Geometry

Zachary Friggstad

Programming Club Meeting

Points

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typedef complex<double> point;

point p(1.0, 5.7);
p.real(); // x component
p.imag(); // y component
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Helpful operations

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point p, q;
p+q; // exactly what you expect
p *= polar(1, theta); //rotate around (0,0) by theta radians
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arg(p); //angle from positive x-axis, measured in (-pi, pi]
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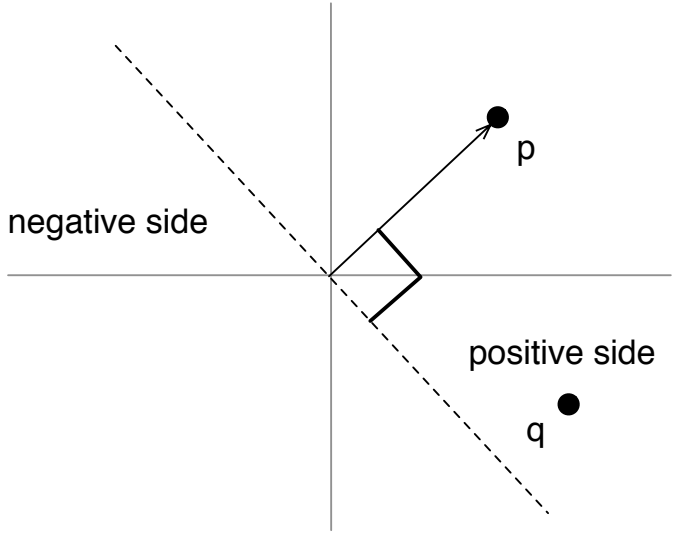
One Annoyance: we can't update the x and y components without creating a new point.

Dot Product

$$p \circ q = p_x \cdot q_x + p_y \cdot q_y = ||p|| \cdot ||q|| \cdot \cos\theta$$

```
double dot(point p, point q) { return real(p*conj(q)); }
```



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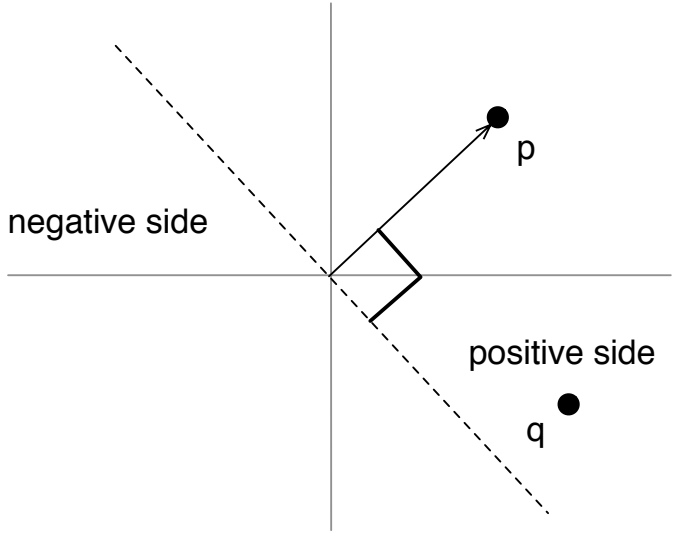

- $p \circ q = 0$ if $p \perp q$ (or one of them is 0)
- $p \circ p = ||p||^2$
- $p \circ q > 0$: q lies in the *same* general direction as p
- $p \circ q < 0$: q lies in the *opposite* general direction as p

