

## Lecture 17: Wednesday February 12, 2003

### today

- decision tree sorting lower bound [CLRS Ch. 8.1]

### soon

- dynamic programming (start today) [CLRS Ch. 15.1-3]
- union find [CLRS Ch. 21]
- graph algorithms [CLRS Ch. 22,23]

**a sorting lower bound** [CLRS Ch. 8.1]

**two useful trees in algorithm analysis**

- **recursion tree**

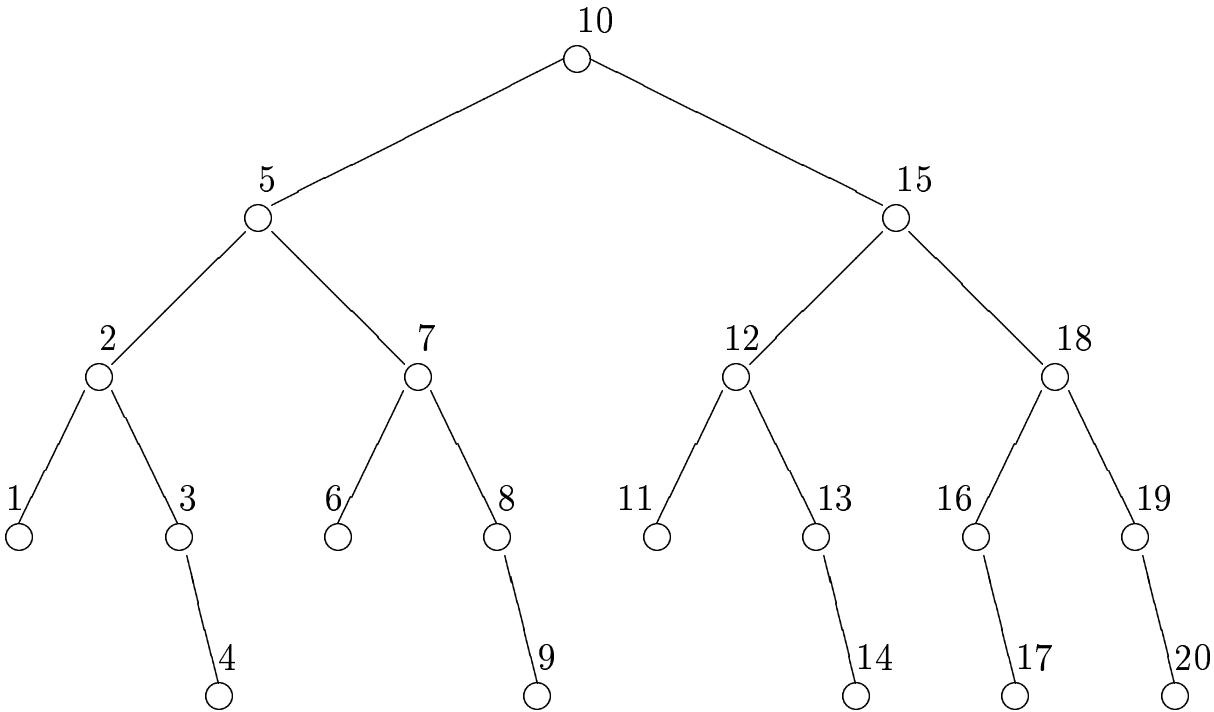
- node  $\leftrightarrow$  recursion call
- describes algorithm execution for one particular input, by showing all calls made
- one algorithm execution  $\leftrightarrow$  all nodes
- useful in analysis: sum number of operations over all nodes

- **decision tree**

- node  $\leftrightarrow$  algorithm decision
- describes algorithm execution for all possible inputs, by showing all possible algorithm decisions
- one algorithm execution  $\leftrightarrow$  one root-to-leaf path
- useful in analysis: sum number of operations over one path

## binary search decision tree, $n = 20$

- assume input keys in array  $A[1 \dots 20]$
- tree node:  $\leftrightarrow$  '3-way' key comparison  $<? =? >?$
- node label:  $A[j]$

