Agenda:

- 0/1 Knapscak
- Chain Matrix Multiplication

Reading:

• Textbook pages 331-349

Dynamic programming introduction:

- An algorithm design technique
- Usually for optimization problems
- Typically like divide-and-conquer uses solutions to subproblems to solve the problem, BUT
- Key idea:
  - Avoids re-computation
  - of repeated subproblems by storing subproblem answers in tables/arrays
- 1<sup>st</sup> example problem Fibonacci numbers

	$f(n) = \begin{cases} n, & \text{when } n = 0, 1\\ f(n-1) + f(n-2), & \text{when } n \ge 2 \end{cases}$										
n	0	1	2	3	4	5	6	7	8	9	
f(n)	0	1	1	2	3	5	8	13	21	34	

Question: how do we compute f(n)?

1<sup>st</sup> Naive Fibonacci implementation – recursion

• Pseudocode:

```
procedure f(n)

if n < 2 then

return n

else

return f(n-1) + f(n-2)
```

• Recursion tree:

f(5)

$$\begin{array}{cccc} f(4) & f(3) \\ f(3) & f(2) & f(2) & f(1) \\ f(2) & f(1) & f(1) & f(0) & f(1) & f(0) \\ f(1) & f(0) \end{array}$$

- Notice that there are a lot of repeated function calls
- Running time recurrence  $T(n) = \begin{cases} c_1, & \text{when } n = 0, 1 \\ c_2 + T(n-1) + T(n-2), & \text{when } n \ge 2 \end{cases}$
- Conclusion:  $T(n) > f(n) \longrightarrow T(n) \in \Omega\left(\left(\frac{1+\sqrt{5}}{2}\right)^n\right)$

- $\bullet$  Problem with the  $1^{\rm st}$  implementation repeated function calls
- Key idea:

Do the computation in a bottom up manner, and Store the compute values for future use.

- Define array F[0..n] where F[i] is going to store f(i).
- Fill in the values of F[0] and F[1] from the definition (initialization)
- Start computing F[i], from i = 2 onward, using the recurrence  $F[i] \leftarrow F[i-1] + F[i-2]$ .
- Each time, we want to compute F[i], F[i-1] and F[i-2] are *already computed!* (bottom up).

2<sup>nd</sup> Fibonacci implementation — dynamic programming

• Pseudocode:

```
procedure Dynfib(n)

F[0] \leftarrow 0

F[1] \leftarrow 1

for j \leftarrow 2 to n do

F[j] \leftarrow F[j-1] + F[j-2]

return F[n]
```

• Running time

 $T(n) \in \Theta(n)$ 

General steps in designing a dynamic programming solution:

- Step 1: Describe an array of values that you want to compute.
   Do not say how you compute the array, but define what you store in the array. (e.g. array F[0..n] and F[i] is going to hold f(i)).
- Step 2: Give a recurrence relating some values in the array to other values in the array.

The basis of your recurrence should specify how to initialize the array (e.g. F[0] = 0, F[1] = 1, and F[i] = F[i-1] + F[i-2]).

- Step 3: Give a high level program to compute the entries of the array using the recurrence above.
- Step 4: State how to extract the solution from the array (e.g. return F[n]).

2<sup>nd</sup> example problem — Knapsack

- We have a knapsack with capacity  $\boldsymbol{W}$
- *n* items with weights  $w_1, \ldots, w_n \in \mathbb{N}$  and values  $v_1, \ldots, v_n \in \mathbb{N}$ .
- Want to fill the knapsack with items to maximize the value without exceeding its capacity.
- Formally, for each  $S \subseteq \{1, \ldots, n\}$  let  $K(S) = \sum_{i \in S} w_i$ .
- Find  $M = \max_{S \subseteq \{1,...,n\}} \{K(S) | K(S) \le W\}.$
- Example:  $w_1 = 10$ ,  $w_2 = 10$ ,  $w_3 = 15$ ,  $v_1 = 10$ ,  $v_2 = 10$ ,  $v_3 = 16$ , W = 20. Greedy picks item 3 whereas the optimal is to pick 1 and 2.

 $1^{\rm st}$  (naive) solution: try all possible subsets of items and select the best.

- Consider each set S of all  $2^n$  possible subsets of  $\{1, \ldots, n\}$ .
- Compute the weight and value of set S.
- Find the set with maximum value among those that have  $K(S) \leq W$ .
- Running time: at least  $\Omega(2^n)$  subsets to consider!!

2<sup>nd</sup> solution: use Dynamic programming.