Cross Product

$$p \times q = p_x \cdot q_y - p_y \cdot q_x = ||p|| \cdot ||q|| \cdot \sin\theta$$

```
double cross(point p, point q) { return imag(p*conj(q)); }
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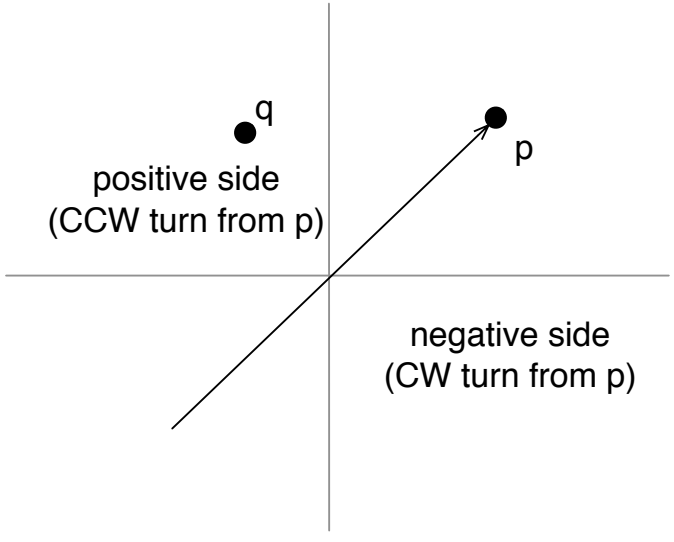

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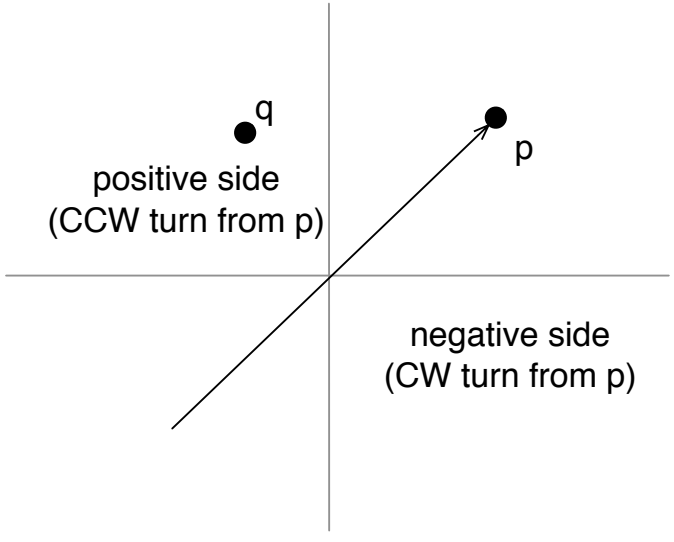
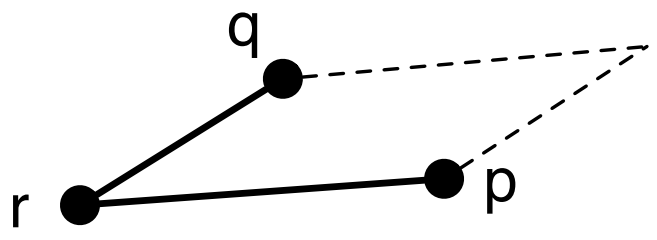


- $p \times q = 0$ if p and q are collinear with 0 (or one of them is 0)
- $p \times q > 0$: $\angle(p, q)$ is *counterclockwise*
- $p \times q < 0$: $\angle(p, q)$ is *clockwise*

$\frac{1}{2}|(p-r)\times(q-r)|$ is the area of the triangle with corners p, q, r.



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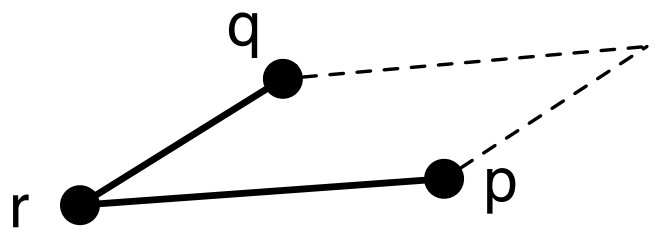
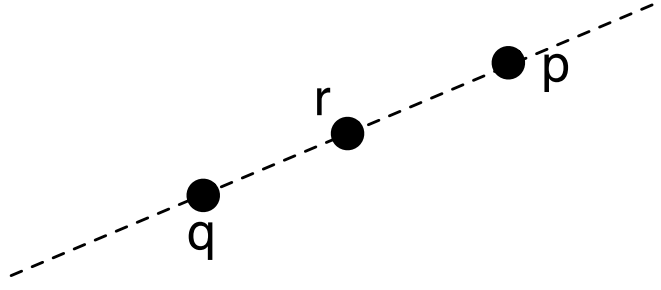


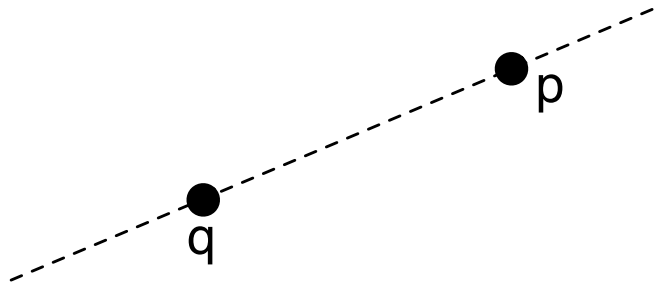
Tip: p lies on the line passing through points q and r **if and only if** $(q-p)\times(r-p)=0$.



Additionally: if p lies on this line then it lies between q and r **if and only** if $(q-p)\circ(r-p)\leq 0$.

Parametric representation of a line passing through p and q:

$$r(t) = (1 - t) \cdot p + t \cdot q, \quad t \in \mathbb{R}$$



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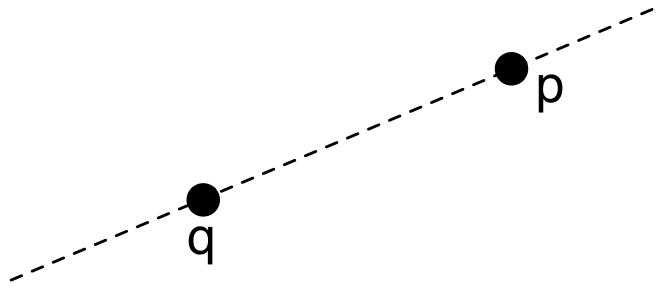

Note $r(0) = p$ and $r(1) = q$.

The line segment connecting p and q is parameterized this way, with the restriction $0 \leq t \leq 1$.

Given two lines passing through p, q and p', q' respectively, compute their intersection point (if any).

Solve $(1 - t) \cdot p + t \cdot q = (1 - t')p' + t' \cdot q'$ for $t, t' \in \mathbb{R}$.

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$$\begin{bmatrix} q_x - p_x & p'_x - q'_x \\ q_y - p_y & p'_y - q'_y \end{bmatrix} \cdot \begin{bmatrix} t \\ t' \end{bmatrix} = \begin{bmatrix} p'_x - p_x \\ p'_y - p_y \end{bmatrix}$$

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Use Cramer's rule: for $A \cdot x = b$ we have

$$x_i = \frac{\det A_i}{\det A}$$

Where A_i is the matrix obtained by replacing column i of A with b.

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Tip: $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$.

$\det A = 0$ means the lines are parallel.

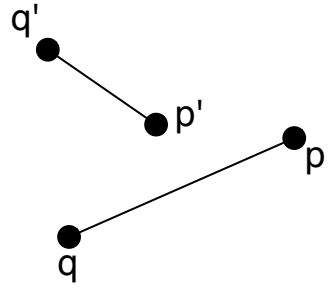
Code

Note the 2×2 determinants can just be replaced by cross products!