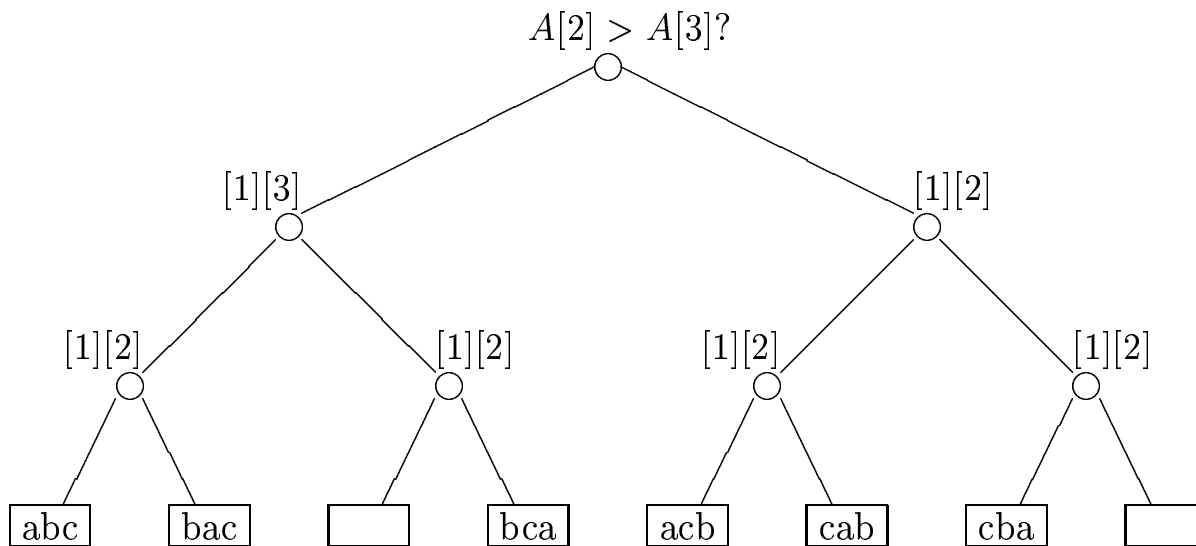


- WC number KC: 5 in general,  $1 + \lfloor \lg n \rfloor$
- AC number KC? ask: input distribution?
  - target in list, each location equiprobable  
 $(2^0 \cdot 1 + 2^1 \cdot 2 + 2^2 \cdot 3 + 2^3 \cdot 4 + 5 \cdot 5) / 20 = 3.7$
  - target not in list, each 'gap' equiprobable  
 $(11 \cdot 4 + 10 \cdot 5) / 21 \approx 4.5$
  - both dist'ns:  $AC(n = 2^k - 1) \approx \lfloor \lg n \rfloor + 1/2$

## selection sort decision tree, $n = 3$

- assume input keys in array  $A[1 \dots 3]$ , initially  $[a \ b \ c]$
- tree node:  $A[k] > A[j]$ ? key comparison
- node label:  $A[j]$

```
for j <- n downto 2 do
  psn <- j    (*index of max*)
  for k <- j-1 downto 1 do
    if A[k] > A[psn] then psn <- k
  exchange A[j] <-> [psn]
```



- notice: every case, 3 KC

## sorting lower bound

- comparison based sort: keys can be compared **only**
- this argument considers **only** comparison based sort algorithms
- any binary tree with  $t$  leaves and  $k$  levels:
  - $t \leq 2^{k-1}$
  - $\lg t \leq k - 1$
  - $1 + \lg t \leq k$ , namely  
binary tree with  $t$  leaves has  $\geq 1 + \lg t$  levels
- the decision tree of any comparison based sort ...
  - binary
  - has  $n!$  leaves
  - ...so has at least  $1 + \lg(n!) = 1 + \sum_{j=1}^n \lg j \in \Theta(n \lg n)$  levels
- conclusion: any comparison based sort has
  - worst case number of key comparisons in  $\Omega(n \lg n)$
  - worst case run time in  $\Omega(n \lg n)$  😊
- comparison based: selectsort, insertsort, heapsort, quicksort
- **not** comparison based: radix sort, bucket sort
- see Ch. 8 for extra reading



end of material for Section B1 Midterm



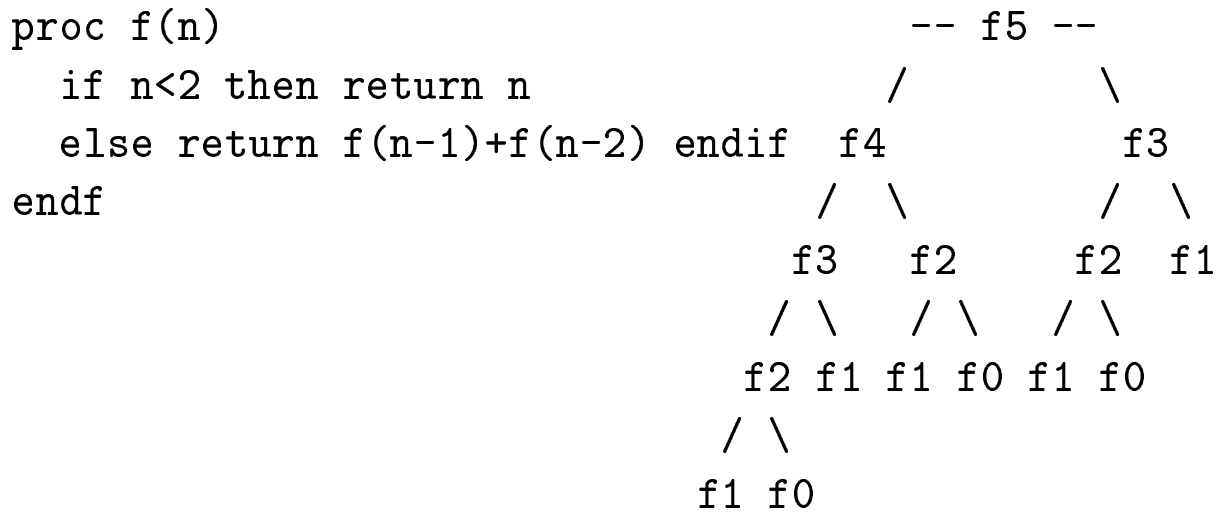
## dynamic programming

- an algorithm design technique
- DP: avoiding recomputation of repeated subproblems by storing subproblem answers in tables/arrays

### 1st example problem: Fibonacci numbers

- $$f(n) = \begin{cases} n & \text{if } n = 0, 1 \\ f(n-1) + f(n-2) & \text{if } n \geq 2 \end{cases}$$

- 1st Fibonacci implementation: recursion



- ☹ repeated function calls

- time 
$$T(n) = \begin{cases} c_1 & \text{if } n = 0, 1 \\ c_2 + T(n-1) + T(n-2) & \text{if } n \geq 2 \end{cases}$$

- $T(n) > f(n)$  so 
$$T(n) \in \Omega\left(\left(\frac{1+\sqrt{5}}{2}\right)^n\right) \quad \text{☹}$$