- Step 1: Define array A[i, D],  $0 \le i \le n$  and  $0 \le D \le W$  where A[i, D] is the value of best possible knapsack of weight at most D using only items from 1 to i. Final sol. value: A[n, W].
- Step 2: How to compute A[i, D]?
  - If i = 0 or D = 0 then trivially A[i, D] = 0.
  - Else, consider item i:
    - \* If we do not choose item *i*: knapsack must be packed optimally with items from  $1 \dots (i-1)$ .
    - \* If we choose item *i* (assuming  $D \ge w_i$ ): rest of  $D w_i$  remaing cap. must be packed with items  $1 \dots (i-1)$ .

\* So 
$$A[i, D] = \max \begin{cases} A[i-1, D] \\ (\text{if } D \ge w_i) v_i + A[i-1, D-w_i] \end{cases}$$

• Step 3:

procedure Knapsack

for 
$$i \leftarrow 1$$
 to  $n$  do  
 $A[i,0] \leftarrow 0$   
for  $D \leftarrow 0$  to  $W$  do  
 $A[0,D] \leftarrow 0$   
for  $i \leftarrow 1$  to  $n$  do  
for  $D \leftarrow 1$  to  $W$  do  
 $A[i,D] \leftarrow A[i-1,D]$   
if  $D \ge w_i$  and  $A[i,D] < A[i-1,D-w_i] + v_i$  then  
 $A[i,D] \leftarrow A[i-1,D-w_i] + v_i$   
return  $A[n,W]$ 

• The running time is O(nW) since the are only a constant number of operation per each iteration of the inner loop.

- Step 4: How to find the set of items of the optimal packing?
- Consider item n. It can be seen that if A[n, W] = A[n 1, W] then item n is not in the optimal solution. Else it is in the solution and A[n, W] is obtained from  $A[n 1, W w_n]$  by adding item n.
- We can so go to this new entry to find out if item n-1 is in the solution or not.
- This suggests the following algorithm to find the optimal solution itself:

```
If i = 0 or D = 0 then
return
Else
If A[i, D] \neq A[i - 1, D] then
Print (i)
Print-Opt-Knapsack (i - 1, D - w_i)
else if A[i, D] = A[i - 1, D] then
Print-Opt-Knapsack (i - 1, D)
```

procedure Print-Opt-Knapsack (i, D)

Matrix-chain multiplication:

- Input: matrices  $A_1$ ,  $A_2$ , ...,  $A_n$  with dimensions  $d_0 \times d_1$ ,  $d_1 \times d_2$ , ...,  $d_{n-1} \times d_n$ , respectively.
- Output: an order in which matrices should be multiplied such that the product  $A_1 \times A_2 \times \ldots \times A_n$  is computed using the minimum number of scalar multiplications.
- Fact: suppose  $A_1$  is a  $d_1 \times d_2$  matrix,  $A_2$  is a  $d_2 \times d_3$  matrix. Then  $A_1$  and  $A_2$  is multipliable, and  $B = A_1 \times A_2$  can be computed using  $d_1 \times \overline{d_2 \times d_3}$  scalar multiplications.
- Example: n = 4 and  $(d_0, d_1, \dots, d_n) = (5, 2, 6, 4, 3)$

Possible orders with different number of scalar multiplications:

 $\begin{array}{ll} ((A_1 \times A_2) \times A_3) \times A_4 & 5 \times 2 \times 6 + 5 \times 6 \times 4 + 5 \times 4 \times 3 = 240 \\ (A_1 \times (A_2 \times A_3)) \times A_4 & 5 \times 2 \times 4 + 2 \times 6 \times 4 + 5 \times 4 \times 3 = 148 \\ (A_1 \times A_2) \times (A_3 \times A_4) & 5 \times 2 \times 6 + 5 \times 6 \times 3 + 6 \times 4 \times 3 = 222 \\ A_1 \times ((A_2 \times A_3) \times A_4) & 5 \times 2 \times 3 + 2 \times 6 \times 4 + 2 \times 4 \times 3 = 102 \\ A_1 \times (A_2 \times (A_3 \times A_4)) & 5 \times 2 \times 3 + 2 \times 6 \times 3 + 6 \times 4 \times 3 = 138 \end{array}$ 

## 1<sup>st</sup> Matrix-chain multiplication — Recursion:

• Let T(n) be the number of multiplication orders for n matrices.

How big is T(n) ???

 n
 1
 2
 3
 4
 5
 6
 ...

 T(n) 1
 1
 2
 5
 14
 42
 ...

- Consider the highest level parenthesis:  $(A_1 \dots A_i)(A_{i+1} \dots A_n)$ .
- There are n − 1 possiblities: i can be anyware between 1 to n − 1 (e.g A<sub>1</sub>(A<sub>2</sub>...A<sub>n</sub>) to (A<sub>1</sub>...A<sub>n-1</sub>)A<sub>n</sub>.
- The number of ways to put parentheses for each of  $(A_1 \dots A_i)$ and  $(A_{i+1} \dots A_n)$  is T(i) and T(n-i), respectively.
- Therefore:

$$T(n) = \begin{cases} 1, & \text{when } n = 0, 1\\ \sum_{i=1}^{n-1} T(i) \times T(n-i), & \text{when } n \ge 2 \end{cases}$$

- Solving this recurrence (not easy) shows:  $T(n) = \frac{\binom{2n}{n}}{\frac{n+1}{n+1}} \approx \frac{4^n}{n\sqrt{\pi n}}$
- Recursive program will have similar running time:  $\Omega(3^n)$ .
- Cannot afford this!!