```
// find where lines p1q1 and p2q2 intersect
// assumes p1 != q1, p2 != q2
point isect(point p1, point q1, point p2, point q2) {
    double den = cross(q1-p1, p2-q2);
    if (fabs(den) < EPS) {
        // parallel lines, do whatever you want
        // they coincide iff fabs(cross(p1-p2, q1-p2)) < 1e-8
    }
    double t = cross(p2-p1, p2-q2)/den;

    return (1-t)*p1 + t*q1;
}
```

Computing the intersection of two line segments.



- If the infinite lines intersect (i.e. not parallel), get values t, t'.
- Ensure $0 \leq t \leq 1$ and $0 \leq t' \leq 1$.

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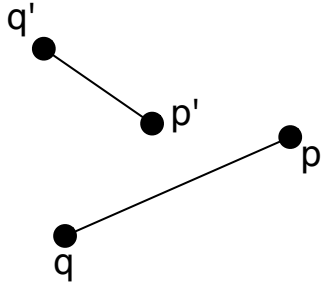

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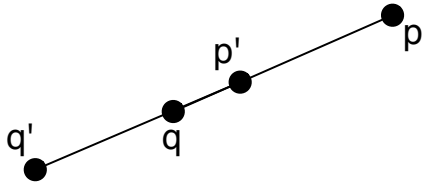
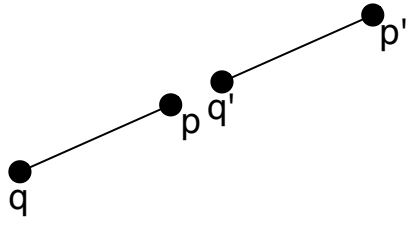
If lines are colinear:

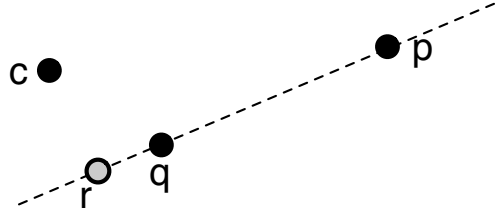




- If $p = p'$ and $q = q'$ or vice versa, they overlap.
- Else if a point is in the interior of the other segment, they overlap.
- Else if the segments share a point, they touch only at that point.
- Else they do not touch.

Closest point on a line.

Given a line passing through p, q and another point c, find the point r on the line $\overline{pq}$ nearest to c.



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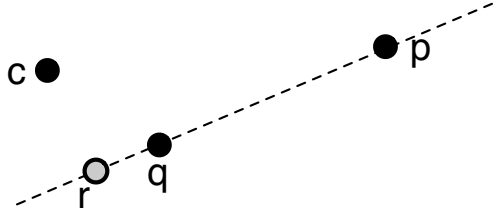

Assume $c = (0, 0)$ by shifting if necessary.

Minimize $||(1 - t)p + t \cdot q||^2$ over $t \in \mathbb{R}$ (avoids the square root).

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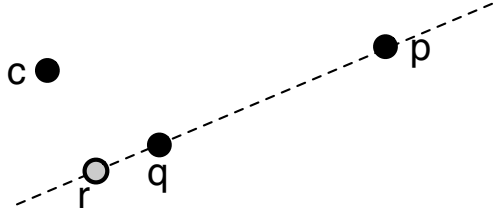

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This is just minimizing some quadratic:

$$A \cdot t^2 + B \cdot t + C$$

Tip: the minimum is at $-\frac{B}{2A}$. If $A = 0$, then $p = q$.

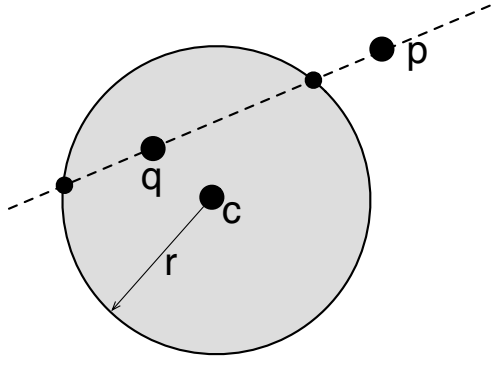
Code

After working out details...

