 2021 - Present Supervisors: Nilanjan Ray and Nidheesh Dadheech, University of Alberta

- Developing a deep learning pipeline to determine the viability of Inducible Pluripotent Stem Cells (IPSCs) to develop into insulin producing islet cells for type 1 diabetes patients
- Localizing individual cells and colonies using panoptic segmentation and tracking
- Classifying these through temporal analysis with sequential networks like transformers

Deep MDP

Supervisor: Nilanjan Ray, University of Alberta

- Attempted to improve the performance of the MDP muti-object tracking system and reduce its dependency on handcrafted features and heuristics using deep learning
- Created an elegant abstraction to generalize this framework to incorporate deep learning-based trackers, feature extractors and classifiers and make end-to-end training feasible
- Developed a parameter specification and parsing library for deeply nested and modular systems

Fence Damage Detection with Laser Imaging

Supervisor: Ken Brizel, ACAMP

- Extracted binary masks for fence sections by applying edge detection to stitched laser line images
- Used autoencoders and other unsupervised methods to detect fence anomalies including holes

Title Block Detection in Construction Documents

Supervisors: Nilanjan Ray and Yasser Mohammad, University of Alberta

• Helped develop a deep learning pipeline for classifying and extracting information from scanned construction documents

River Ice Segmentation with Deep Learning

Supervisors: Nilanjan Ray and Mark Loewen, University of Alberta

- Adapted 4 state of the art architectures UNet, SegNet, Deeplab and DenseNet for dense pixelwise segmentation of river ice images and videos into frazil and anchor ice
- Devised a new metric for unsupervised evaluation of video segmentations

Animal and Human Detection with Deep Learning May - Aug 2018, Jan - Apr 2019 Supervisors: Nilanjan Ray, University of Alberta and Nehla Ghouaiel, ACAMP

May 2019 - Apr 2021

Aug 2018 - Present

Jan - Apr 2018

Sept 2020 - Mar 2021

Sept 2021 - Present

- Trained a variety of deep detectors Faster RCNN, RFCN, SSD, YOLOv3 for detecting humans and 8 types of animals
- Trained several instance segmentation models Mask RCNN, Sharpmask, FCIS and integrated them within a user-friendly GUI to generate realistic synthetic data
- Developed efficient ways to get compressed video data from ATV to GPU server in real time

Improving model-based RL with Adaptive Rollout

Supervisor: Martha White, University of Alberta

• Helped develop an algorithm to improve model based RL by automatically selecting the imagination rollout length for planning

Mar 2017 - Jan 2018 Vehicle and Pedestrian Tracking for Intersection Traffic Analysis Supervisor: Nilanjan Ray, University of Alberta

- Created a system for tracking vehicles and pedestrians in road traffic videos captured from UAVs and pole mounted cameras at intersections and round-abouts
- Converted Matlab implementation of the MDP tracker to Python and made it an order of magnitude faster to allow real time deployment

Modular Tracking Framework

Supervisor: Martin Jagersand, University of Alberta

- Devised a novel way to study registration based trackers by decomposing them into three constituent sub-modules: appearance model, search method and state space model
- Created a highly efficient tracking library in C++ with MATLAB and Python bindings

3D Object Recognition using Deep Learning

Supervisor: Dale Schuurmans, University of Alberta

• Developed and tested several variants of the 6 hidden layer LeNet-5 architecture for classifying handwritten digits and 3D real world objects

Abandoned Object Detection in Video

Supervisor: Anupam Agrawal, IIIT Allahabad

• Created a complete modular framework for detecting abandoned and removed objects in video streams using C++ with OpenCV

Multi Object Recognition in an Indoor Environment

Supervisor: U.S. Tiwary, IIIT Allahabad

• Created an object recognition system based on a hierarchical model of visual processing in the human visual cortex

Online Signature Verification using Segment-Level Fuzzy Modeling May - Jul 2011, 2012 Supervisor: Madasu Hanmandlu, IIT Delhi

• Used geometric extrema to segment the signature, dynamic time warping to match segments of different samples and Mamdani fuzzy model to compare matching segments

Jan - Jun 2012 Dimensionality Reduction and Classification of Hyper-Spectral Images Supervisor: Anupam Agrawal, IIIT Allahabad

• Used PCA and ICA for dimensionality reduction and SVM with sequential minimal optimization algorithm for classification of 224 band AVIRIS and 210 band HYDICE remote sensing images

Object Based Change Detection in Multi-Temporal Satellite Images Jul - Nov 2011 Supervisor: Anupam Agrawal, IIIT Allahabad

• Extended a multi-feature fusion based change detection system with a hierarchical clustering and tested on Google Earth images of IIIT-A taken in 2004 and 2008

Jan - Apr 2014

May 2014 - Feb 2017

Jan - Jul 2013

Jul - Nov 2012

Jan - Apr 2018

Academic Experience	EMICGraduate Courses:Optimization Principles for Reinforcement Learning, Visual RecognitionRIENCEReinforcement Learning for AI, Autonomous Robot Navigation, Computational Neuroscience Representational Learning, Computer Graphics, Online LearningTeaching Assistant:Digital Image Processing, Visual Recognition, Computer Vision, Introduction to Computer Graphics, Introduction to the Foundations of Computation		
	Research Assistant Summer 2017, 20 Supervisor: Nilanjan Ray, University of Alberta • Created a vehicle and pedestrian tracking system and extended it with deep lease)19, 2020, 2021	
	• Worked on a cell tracking and segmentation project for IPSC growth prediction		
	 Research Assistant Summer 2014, 2015, 2016 Supervisor: Martin Jagersand, University of Alberta Created a modular system for registration based tracking and implemented 13 appearance models, 12 state space models, 10 search methods and 3 illumination models 		
Industry Experience	 ACAMP May - Aug 2018, Jan - Apr 2019, Sept 2020 - Mar 2021 Worked on the vision and AI aspects of an autonomous ATV patrolling the perimmeter at Edmonton International Airport 		
	Mojow Autonomous Solutions Sept • Working on a variety of farming related visual recognition tasks including rock boundary detection, road detection and 3D pose estimation	2021 - Present detection, field	
Scholastic Tests	• CELPIP General Test Listening: Level 11, Reading: Level 12, Writing: Level 9, Speaking: Level 8	Aug 2017	
	• Graduate Aptitude Test in Engineering (CS & IT): 99.96 percentile	Jan 2013	
	• GRE revised general test	Nov 2012	
	Verbal Reasoning: 165, Quantitative Reasoning: 169, Analytical Writing: 4.5	N. 0010	
	• TOEFL iBT Listoning: 20 Reading: 20 Writing: 30 Speaking: 26	Nov 2012	
	• eLitmus pH test: 00 07 percentile	July 2012	
	• All India Engineering Entrance Examination: 99.11 percentile	Apr 2009	
	National Talent Search Examination: Qualified Stage I	Nov 2006	
Technical Skills	 Languages: C/C++, Python, C#, Java, MATLAB, HTML, JavaScript, Prolog, SOAR, Lex-Yacc, Assembly (8086) Software: MS Visual Studio, Netbeans, Eclipse, Code::Blocks, PyCharm, Intel Parallel Studio, ERDAS Imagine, ITTVIS ENVI, CLIPS, Adobe Photoshop Libraries: PyTorch, Tensorflow, MXNet, Keras, Theano, CUDA, OpenAI Gym, OpenGL, OpenCV, ViSP, Eigen, Intel TBB, OpenMP, GSL, ROS, Weka, LibSVM, VLFeat Operating Systems: Linux (Ubuntu, Fedora), Windows, macOS, iOS, Android 		