Use dynamic programming:

- Step 1: Define *M*[*i*, *j*] (1 ≤ *i* ≤ *j*): the minimum number of scalar multiplications needed to compute product *A<sub>i</sub>* × *A<sub>i+1</sub>* × ... × *A<sub>j</sub>* (*i* ≤ *j*)
- Step 2: The recurrence to fill in the entries of the array:  $M[i,j] = \begin{cases} 0, & \text{if } i = j \\ \min_{i \le k < j} \{M[i,k] + M[k+1,j] + d_{i-1}d_kd_j\}, & \text{if } i < j \end{cases}$
- for example,

$$M[1,4] = \min \left\{ \begin{array}{c} M[1,1] + M[2,4] + d_0 \times d_1 \times d_4 \\ M[1,2] + M[3,4] + d_0 \times d_2 \times d_4 \\ M[1,3] + M[4,4] + d_0 \times d_3 \times d_4 \end{array} \right\}$$

• Step 3: Pseudocode (to obtain the optimal cost):

procedure dpM(1, n)

```
for i \leftarrow 1 to n do

M[i,i] \leftarrow 0

for shift \leftarrow 1 to n do

for i \leftarrow 1 to n - shift do

j \leftarrow i + shift

M[i,j] \leftarrow \infty

for k \leftarrow i to j - 1 do

new \leftarrow M[i,k] + M[k+1,j] + d_{i-1} \times d_k \times d_j

if new < M[i,j] then

M[i,j] \leftarrow new

return M[1,n]
```

• To obtain the actual ordering:

```
procedure dpM(1, n)

for i \leftarrow 1 to n do

M[i,i] \leftarrow 0

for shift \leftarrow 1 to n do

for i \leftarrow 1 to n - shift do

j \leftarrow i + shift

M[i,j] \leftarrow \infty

for k \leftarrow i to j - 1 do

new \leftarrow M[i,k] + M[k+1,j] + d_{i-1} \times d_k \times d_j

if new < M[i,j] then

M[i,j] \leftarrow new

S[i,j] \leftarrow k

return M[1,n]

• We call Print-Opt-Order (S, 1, n):
```

```
If i = j then

Print ("A_i'')

Else

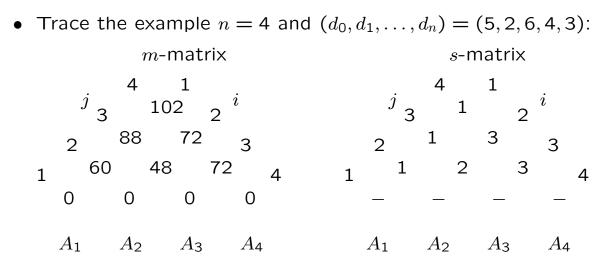
Print ''(''

Print-Opt-Order (S, i, S[i, j])

Print-Opt-Order (S, S[i, j] + 1, j)

Print '')''
```

procedure Print-Opt-Order(S, i, j)



- The innermost for loopbody takes constant time ...
   So dpM(n) worst case running time ∈ Θ(n<sup>3</sup>).
- Some final observations:
  - Suppose we have computed the order of multiplications
  - And the last multiplication is between  $(A_1 \times \ldots \times A_j)$  and  $(A_{j+1} \times \ldots \times A_n)$
  - Then the suborders  $(A_1 \times \ldots \times A_j)$  and  $(A_{j+1} \times \ldots \times A_n)$  are optimal orders for the subproblems, respectively.
  - We call this ... optimal substructures
  - Equivalently, we need to compute optimal orders for
    - \* multiplying matrices  $A_1, A_2, \ldots, A_j$
    - \* multiplying  $A_{j+1}, A_{j+2}, \ldots, A_n$ ,
  - for every  $1 \le j \le n-1$ , and combine them into an order to multiplying  $A_1, A_2, \ldots, A_n$
  - choose the best order out of the (n-1) possibilities

Dynamic programming key characteristics:

- Recurrence relation exists
- Recursive calls overlap
- Small number of subproblems
- Huge number of calls
- Avoid re-computation
- Bottom-up computation
- Top-down trace

Other problems suited to Dynamic programming:

- String matching: Longest Common Subsequence (next lecture)
- Optimal binary search tree construction (textbook page 356)
- All pair shortest paths in (di)graphs (CMPUT 304)
- Optimal layout in VLSI (could be a thesis topic :-))