```
// return the point on the line pq closest to c
point closest_point(point p, point q, point c) {
    p -= c; q -= c;
    double den = norm(p-q);
    if (fabs(den) < 1e-8) {
        // p=q, do whatever you want
    }
    double t = dot(p, p-q)/den;
    return (1-t)*p + t*q + c;
}
```

Line-Circle Intersection

A line $\overline{pq}$ and a circle (r, c) (radius/center point) does the line puncture the circle?



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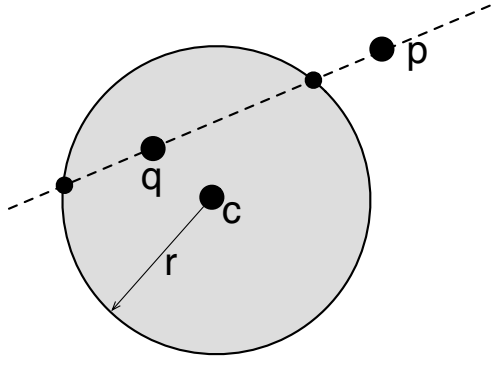

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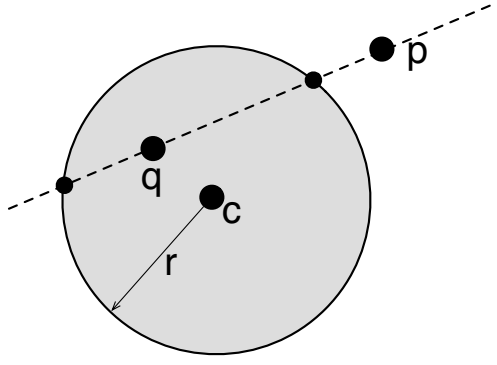

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Rearrange: $A\cdot t^2 + B\cdot t + C = 0$. $A = 0$ means $p = q$.

Tip: Use the quadratic formula

$$\frac{-B \pm \sqrt{\Delta}}{2A} \quad \text{where} \quad \Delta = B^2 - 4AC.$$

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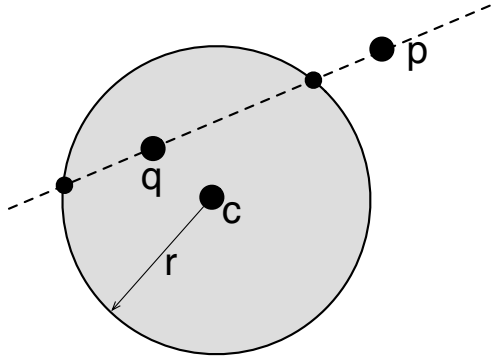

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$\Delta < 0$: line misses, $\Delta = 0$: line tangent, $\Delta > 0$: line punctures.

Code

```
// return # of intersections and set parameters
// z1, z2 to these points (if applicable)
int line_circle(point c, double r, point p, point q,
                point& z1, point& z2) {
    p -= c; q -= c;
    double A = norm(p-q), B = 2*dot(p, q-p), C = norm(p)-r*r;
    double disc = B*B - 4*A*C;

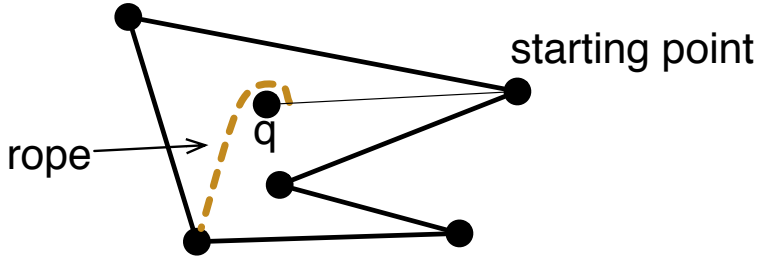
    if (disc + EPS < 0) return 0;

    double rt = sqrt(fabs(disc));
    double t1 = (-B+rt)/(2*A);
    double t2 = (-B-rt)/(2*A);

    z1 = (1-t1)*p + t1*q + c;
    z2 = (1-t2)*p + t2*q + c;
    return (disc < EPS ? 1 : 2);
}
```

Point q in Polygon $P : p_1, \ldots, p_n$?

Intuition: walk about the polygon with a rope taut with "post" q.



If q is inside, the rope wraps around once. If q is outside, the rope doesn't wrap around.

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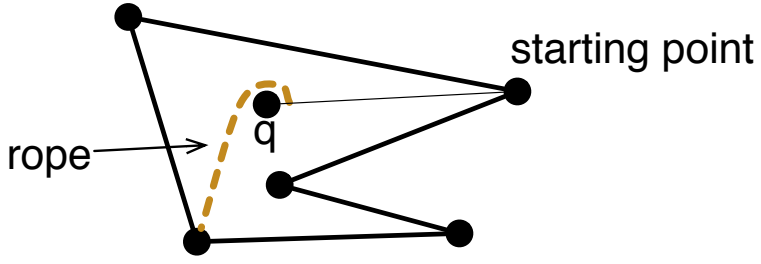

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```
double delta = 0;
for (int i = 0, j = n-1; i < n; j = i++)
    delta += arg((p[i]-q) / (p[j]-q)); //change in angle
return fabs(delta) > 1; //|delta| is 0 or 2*pi
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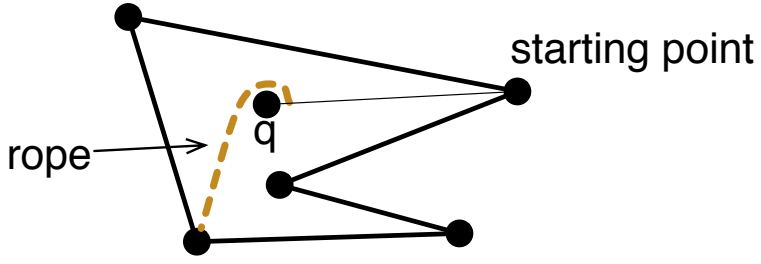

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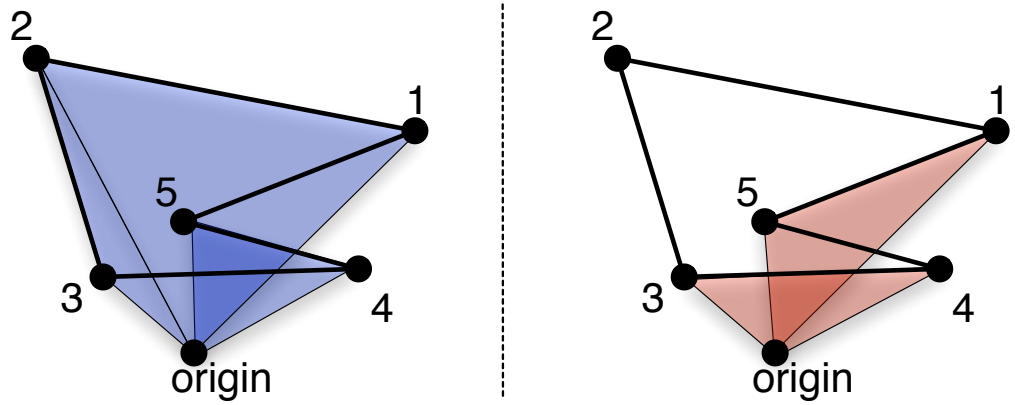
Have to add a bit more to check if q lies on the boundary (cross and dot product test mentioned earlier).

Area of a Polygon $P : p_1, \ldots, p_n$



blue triangle: count the area **positively** (CCW turn about origin)

red triangle: count the area **negatively** (CW turn about origin)

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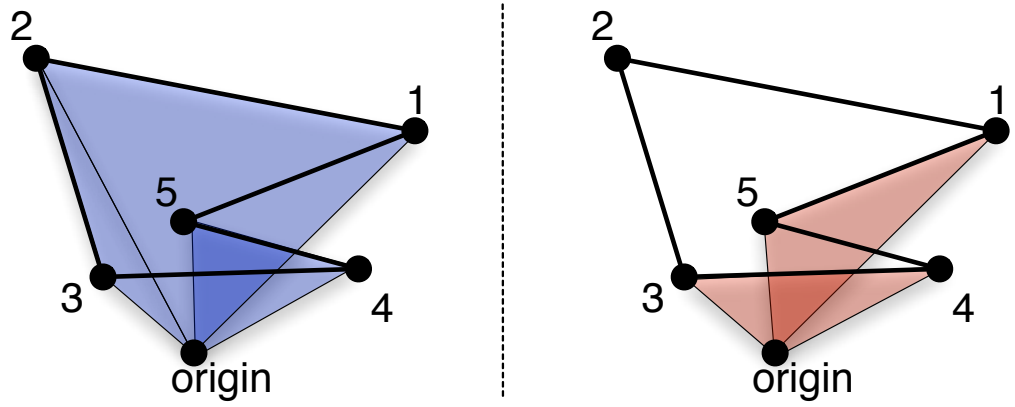

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for (int i = 0, j = n-1; i < n; j = i++)
    //signed area of triangle [origin, p[i-1], p[i]]
    area += cross(p[i], p[j])*0.5;
return fabs(area);
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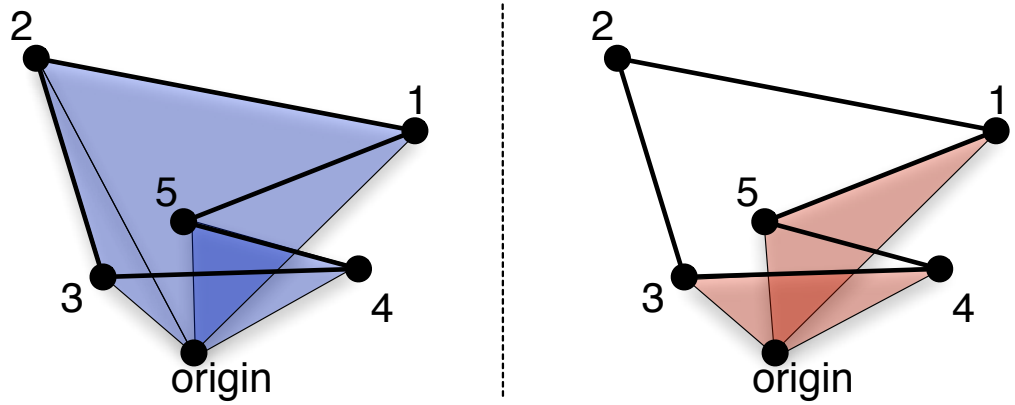

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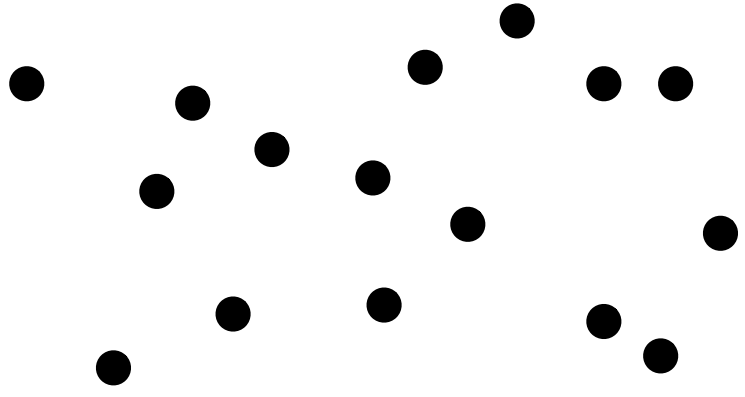
```

Points outside are "cancelled", points inside are counted $+1$ times (after cancelling). The net sum is the area of P.

Convex Hull

Given points $p_1, \ldots, p_n$, what is their *convex hull*?



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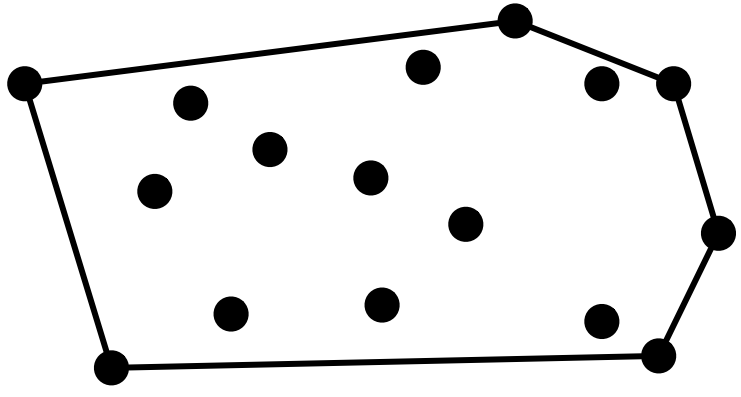

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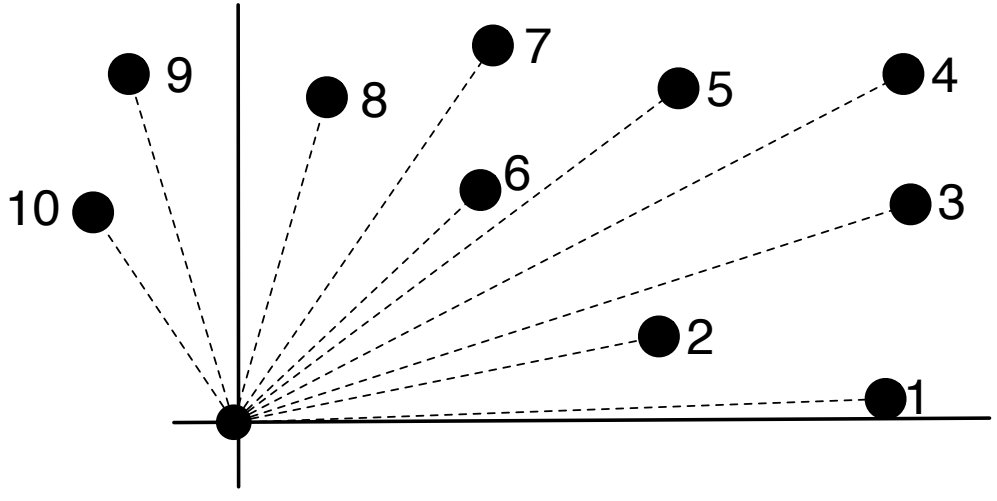
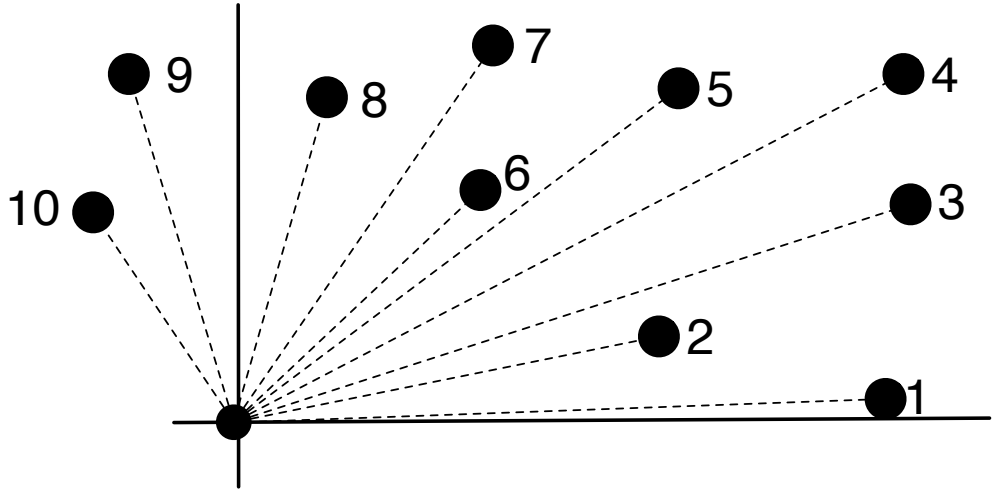
The bottom-most point must be on the convex hull. If there are many, choose the leftmost. Suppose this point is $(0, 0)$ by shifting all points if needed.



Sort all other points by their angle with the positive x-axis.
To check if $p_i < p_j$ according to this order:

Convex Hull

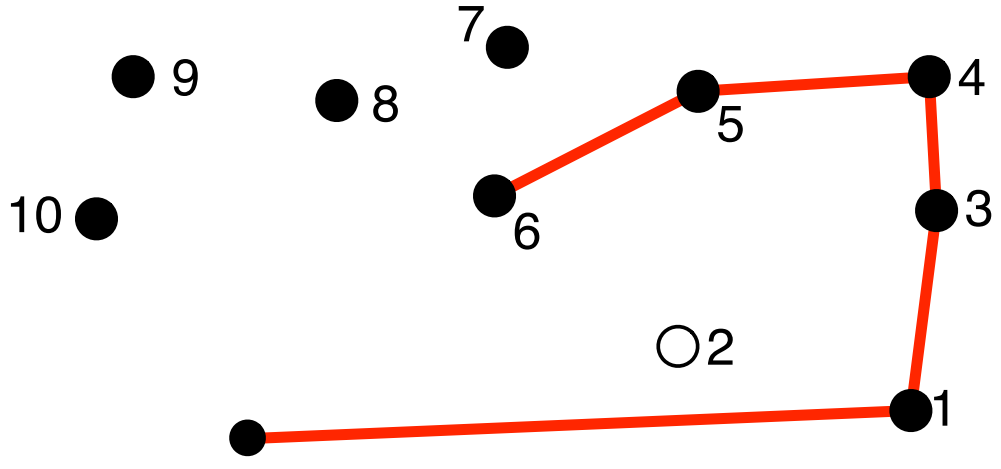
The bottom-most point must be on the convex hull. If there are many, choose the leftmost. Suppose this point is $(0, 0)$ by shifting all points if needed.



Sort all other points by their angle with the positive x-axis.
To check if $p_i < p_j$ according to this order: check $p_i \times p_j > 0$.

The origin and the first point after sorting are on the hull for sure.

Build the hull one point at a time: add the points in the sorted order.



If one creates a clockwise turn with the previous two on the hull, then pop the end of the current hull.

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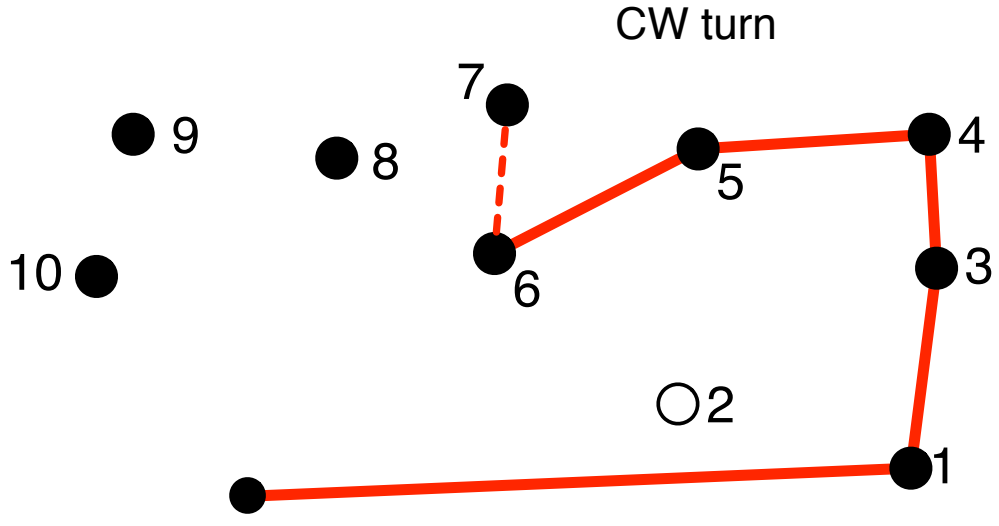

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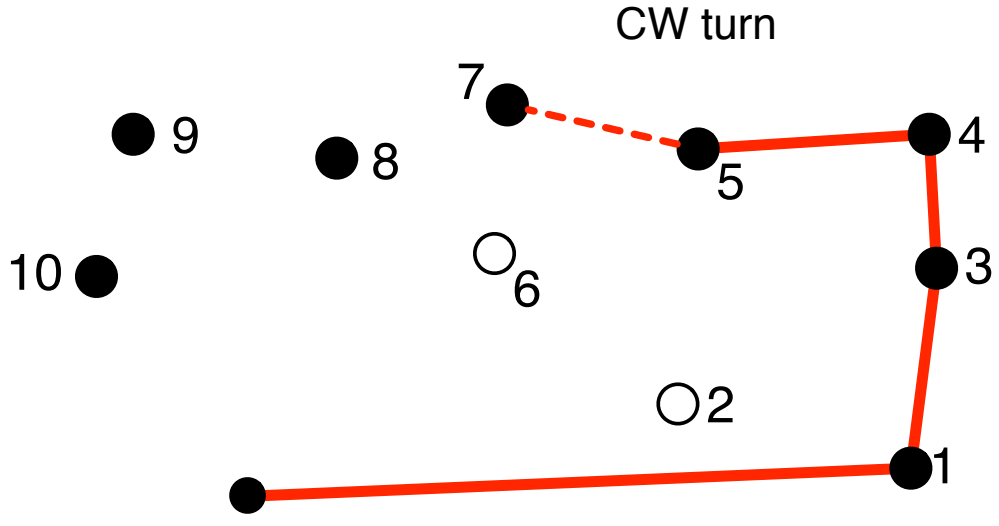

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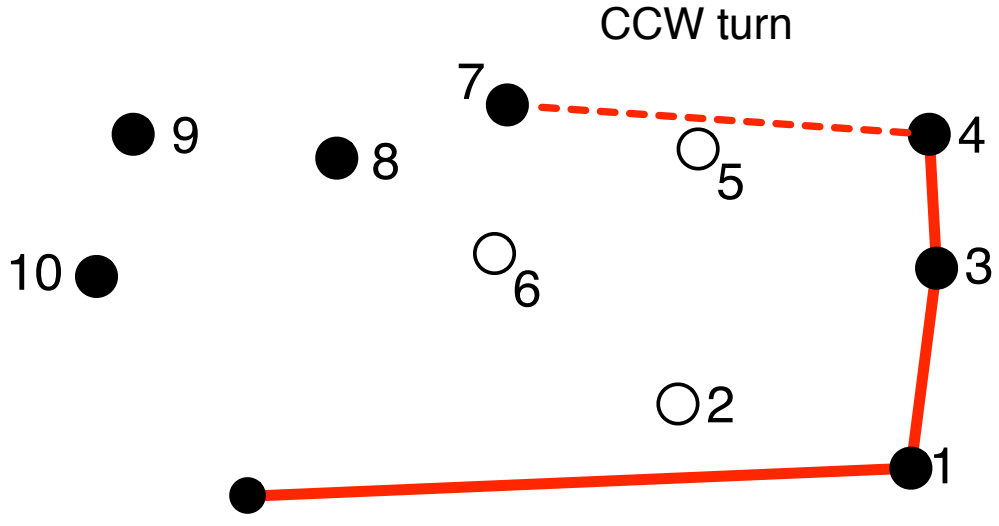

If one creates a clockwise turn with the previous two on the hull, then pop the end of the current hull.

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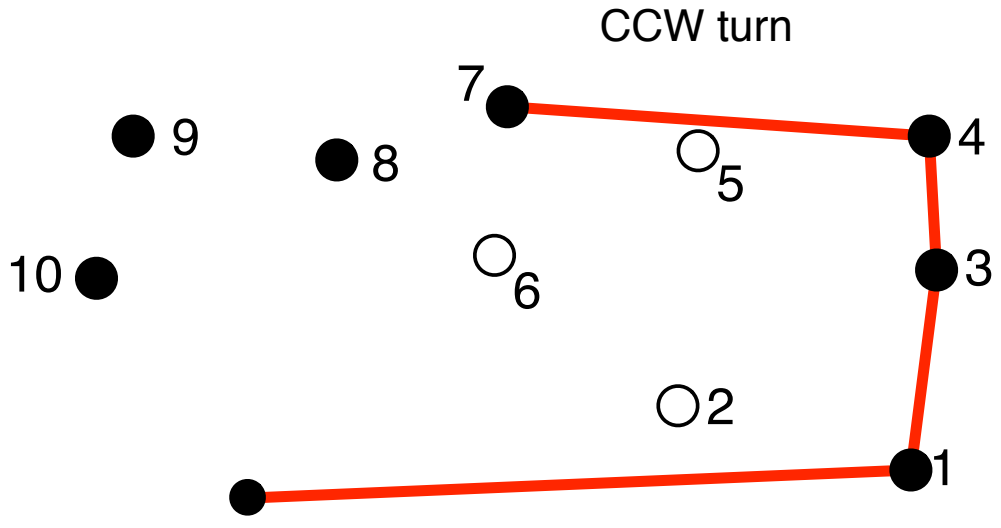
Build up the hull one point at a time: add the points in the sorted order.



If one creates a clockwise turn with the previous two on the hull, then pop the end of the current hull.

```
bool cmp(point a, point b) { return cross(a, b) > 0; }

point p[MAXN], hull[MAXN];
//Assume p[n-1] is the lowest point (breaking ties by
//taking leftmost) and no 3 points are collinear

for (int i = 0; i < n-1; ++i) p[i] -= p[n-1];
sort(p, p+n-1, cmp); //sort by angle from x-axis

hull[0] = point(0,0);
hull[1] = p[0];
int hs = 2;

for (int i = 1; i < n-1; ++i) {
  while (cross(hull[hs-1]-hull[hs-2],p[i]-hull[hs-2]) < 0)
    --hs;
  hull[hs++] = p[i];
}
for (int i = 0; i < hs; ++i) hull[i] += p[n-1];
```

Running time: $O(n \log n)$

Tips

Never use `float`, not enough precision. Use `double`.

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Safer comparisons.

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#define EPS 1e-8
double a, b;
if (fabs(a-b) < EPS) ...   //check if a == b
if (a + EPS < b) ...       //check if a < b
if (a < b + EPS) ...       //check if a <= b
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Can there be 3 collinear points? Can points be equal? How can you deal with this?

Missing Topics

`Voronoi diagrams/Delaunay triangulations, 3D convex hull, closest pair of points, furthest pair of points, triangulating a polygon.`

Next Time

Number Theory

Some Topics To Come

- Combinatorics and Arithmetic
- String Processing
- Matchings and Network Flow
- Probability Theory

Open Kattis - polygonarea

https://open.kattis.com/problems/polygonarea

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- We already talked about how to compute the area of a polygon.
- How can you check if it is in CW or CCW order?
- Solution: check if the area is positive before returning the absolute value: > 0 means CCW, < 0 means CW.

Open Kattis - rafting

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Running time: $O(n^2)$.

Open Kattis - wrapping

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Basic approach:

- The total area of the objects is simple, you know the width and height of each (rectangle area $= w \cdot h$).

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- The total area of the objects is simple, you know the width and height of each (rectangle area $= w \cdot h$).
- You need the actual corners to compute the convex hull. Rotate the four corners of the axis-parallel rectangles. by the given angle: simple using complex points (recall: $\mathit{radians} = \frac{\pi}{180} \cdot \mathit{degrees}$).

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- Find the convex hull.

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- Compute the area of the convex hull using the algorithm discussed earlier.

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Running time: $O(n \log n)$

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- Consider the line L passing through the given point p and point y (a parameter) on the vertical axis.
- Use the quadratic expression $||(1-t)\cdot(0,y)+t\cdot p||^2 = 1$. Expand and rearrange in terms of t.

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Caution: carefully check each step of your calculations!